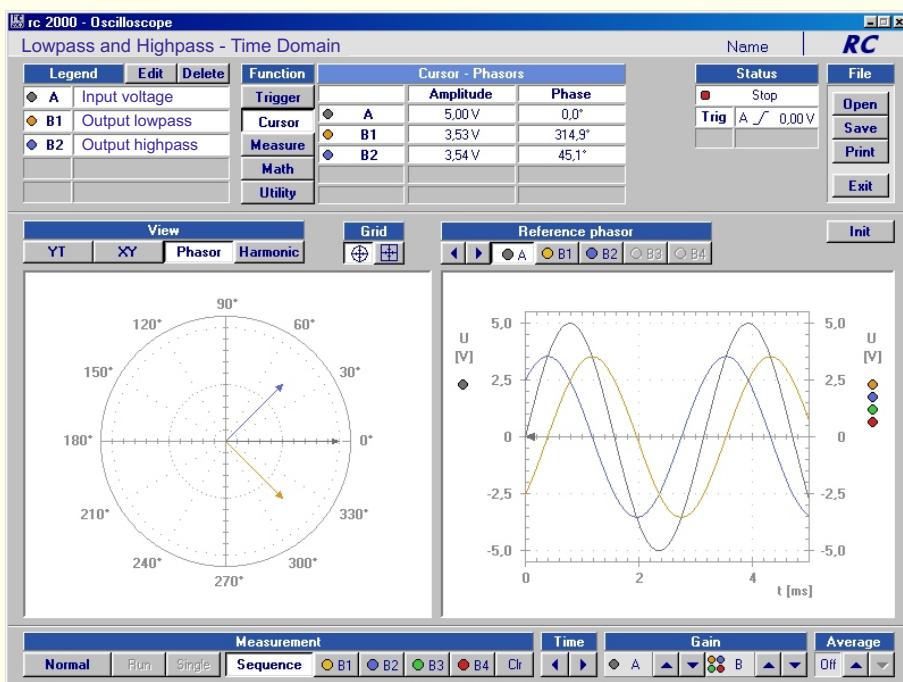


Teaching System rc2000 - μ LAB

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Symbols

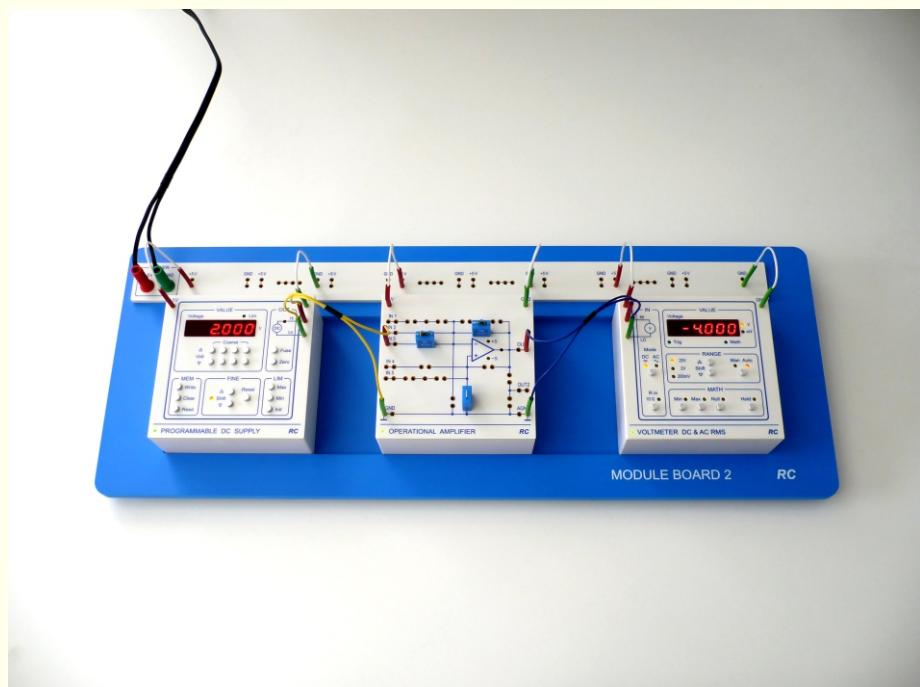
	Component board with built-in precise reference power source 10V.
	Programmable DC supply with the set value.
	Function generator with the set amplitude, frequency and waveform.
	Voltmeter DC & AC RMS on clamps.
	Exact 2-pin resistor of the specified value
	Resistor decade 1 or 2 of the set value.
	Exact 2-pin capacitor of the specified value.
	Capacitor decade of the specified value.
	Connectors of probes in input of measuring unit ADDU - Channel A (+IN A -IN A) or B (+IN B -IN B).
	Connectors of probes in output of measuring unit ADDU.

Comments

Outputs of the modules are designed to have the minimum output resistance ($R_{\text{OUT}} < 0,1\Omega$). They can therefore be regarded as ideal.

Teaching System rc2000 - μ LAB

DC Circuits



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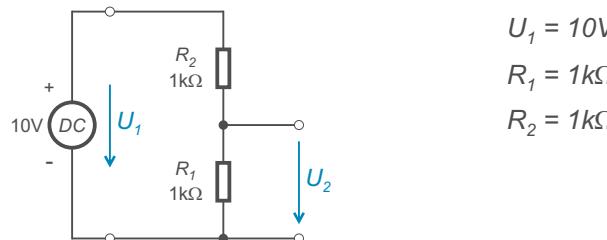
1.1

Unloaded and Loaded Voltage Divider**Exercise**

Verify the validity of the equation for unloaded and loaded voltage divider by comparing the measured and calculated values.

Schema

- 1) Unloaded voltage divider



$$U_1 = 10\text{V}$$

$$R_1 = 1\text{k}\Omega$$

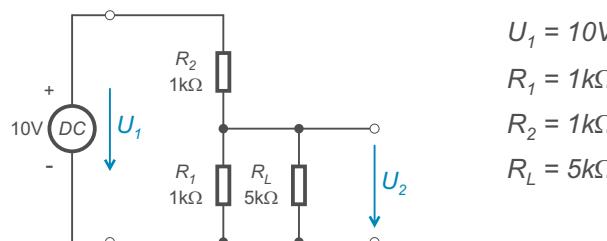
$$R_2 = 1\text{k}\Omega$$

$$U_2 = \frac{R_1}{R_1+R_2} U_1$$

$$U_2 = 5\text{V}$$

Fig. 1 - Unloaded divider

- 2) Loaded voltage divider



$$U_1 = 10\text{V}$$

$$R_1 = 1\text{k}\Omega$$

$$R_2 = 1\text{k}\Omega$$

$$R_L = 5\text{k}\Omega$$

$$U_2 = \frac{R_1 \cdot R_L}{R_2 \cdot R_L + R_1 \cdot R_2 + R_1 \cdot R_L} U_1$$

$$U_2 = 4,545\text{V}$$

Fig. 2 - Loaded divider

1.2

Voltage Source - Internal Resistance

Exercise

Measure the internal resistance R_i of the ideal (Fig. 1 and 2) and a real voltage source (Fig. 3 and 4).

Schema

1) Ideal voltage source

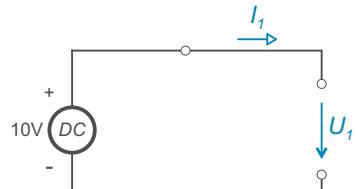


Fig. 1 - Unloaded

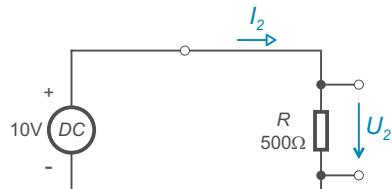


Fig. 2 - Loaded

$$R_i = \frac{U_1 - U_2}{I_2 - I_1}$$

$$I_2 = \frac{U_2}{R}$$

$R_i = 0\Omega$

2) Real voltage source

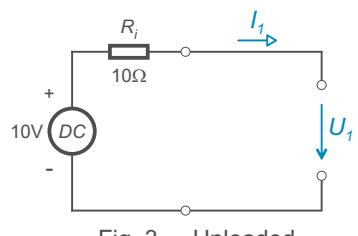


Fig. 3 - Unloaded

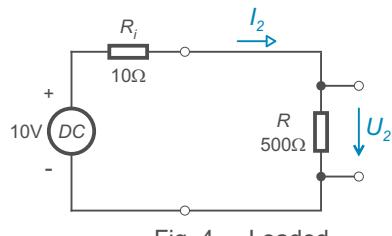


Fig. 4 - Loaded

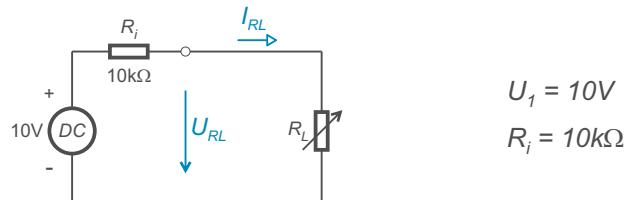
$$R_i = \frac{U_1 - U_2}{I_2 - I_1}$$

$$I_2 = \frac{U_2}{R}$$

$R_i = 10\Omega$

Exercise

Verify that in given circuit the maximum power is being transferred to the load resistor R_L on condition that $R_L = R_i$.

Schema

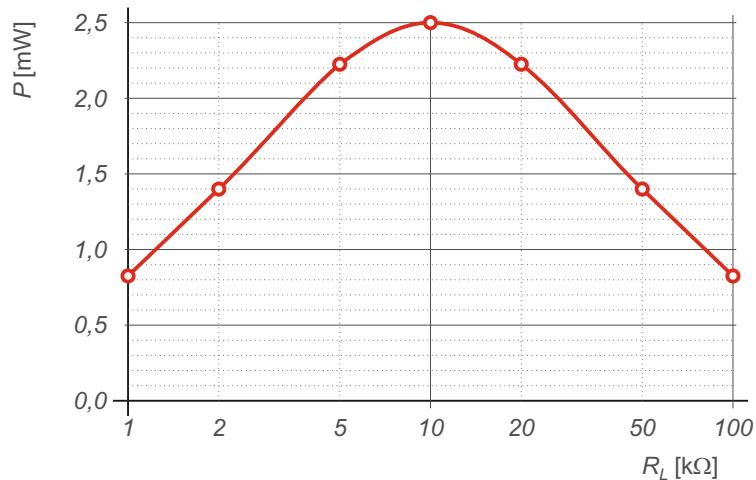
$$U_1 = 10V$$

$$R_i = 10k\Omega$$

$$I_{RL} = \frac{U_{RL}}{R_L}$$

$$P = \frac{U_{RL}^2}{R_L}$$

R_L [kΩ]	0,0	1,0	2,0	5,0	10,0	20,0	50,0	100,0
U_{RL} [V]	0,000	0,909	1,667	3,333	5,000	6,667	8,333	9,091
P [mW]	0,000	0,826	1,389	2,222	2,500	2,222	1,389	0,826



Exercise

Verify the validity of Kirchhoff's first law for the following two circuits.

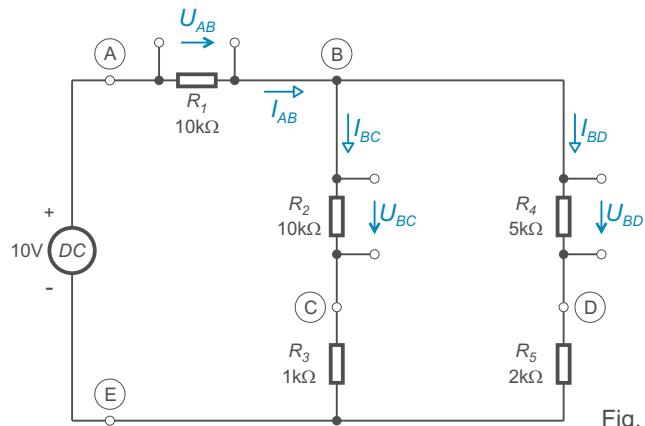
Schema

Fig. 1 - Circuit No. 1

$$I_{AB} = \frac{U_{AB}}{R_1}$$

$$I_{BC} = \frac{U_{BC}}{R_2}$$

$$I_{BD} = \frac{U_{BD}}{R_4}$$

$$I_{AB} = I_{BC} + I_{BD}$$

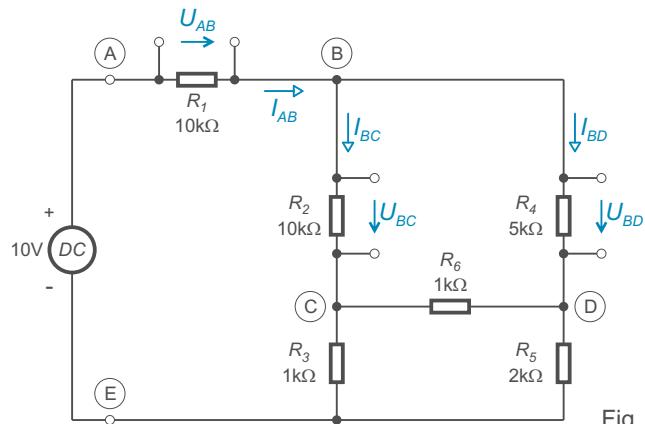


Fig. 2 - Circuit No. 2

$$I_{AB} = \frac{U_{AB}}{R_1}$$

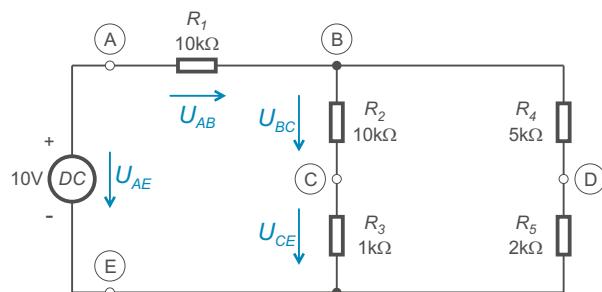
$$I_{BC} = \frac{U_{BC}}{R_2}$$

$$I_{BD} = \frac{U_{BD}}{R_4}$$

$$I_{AB} = I_{BC} + I_{BD}$$

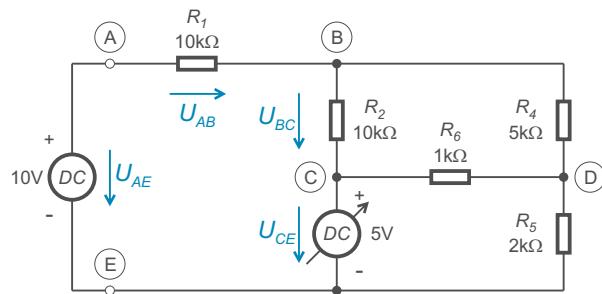
Exercise

Verify the validity of Kirchhoff's second law for the following two circuits.

Schema

$$U_{AE} = U_{AB} + U_{BC} + U_{CE}$$

Fig. 1 - Circuit No. 1

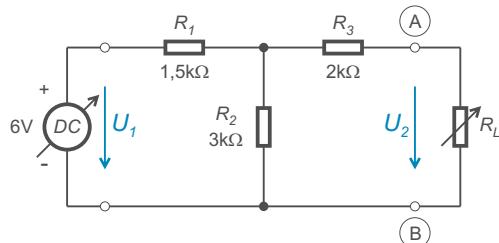


$$U_{AE} = U_{AB} + U_{BC} + U_{CE}$$

Fig. 2 - Circuit No. 2

Exercise

Simplify circuit 1 using the Thevenine theorem.

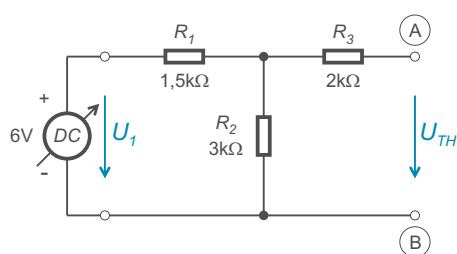
Schema

$$U_1 = 6V \quad R_1 = 1,5k\Omega$$

$$R_2 = 3k\Omega$$

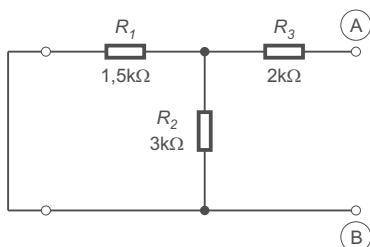
$$R_3 = 2k\Omega$$

Fig. 1 - Given circuit



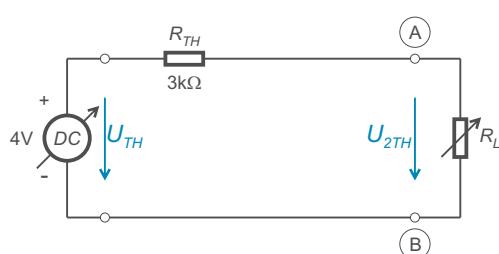
$$U_{TH} = \frac{R_2}{R_1+R_2} U_1$$

$$U_{TH} = 4V$$

Fig. 2 - Replacement voltage U_{TH} 

$$R_{TH} = R_3 + \frac{R_1 \cdot R_2}{R_1+R_2}$$

$$R_{TH} = 3k\Omega$$

Fig. 3 - Replacement resistor R_{TH} 

$$U_{TH} = 4V$$

$$R_{TH} = 3k\Omega$$

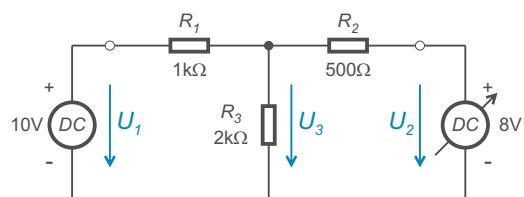
Fig. 4 - Simplified circuit

Exercise

Prove that the superposition principle applies only to linear networks.

Schema

1) Linear circuit



$$U_3 = U_{31} + U_{32}$$

Fig. 1 - Examined linear circuit

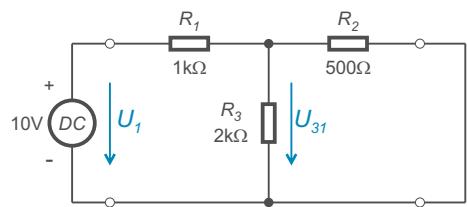


Fig. 2 - Contribution of first source

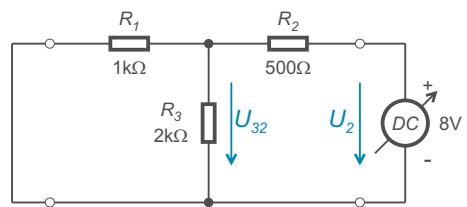


Fig. 3 - Contribution of second source

2) Nonlinear circuit

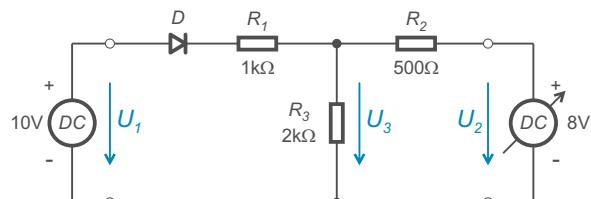


Fig. 4 - Examined nonlinear circuit

$$U_3 \neq U_{31} + U_{32}$$

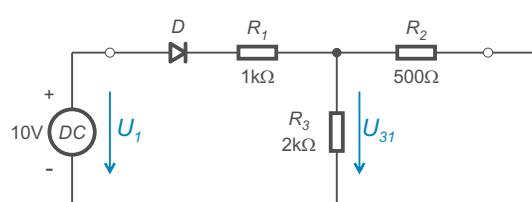


Fig. 5 - Circuit without second source

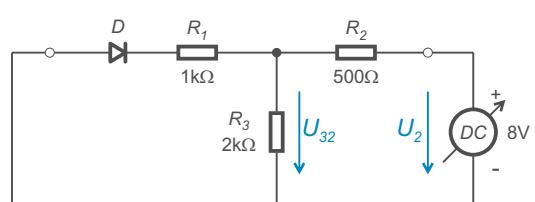


Fig. 6 - Circuit without first source

Exercise

With the delta - star transformation determine the value U_2 in given circuit.

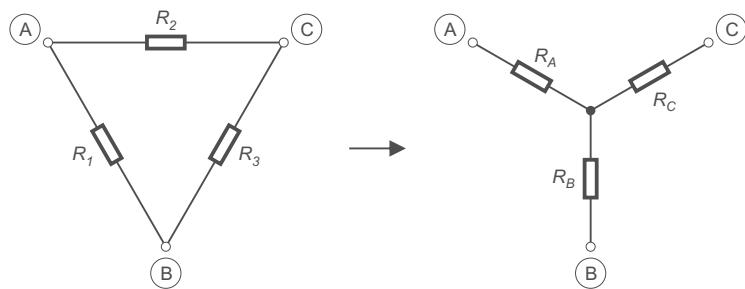
Schema

Fig. 1 - Transformation delta - star

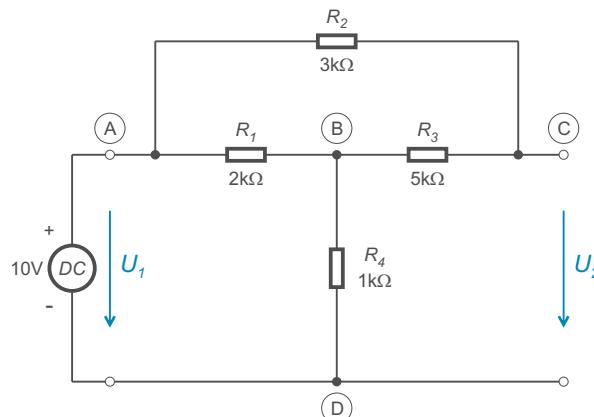


Fig. 2 - Given circuit - delta

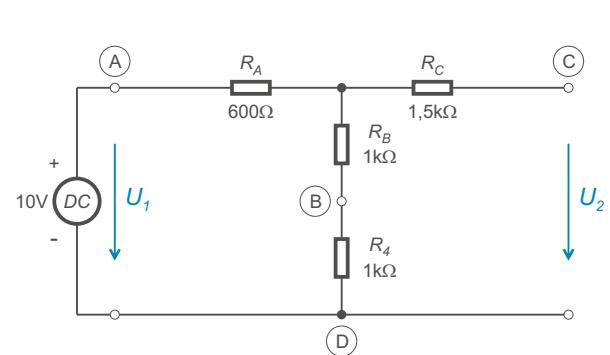
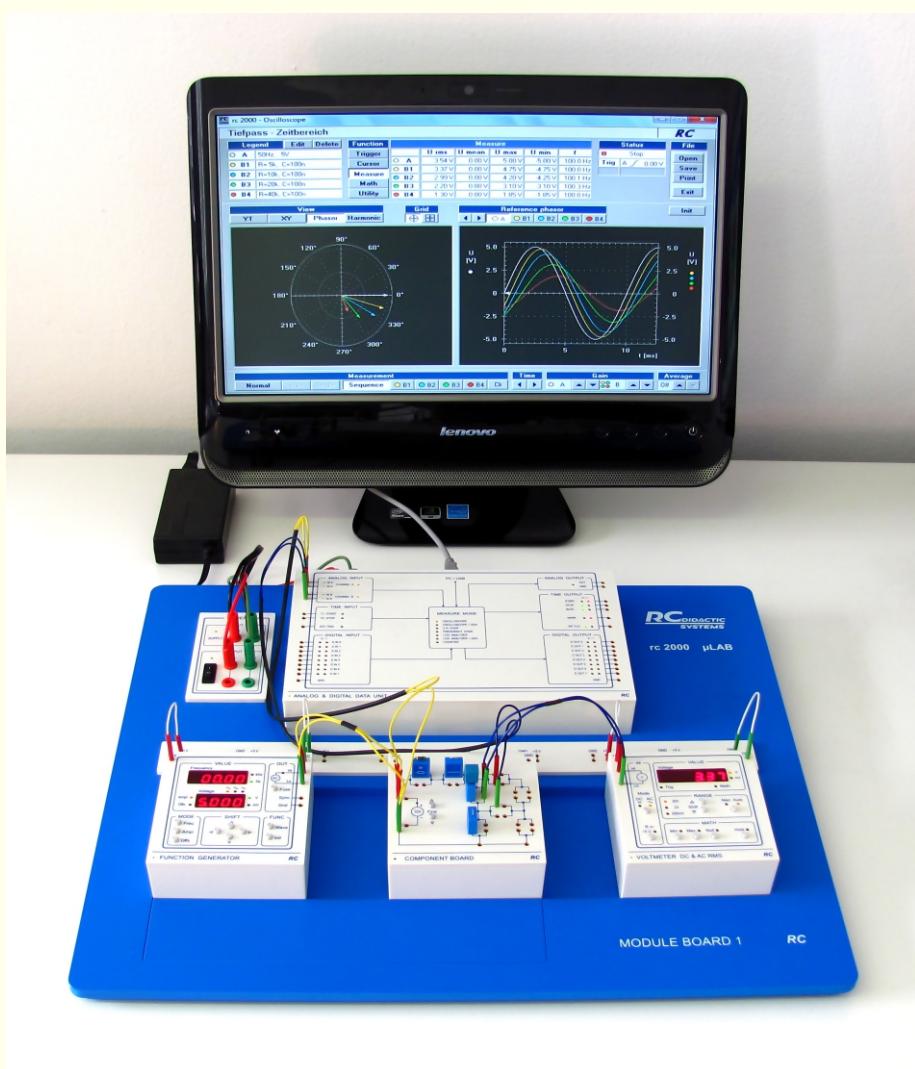


Fig. 3 - Circuit after transformation - star

Teaching System rc2000 - μ LAB

AC Circuits



RC společnost s r. o.
přístroje pro vědu a vzdělání
Cholupická 38
CZ - 142 00 Praha 4

Tel./Fax: 00420-244 464 176
Mobile: 00420-603 158 544
E-mail: info@rctidactic.cz
Web: www.rctidactic.cz

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2.1

RC Integrating Circuit and CR Differentiating Circuit

Exercise

Measure the response of the integrating and differentiating circuit to rectangular voltage. Make the measurement values for capacitor $C = 4 \text{ nF}$, 40 nF , 240 nF .

Schema

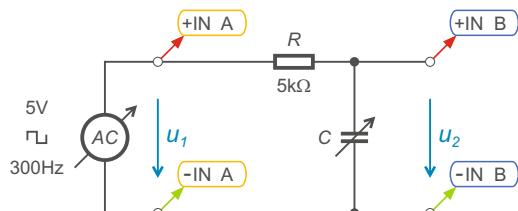


Fig. 1

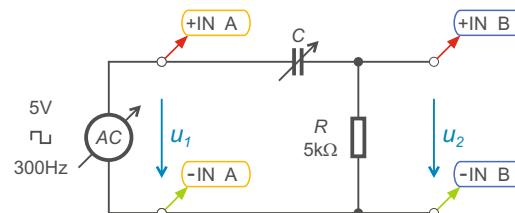
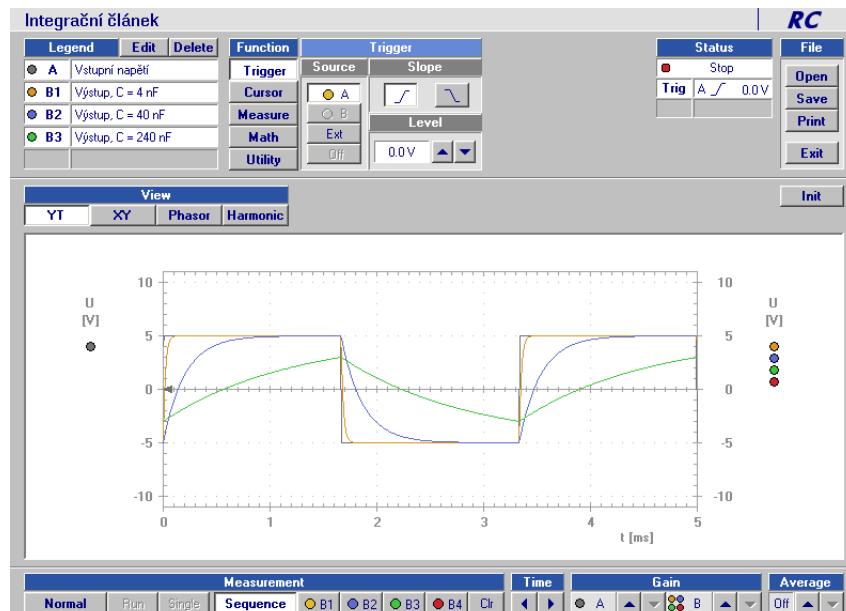


Fig. 2

Measurement



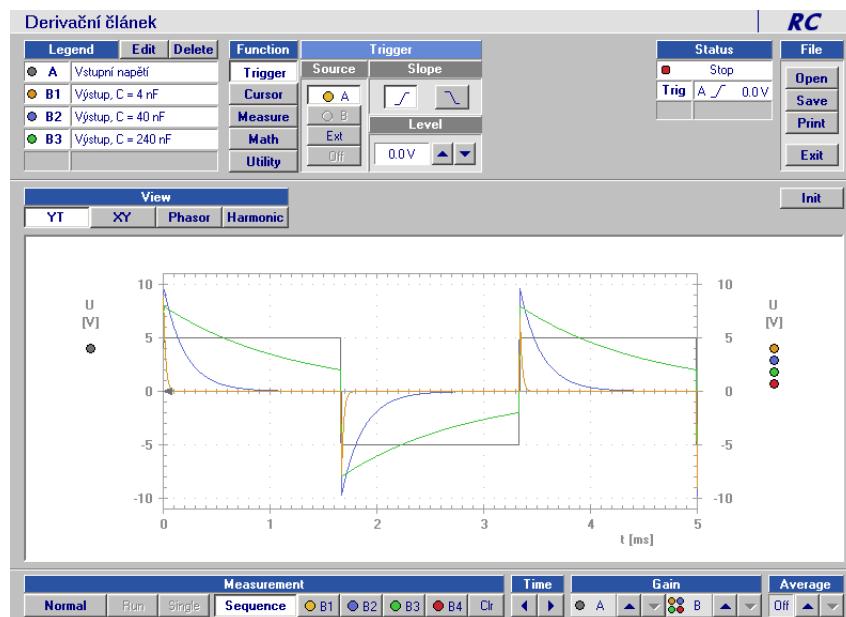
Integrating member

schema

Fig. 1

measuring mode

oscilloscope



Differentiating member

schema

Fig. 2

measuring mode

oscilloscope

2.2

Low Pass and High Pass - Time Domain

Exercise

Display time and phasor diagrams for the lower and upper pass filter (with the same cut-off frequency f_G).

Schema

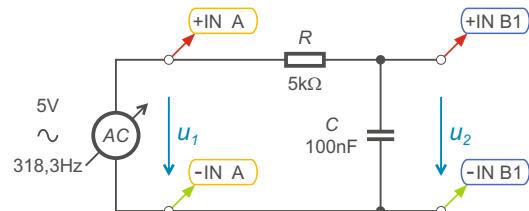


Fig. 1

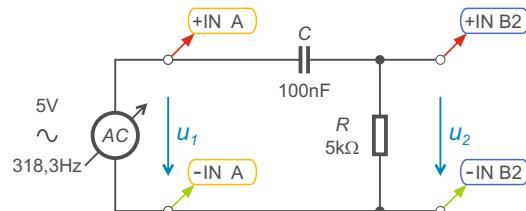
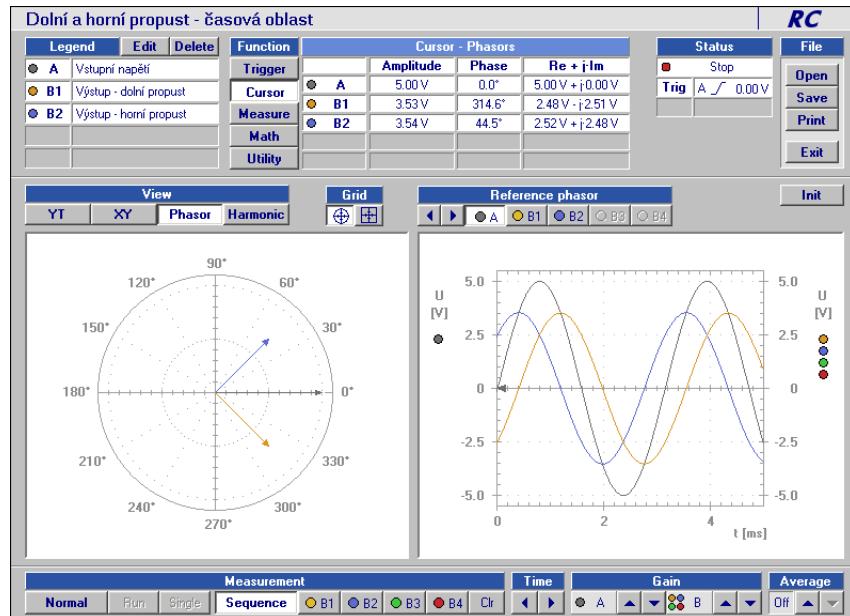


Fig. 2

Measurement



Phase diagrams

schema

Fig. 1, Fig. 2

measuring mode

oscilloscope

measured waveforms

$u_1(t)$

(V)

$u_2(t)$, Fig. 1

(V)

$u_2(t)$, Fig. 2

(V)

formula

$$f_G = \frac{1}{2\pi RC}$$

(Hz)

2.3

Low Pass and High Pass - Frequency Domain

Exercise

Display amplitude and phase frequency characteristics for low pass and high pass (with the same cut off frequency f_G).

Schema

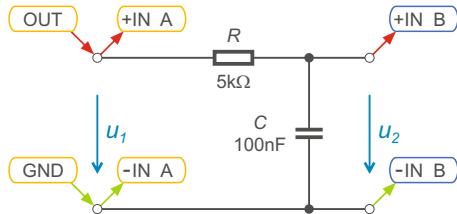


Fig. 1

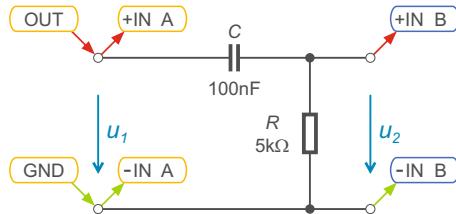
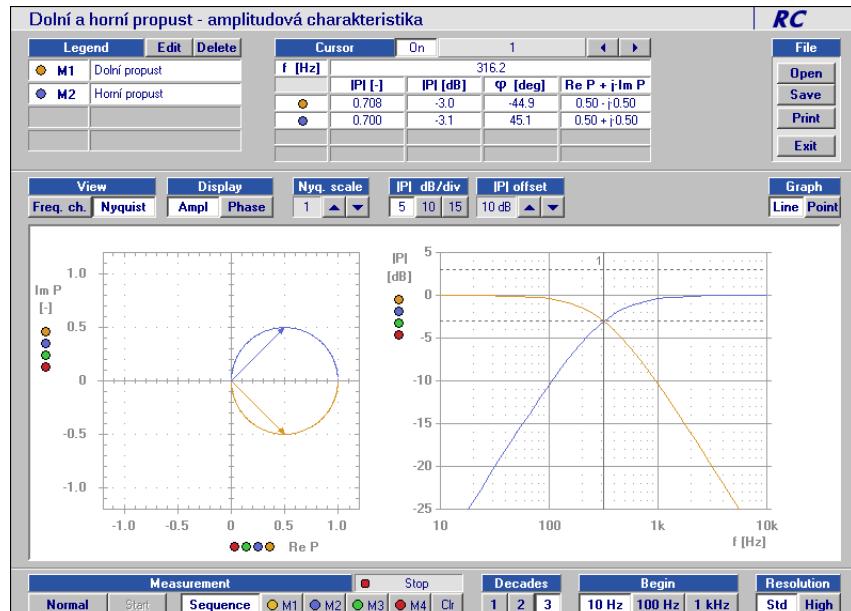


Fig. 2

Measurement



Amplitude characteristics

schema

Fig. 1, Fig. 2

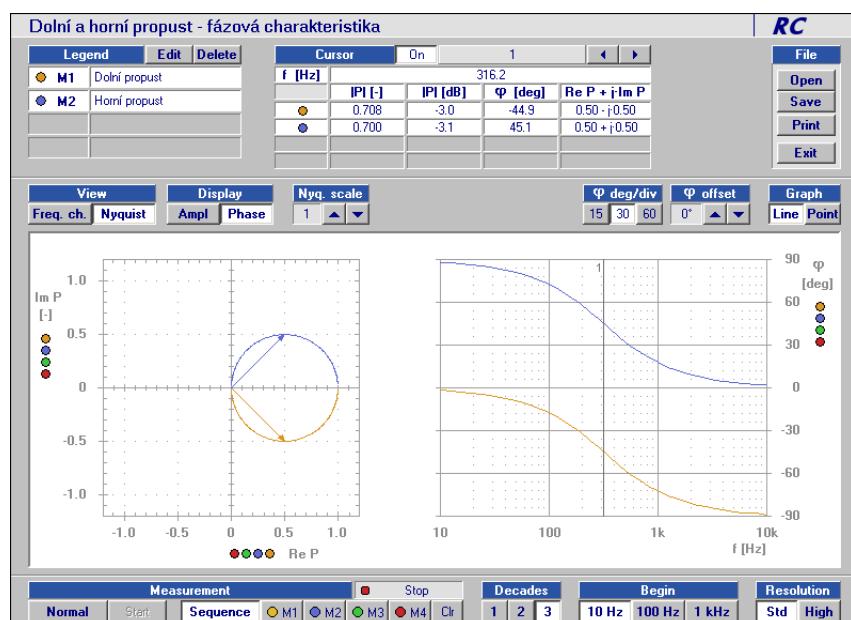
measuring mode

frequency characteristics

measured characteristics

● IPI(f), Fig. 1 (dB)

● IPI(f), Fig. 2 (dB)



Phase characteristics

schema

Fig. 1, Fig. 2

measuring mode

frequency characteristics

measured characteristics

● φ(f), Fig. 1 (°)

● φ(f), Fig. 2 (°)

2.4

RLC Series Resonance Circuit

Exercise

Show time and phasor diagrams for series resonance circuit in connection with ideal capacitor and ideal coil (Fig. 1) and for circuit with ideal capacitor and with real coil (Fig. 2).

Schema

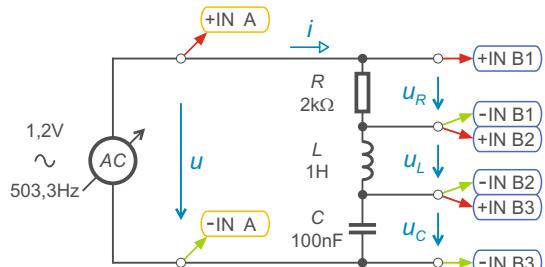


Fig. 1

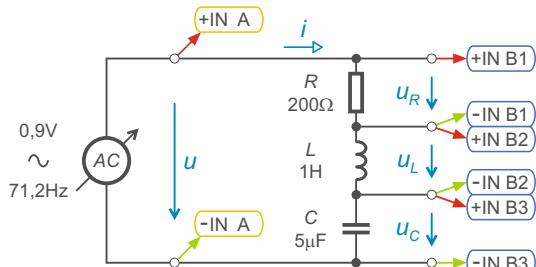
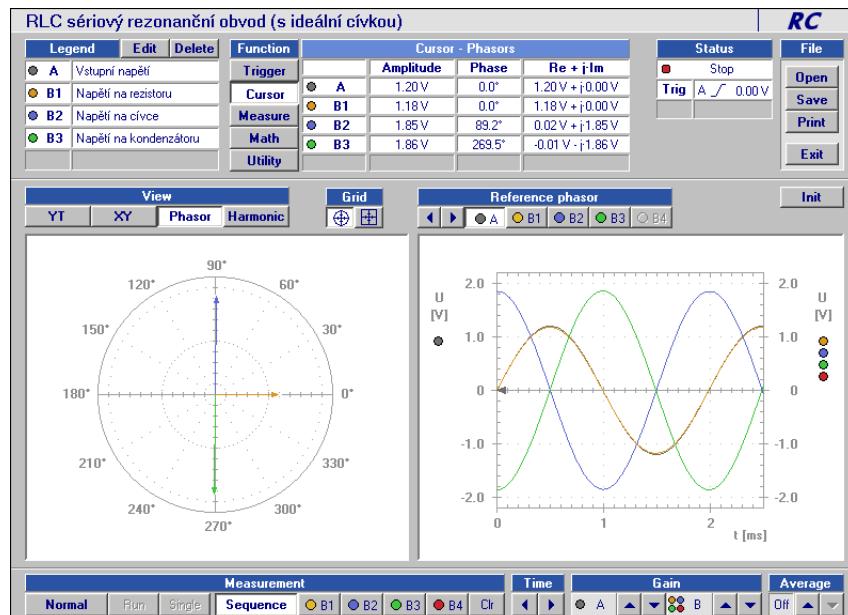


Fig. 2

Measurement



Circuit with ideal coil

schema

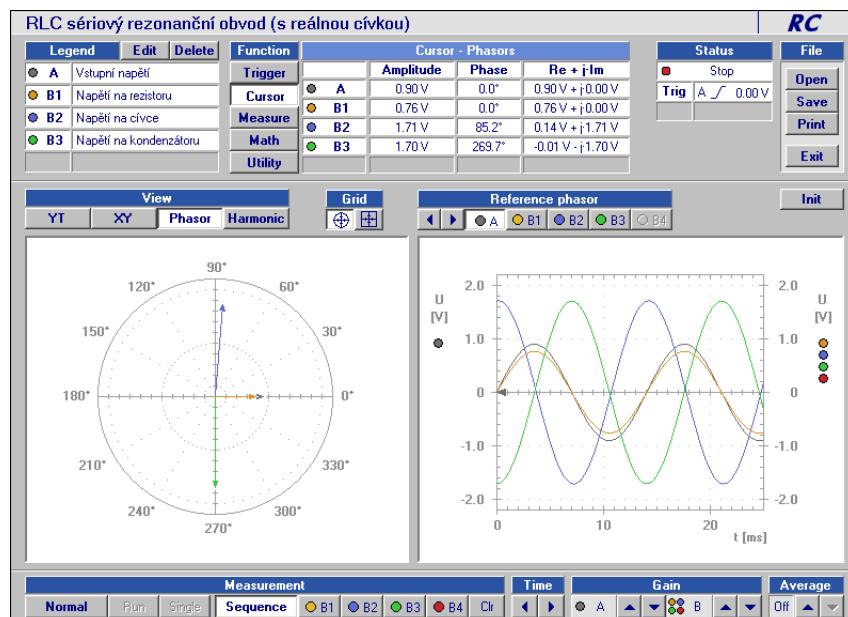
Fig. 1

measuring mode

oscilloscope

measured time curves

- $u(t)$ (V)
- $u_R(t)$ (V)
- $u_L(t)$ (V)
- $u_C(t)$ (V)



Circuit with real coil

schema

Fig. 2

measuring mode

oscilloscope

measured time curves

- $u(t)$ (V)
- $u_R(t)$ (V)
- $u_L(t)$ (V)
- $u_C(t)$ (V)

Exercise

Display amplitude and phase frequency characteristics for RLC bandpass (for different values of damping resistor R , for example $R = 100 \Omega, 200 \Omega, 500 \Omega$).

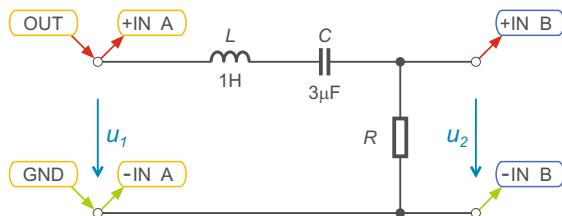
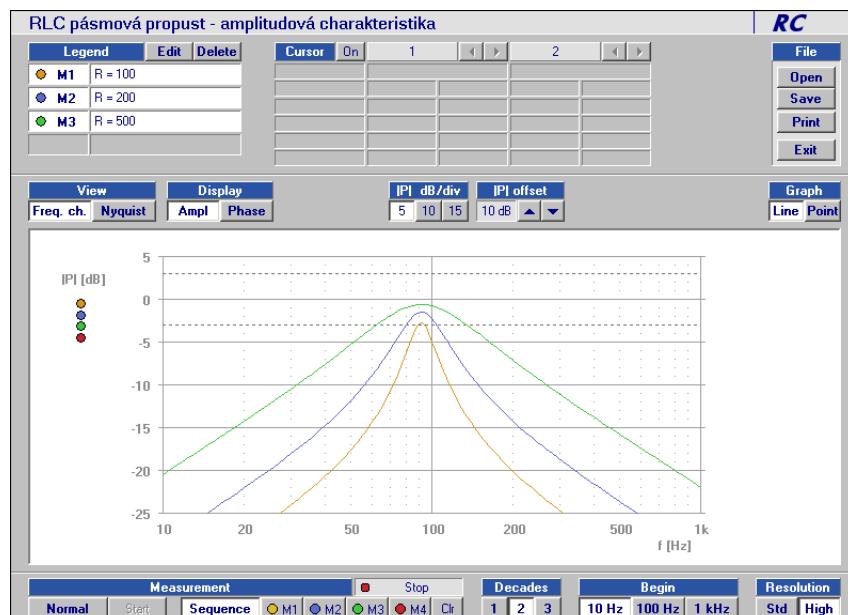
Schema

Fig. 1

Measurement

Amplitude characteristics

schema

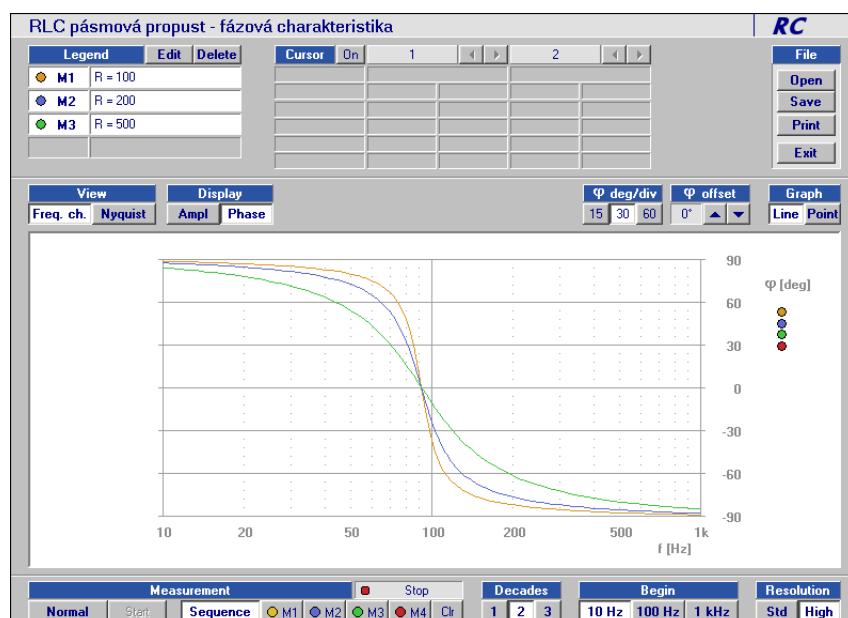
Fig. 1

measuring mode

frequency characteristics

measured characteristics

- IPI(f), $R = 100 \Omega$ (dB)
- IPI(f), $R = 200 \Omega$ (dB)
- IPI(f), $R = 500 \Omega$ (dB)



Phase characteristics

schema

Fig. 1

measuring mode

frequency characteristics

measured characteristics

- $\varphi(f), R = 100 \Omega$ (°)
- $\varphi(f), R = 200 \Omega$ (°)
- $\varphi(f), R = 500 \Omega$ (°)

Exercise

Display amplitude and phase frequency characteristics for RLC band stop (for different values of dampening resistor R , for example $R = 100 \Omega$, 200Ω , 500Ω).

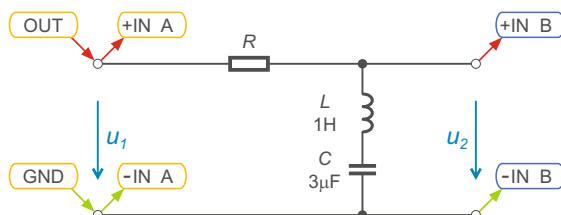
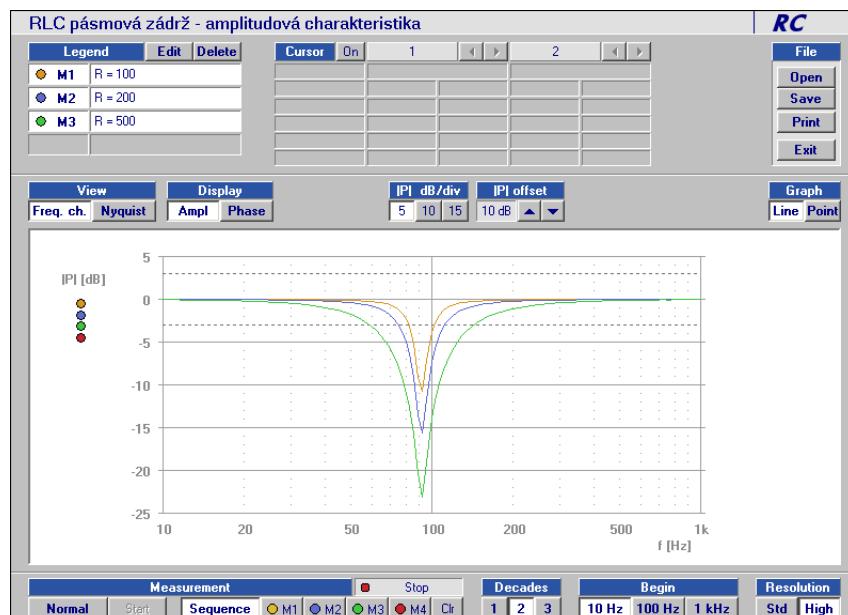
Schema

Fig. 1

Measurement

Amplitude characteristics

schema

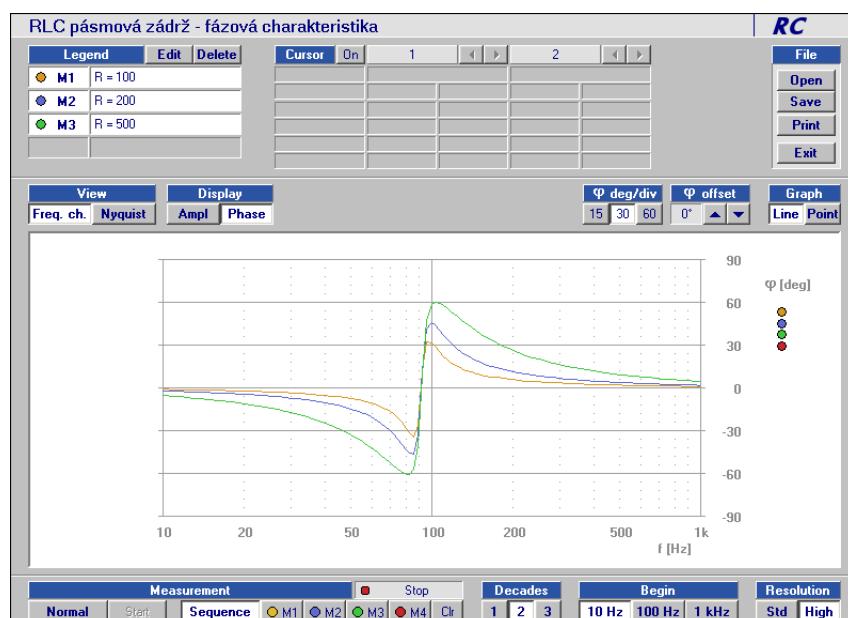
Fig. 1

measuring mode

frequency characteristics

measured characteristics

- IPI(f), $R = 100 \Omega$ (dB)
- IPI(f), $R = 200 \Omega$ (dB)
- IPI(f), $R = 500 \Omega$ (dB)



Phase characteristics

schema

Fig. 1

measuring mode

frequency characteristics

measured characteristics

- $\varphi(f)$, $R = 100 \Omega$ (°)
- $\varphi(f)$, $R = 200 \Omega$ (°)
- $\varphi(f)$, $R = 500 \Omega$ (°)

Exercise

Display waveforms and phasor diagrams for voltage and current in the circuit with a resistor.

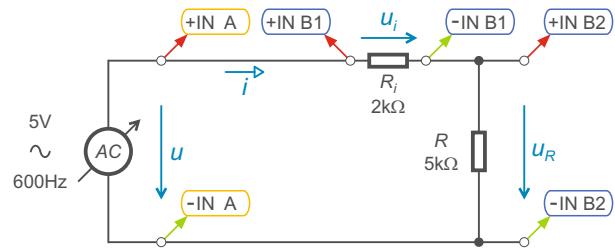
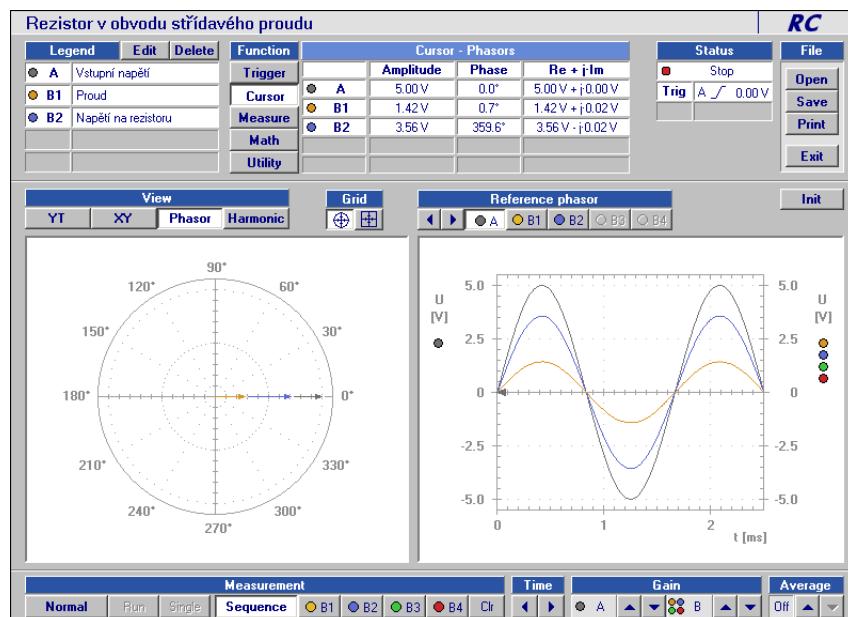
Schema

Fig. 1

Measurement

Waveforms on resistor

schema

Fig. 1

measuring mode

oscilloscope

measured waveforms

- $u(t)$ (V)
- $i(t) = \frac{1}{R_i} u_i(t)$ (mA, kΩ, V)
- $u_R(t)$ (V)

Exercise

Display waveforms and phasor diagrams for voltage and current in the circuit with a coil (ideal and real).

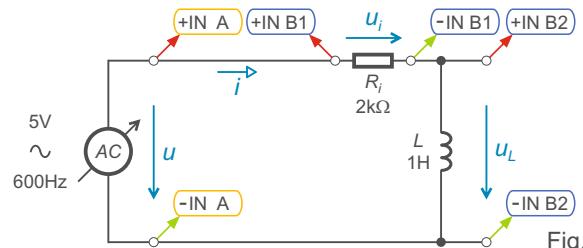
Schema

Fig. 1

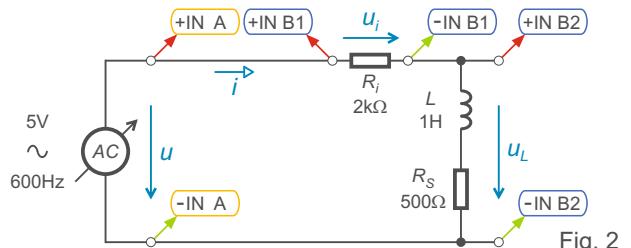
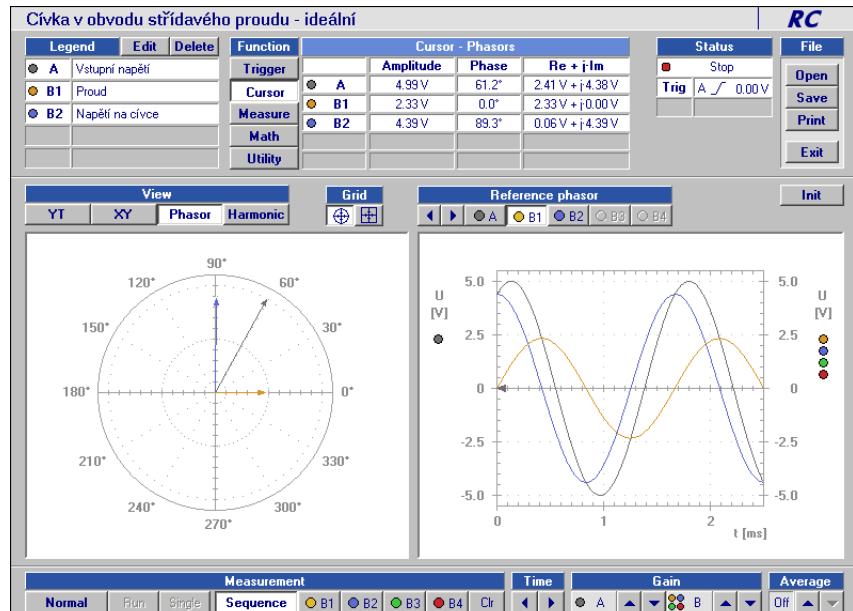


Fig. 2

Measurement

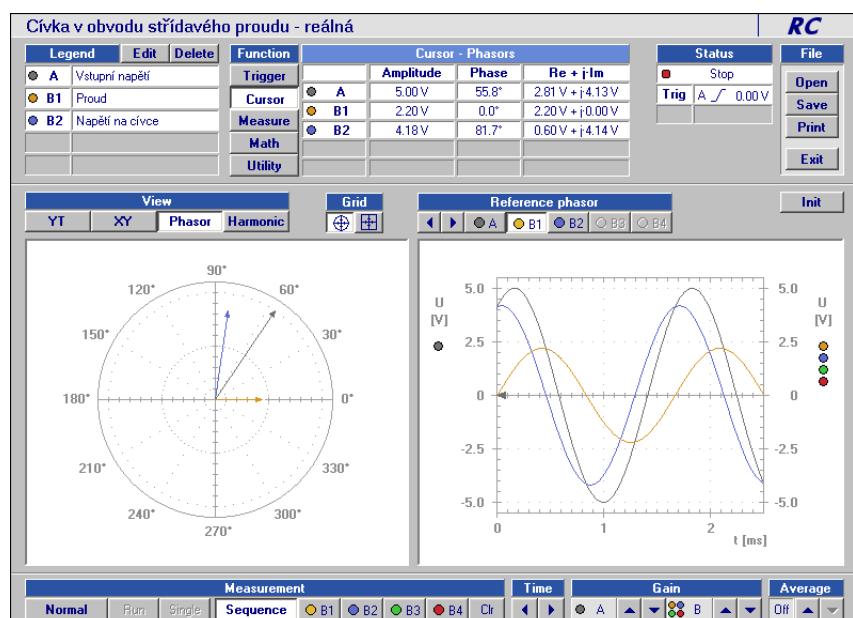
Ideal coil

schema

Fig. 1

measuring mode

oscilloscope



Real coil

schema

Fig. 2

measuring mode

oscilloscope

Exercise

Display waveforms and phasor diagrams for voltage and current in the circuit with a capacitor (ideal and real).

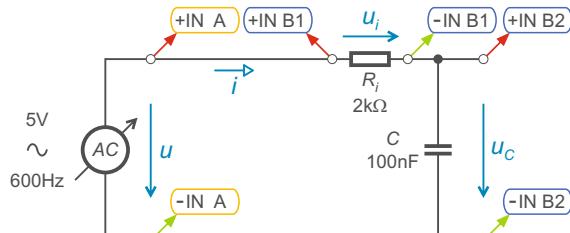
Schema

Fig. 1

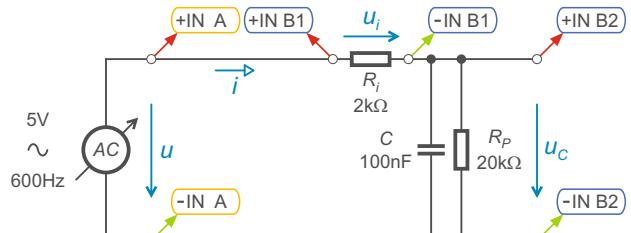
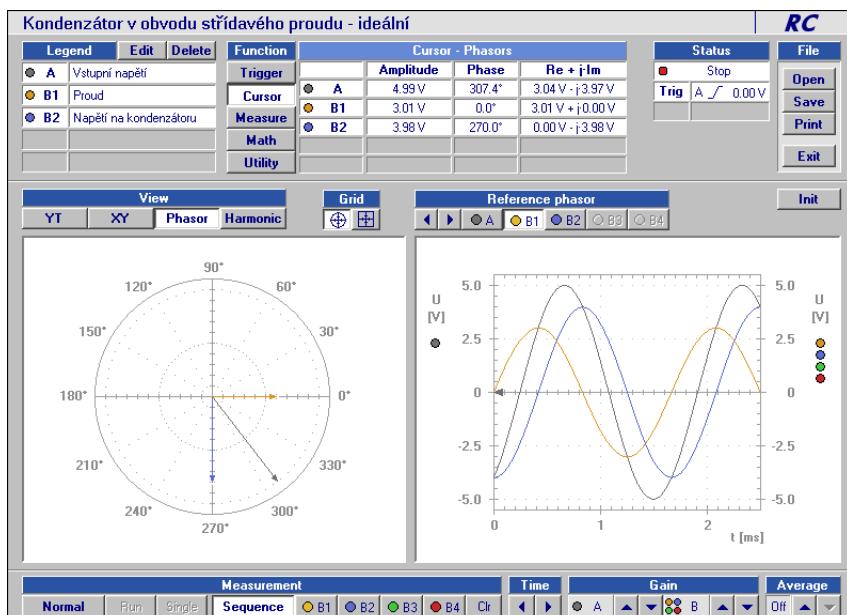


Fig. 2

Measurement

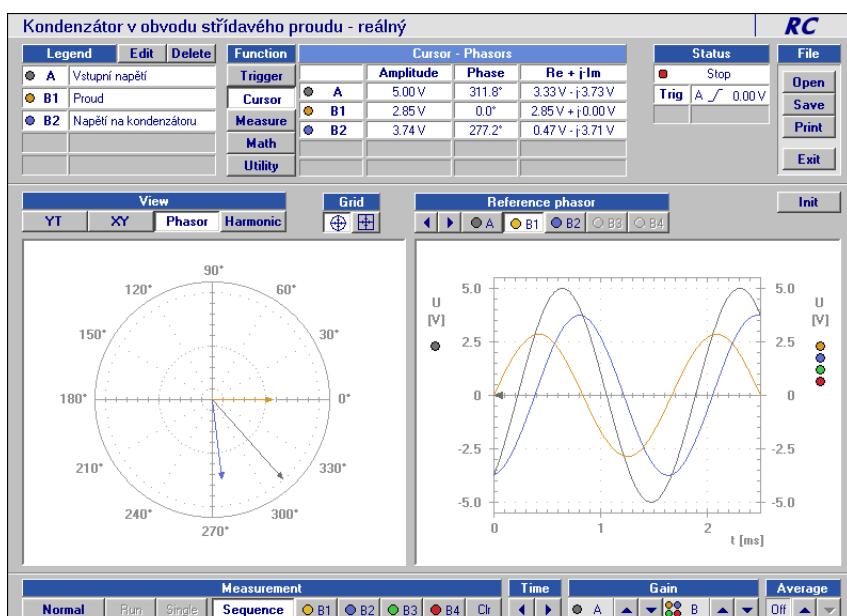
Ideal capacitor

schema

Fig. 1

measuring mode

oscilloscope



Real capacitor

schema

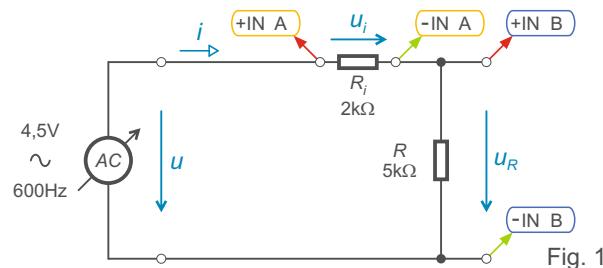
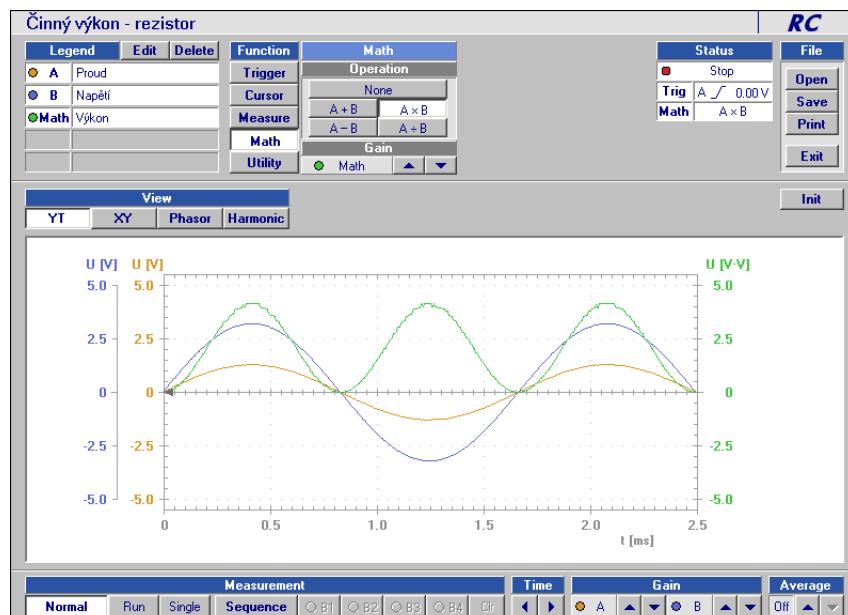
Fig. 2

measuring mode

oscilloscope

Exercise

Display time course of power on resistor.

SchemaMeasurement

Power on resistor

schema

Fig. 1

measuring mode

oscilloscope

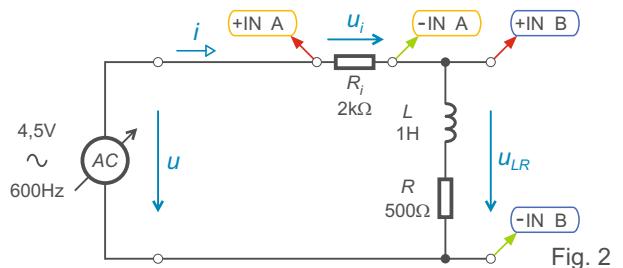
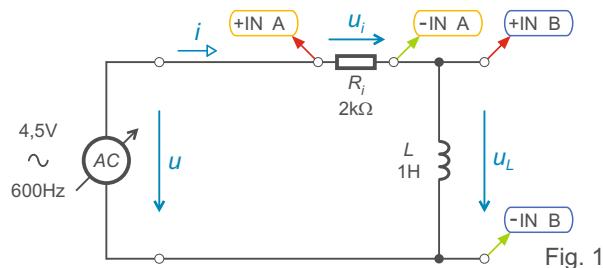
2.11

Reactive Power - Coil

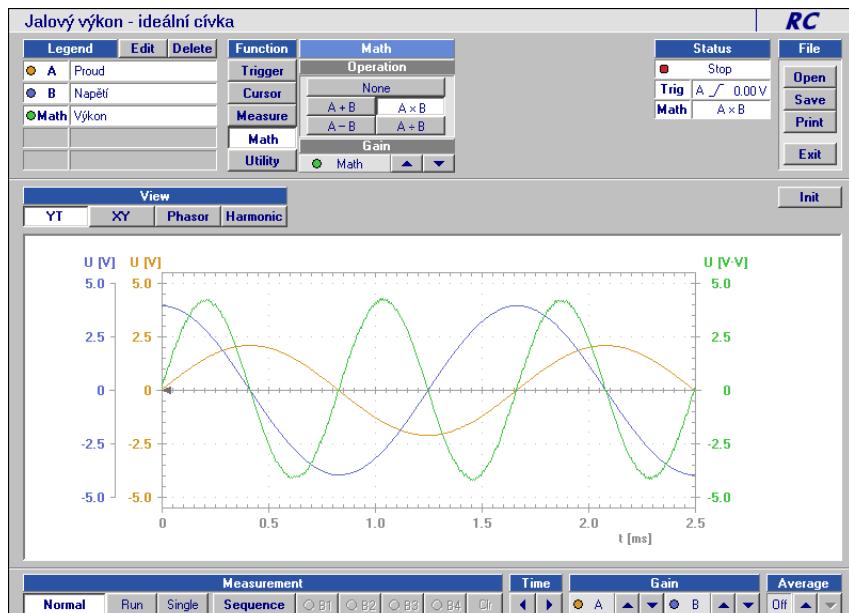
Exercise

Show time course of power on coil. Compare waveforms on the ideal and the real coil.

Schema



Measurement



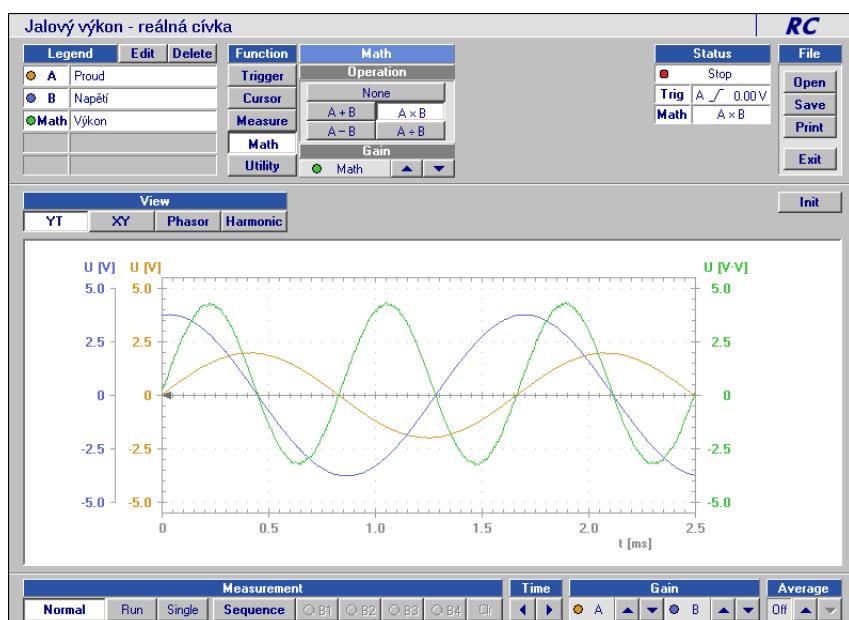
Ideal coil

schema

Fig. 1

measuring mode

oscilloscope



Real coil

schema

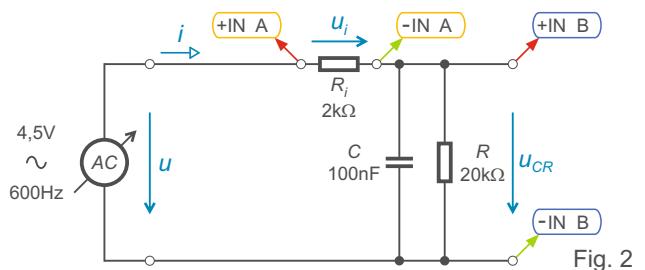
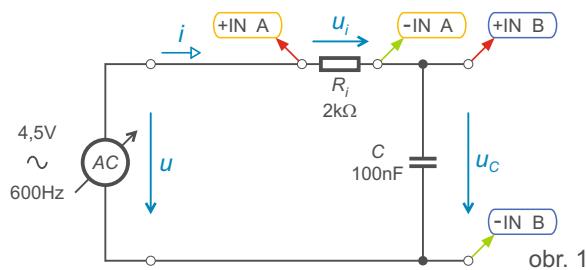
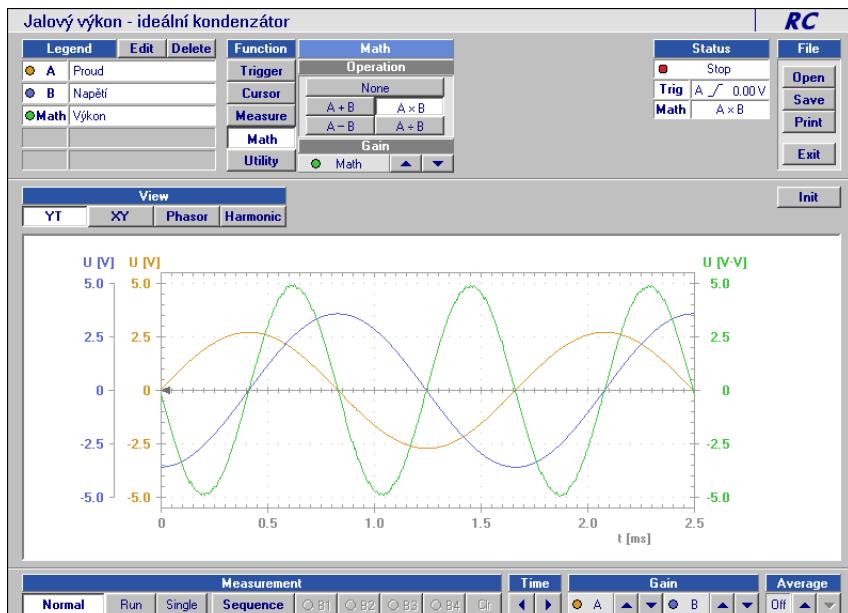
Fig. 2

measuring mode

oscilloscope

Exercise

Display time course of power on capacitor. Compare waveforms on ideal and real capacitor.

Schema**Measurement**

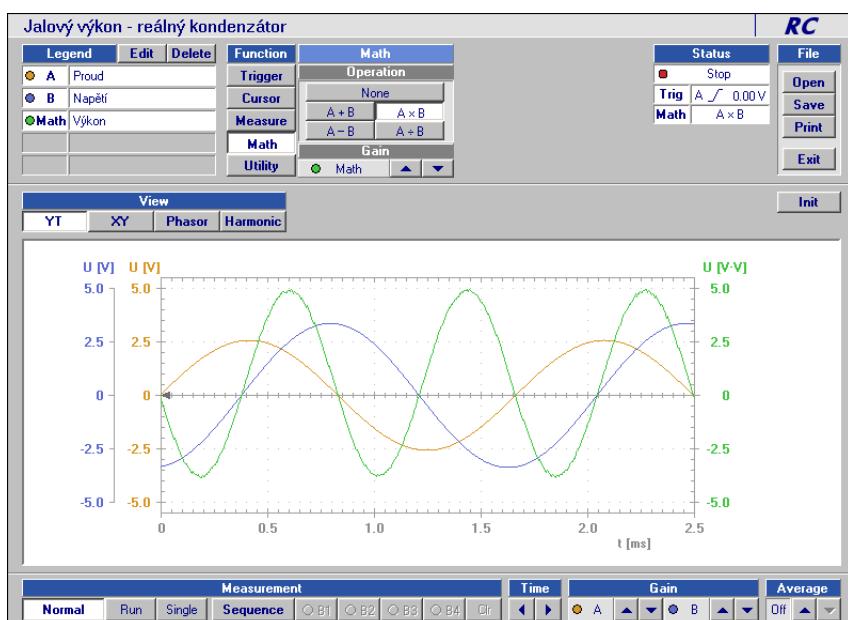
Ideal capacitor

schema

Fig. 1

measuring mode

oscilloscope



Real capacitor

schema

Fig. 2

measuring mode

oscilloscope

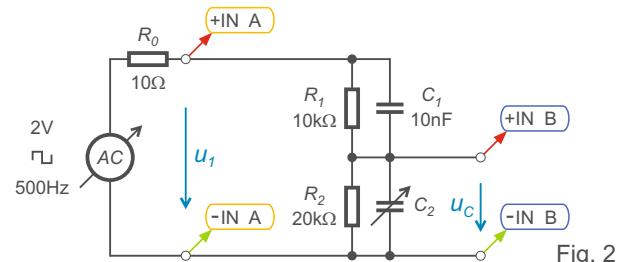
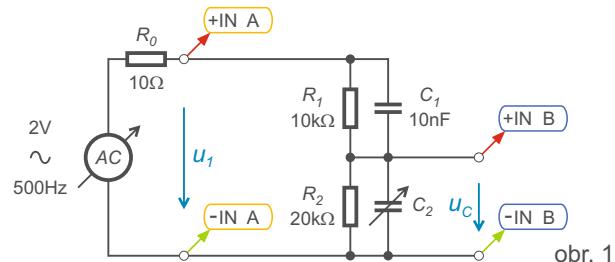
2.13

Impedance Divider - Time Domain

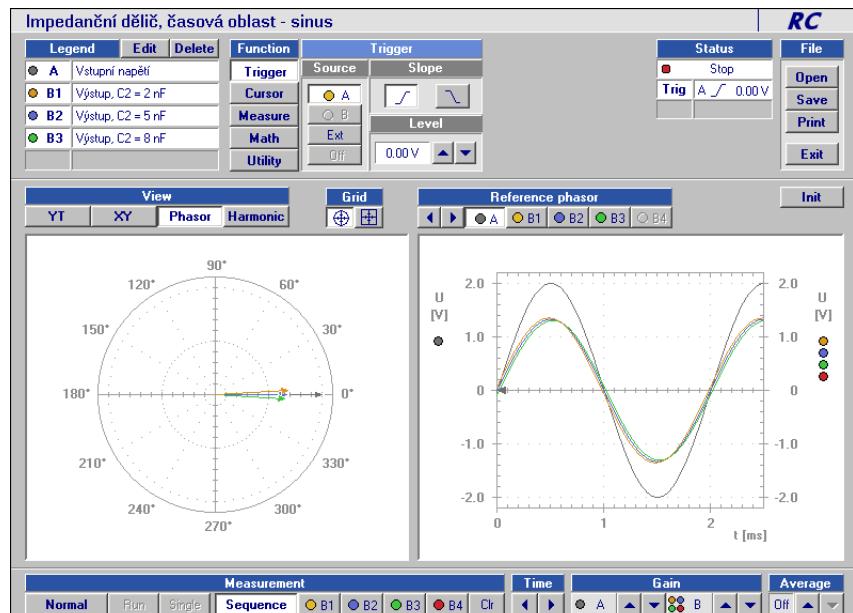
Exercise

Measure voltage transfer of the impedance divider (for $C_2 = 2 \text{ nF}, 5 \text{ nF}, 8 \text{ nF}$). To compensate the divider, following formula must be valid: $R_1 C_1 = R_2 C_2$.

Schema



Measurement



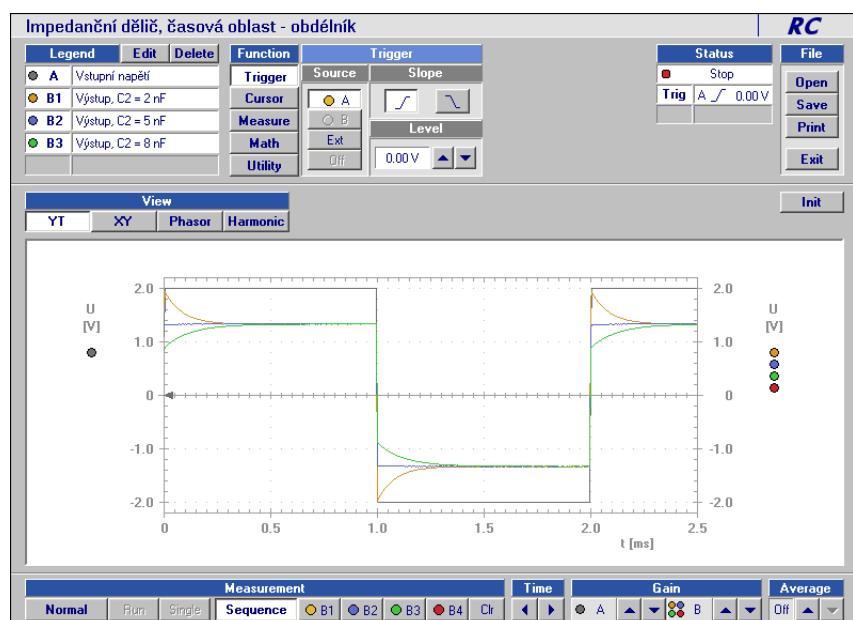
Harmonic course

schema

Fig. 1

measuring mode

oscilloscope



Rectangular course

schema

Fig. 2

measuring mode

oscilloscope

2.14

Impedance divider - Frequency Domain

Exercise

Measure transfer frequency characteristics of the divider (for $C_2 = 2 \text{ nF}$, 5 nF , 8 nF). To compensate the divider, following formula must be valid: $R_1C_1 = R_2C_2$.

Schema

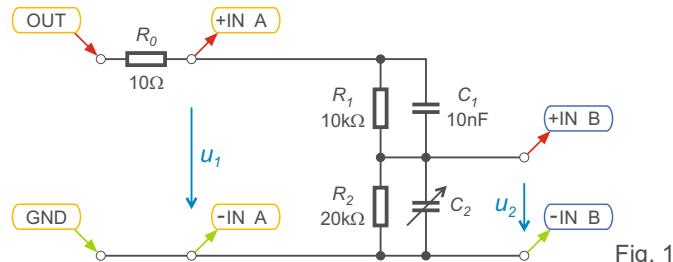
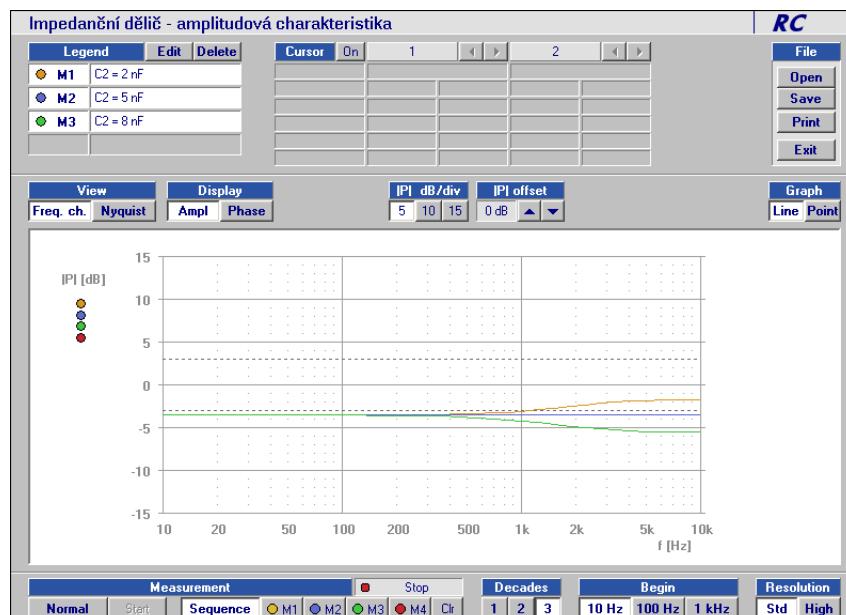


Fig. 1

Measurement



Amplitude characteristics

schema

Fig. 1

measuring mode

frequency characteristics



Phase characteristics

schema

Fig. 1

measuring mode

frequency characteristics

2.15 Equivalent Circuits (For a Single Frequency) - Time Domain

Exercise

Verify that the equivalent circuits have the same voltage transmission only for sinusoidal voltage of a single frequency.

Schema

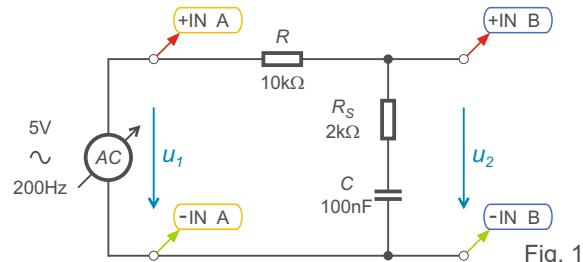


Fig. 1

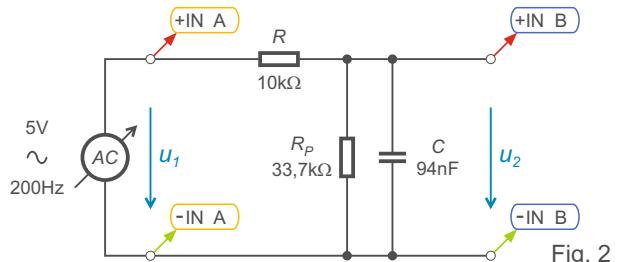
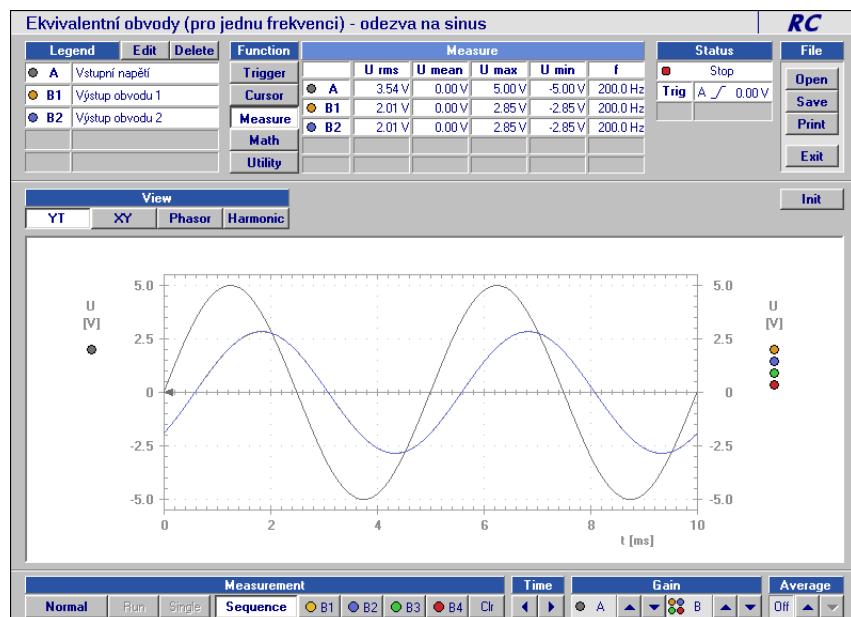


Fig. 2

Measurement



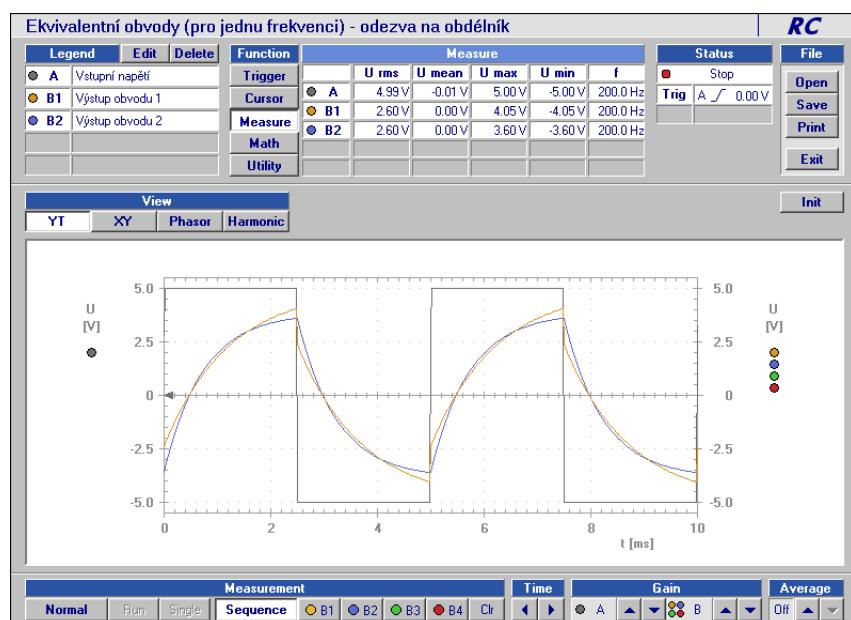
Harmonic course

schema

Fig. 1, Fig. 2

measuring mode

oscilloscope



Rectangular waveform

schema

Fig. 1, Fig. 2

measuring mode

oscilloscope

2.16 Equivalent Circuits (For a Single Frequency) - Frequency Domain

Exercise

Verify that the equivalent circuits have the same voltage transmission only for sinusoidal voltage of a single frequency.

Schema

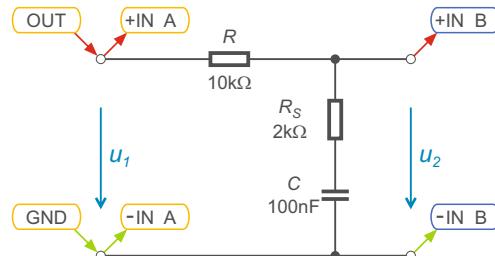


Fig. 1

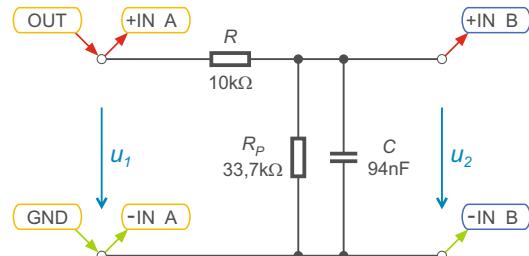
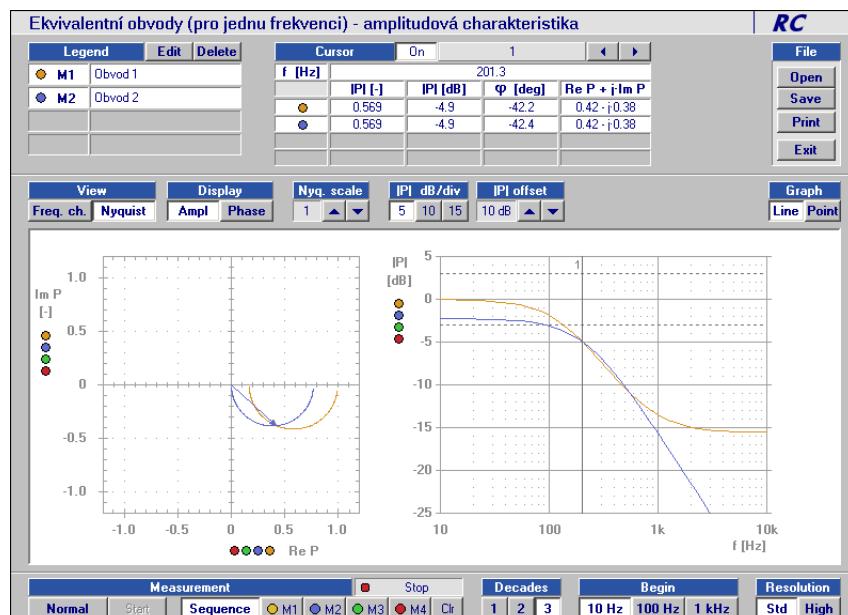


Fig. 2

Measurement



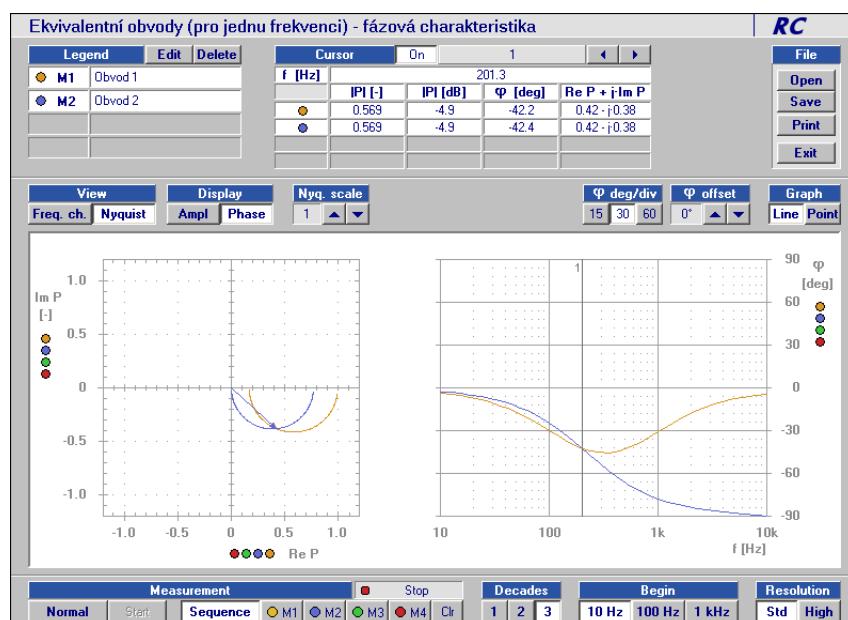
Amplitude characteristics

schema

Fig. 1, Fig. 2

measuring mode

frequency characteristics



Phase characteristics

schema

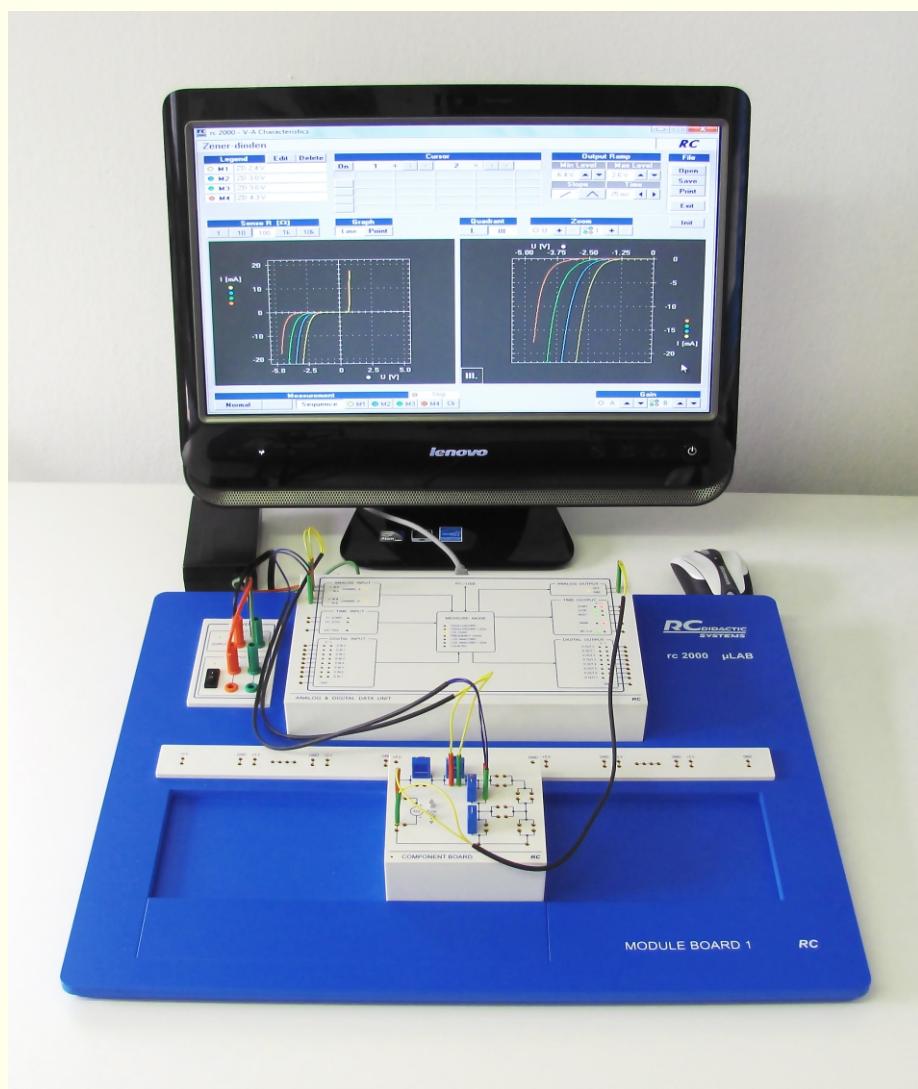
Fig. 1, Fig. 2

measuring mode

frequency characteristics

Teaching System rc2000 - μ LAB

U-I Characteristics



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3.1

Linear Resistors - Ohm Law

Exercise

Display characteristics of linear resistors. Use values 100 Ω , 200 Ω a 500 Ω .

Schema

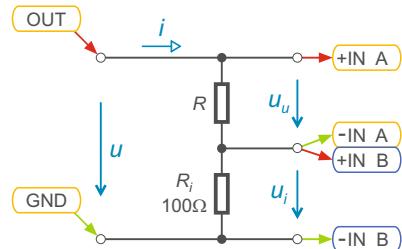
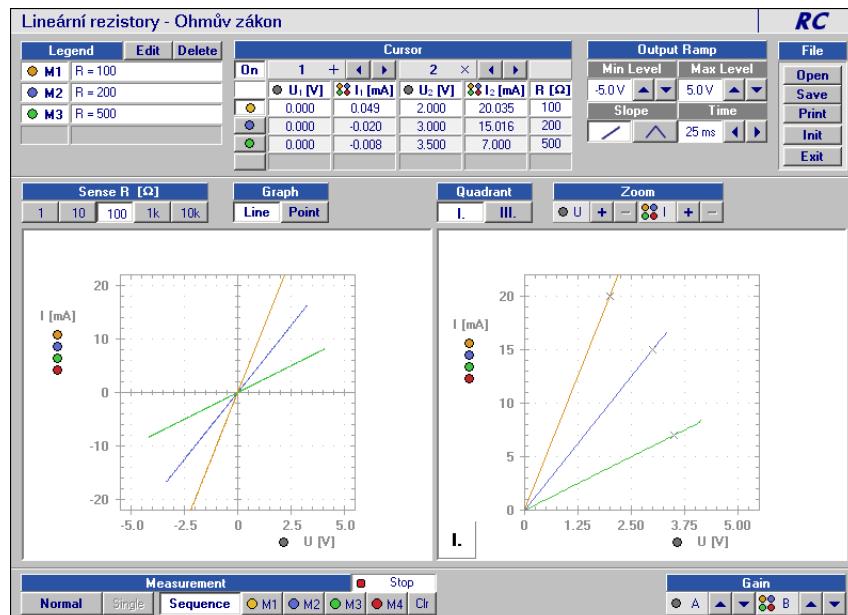


Fig. 1

$$u_u(t) = \frac{R_u}{R_i + R_u} u(t)$$

$$u_i(t) = \frac{R_i}{R_i + R_u} u(t)$$

Measurement



Linear resistors

schema

Fig. 1

measuring mode

U-I characteristics

3.2

NTC Resistor - U-I Characteristic

Exercise

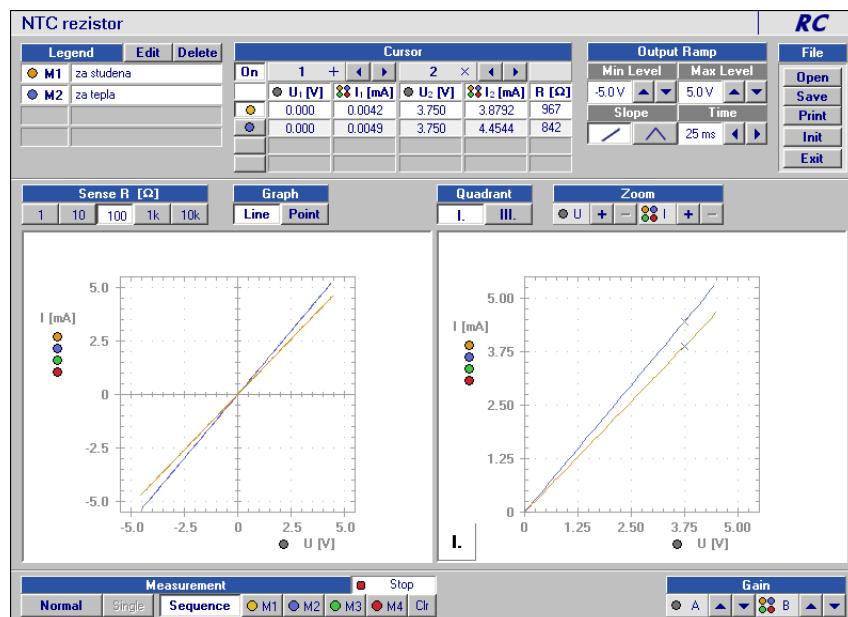
Display U-I characteristics of NTC resistor for two different temperatures.

Schema



Fig. 1

Measurement



NTC resistor

schema

Fig. 1

measuring mode

U-I characteristics

3.3

PTC Resistor - U-I characteristic

Exercise

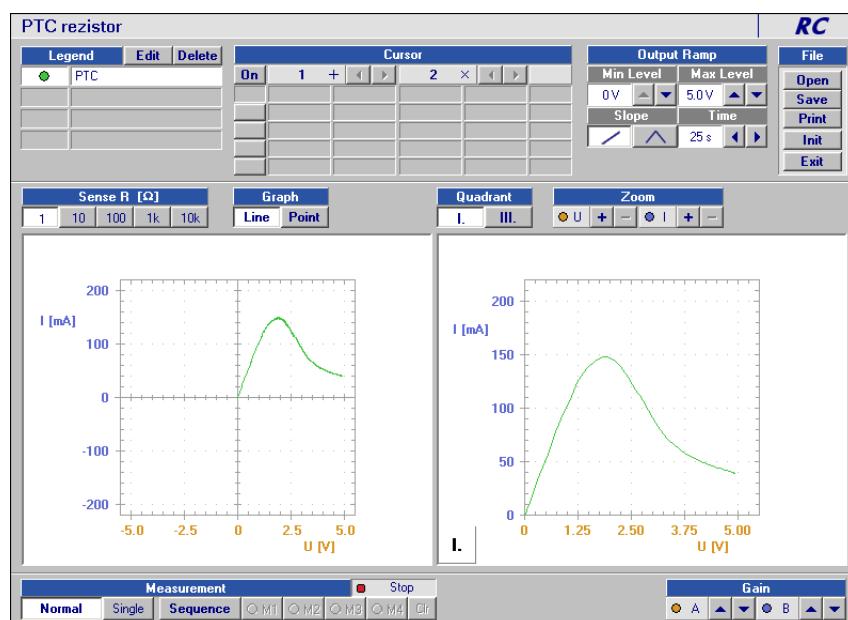
Display U-I characteristic of PTC resistor.

Schema



Fig. 1

Measurement



PTC resistor

schema

Fig. 1

measuring mode

U-I characteristics

3.4

Light Bulb - U-I Characteristic

Exercise

Display U-I characteristic of light bulb. Make the measurement both for increasing and decreasing voltage.

Schema

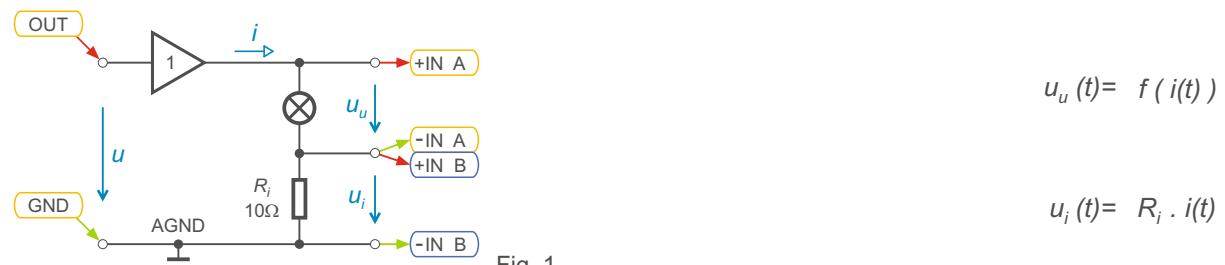
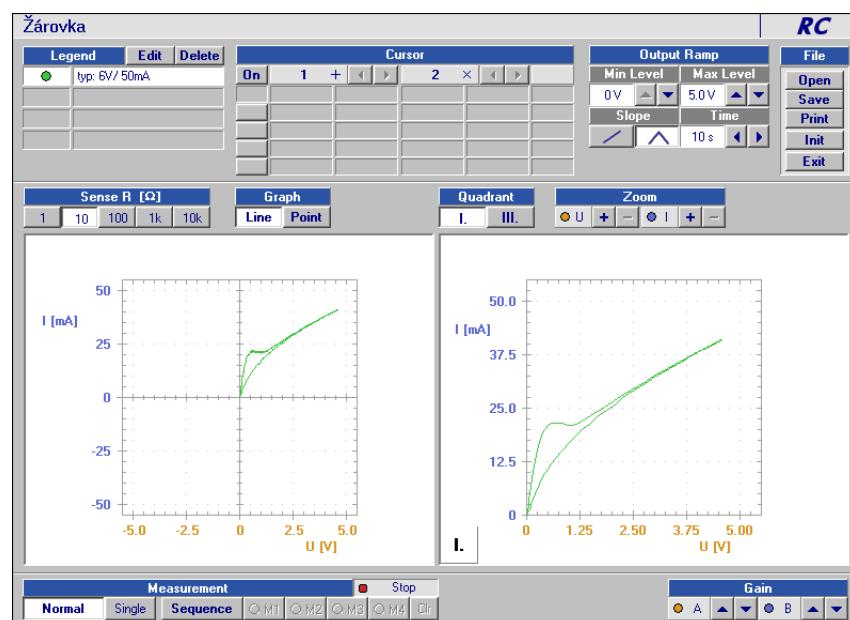


Fig. 1

Measurement



Light bulb

schema

Fig. 1

measuring mode

U-I characteristics

3.5

Rectifier Diodes - U-I Characteristics

Exercise

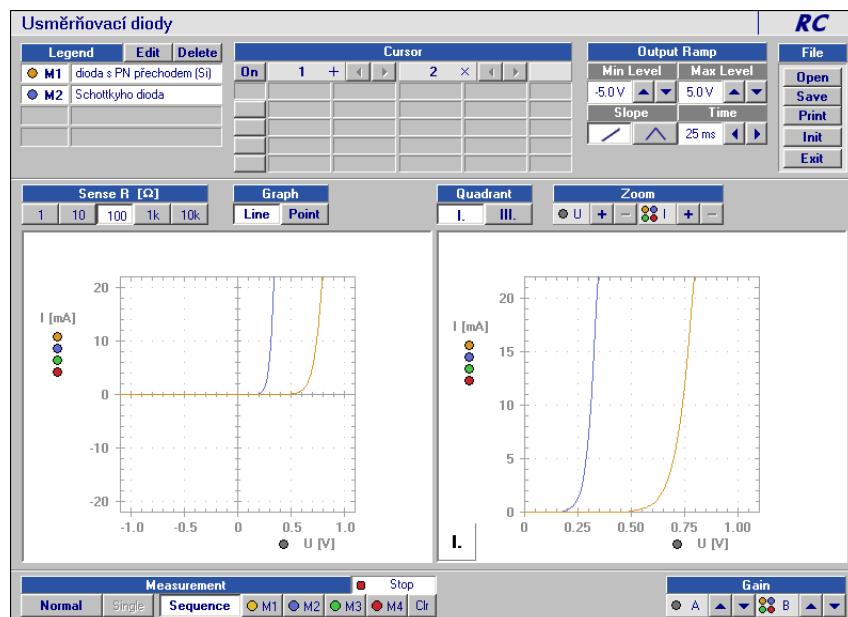
Display U-I characteristics of rectifier diodes. Compare U-I characteristic of Schottky diode with U-I characteristic of PN junction diode.

Schema



Fig. 1

Measurement



Rectifier diode

schema

Fig. 1

measuring mode

U-I characteristics

Exercise

Display U-I characteristics of Zener diodes with different Zener voltage.

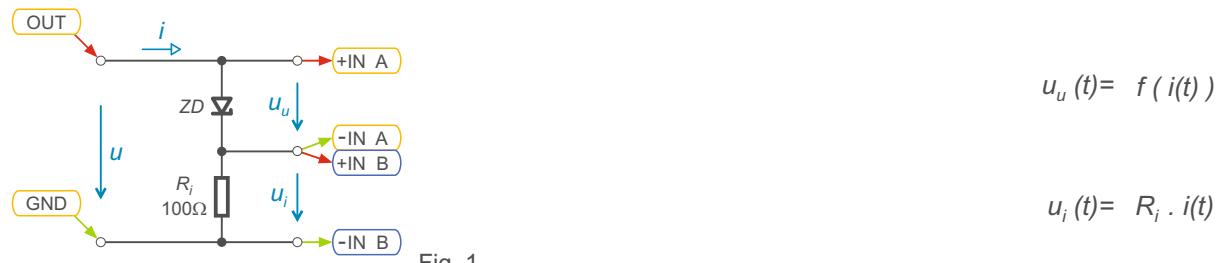
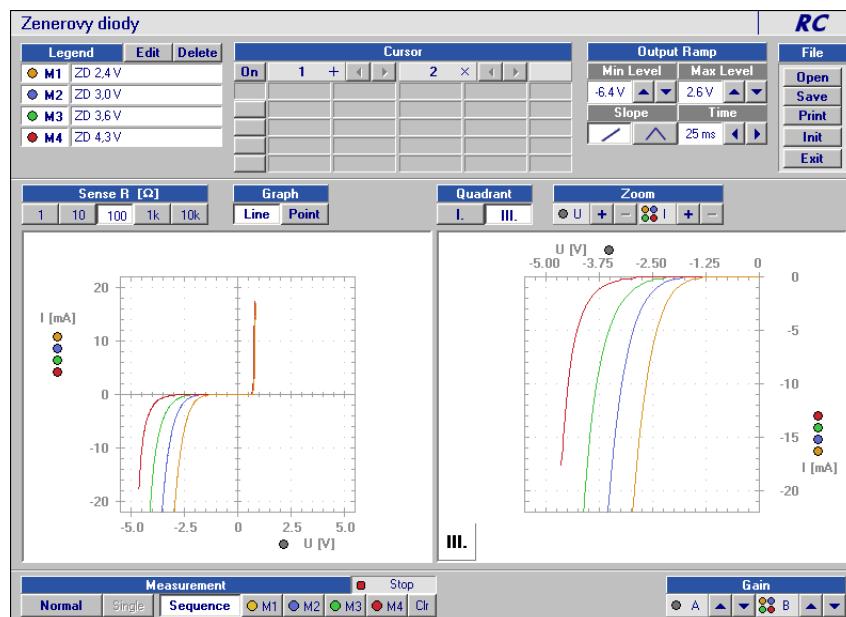
Schema

Fig. 1

Measurement

Zener diodes

schema

Fig. 1

measuring mode

U-I characteristics

3.7

Light Emitting Diodes - U-I Characteristics

Exercise

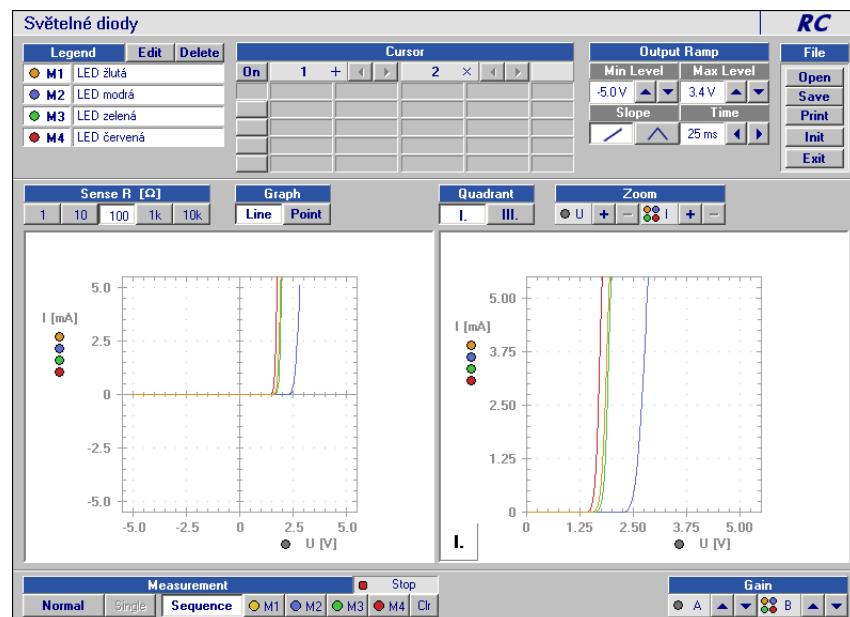
Display U-I characteristics of LEDs of different colors.

Schema



Fig. 1

Measurement



LEDs

schema

Fig. 1

measuring mode

U-I characteristics

3.8

Bipolar transil - U-I Characteristics

Exercise

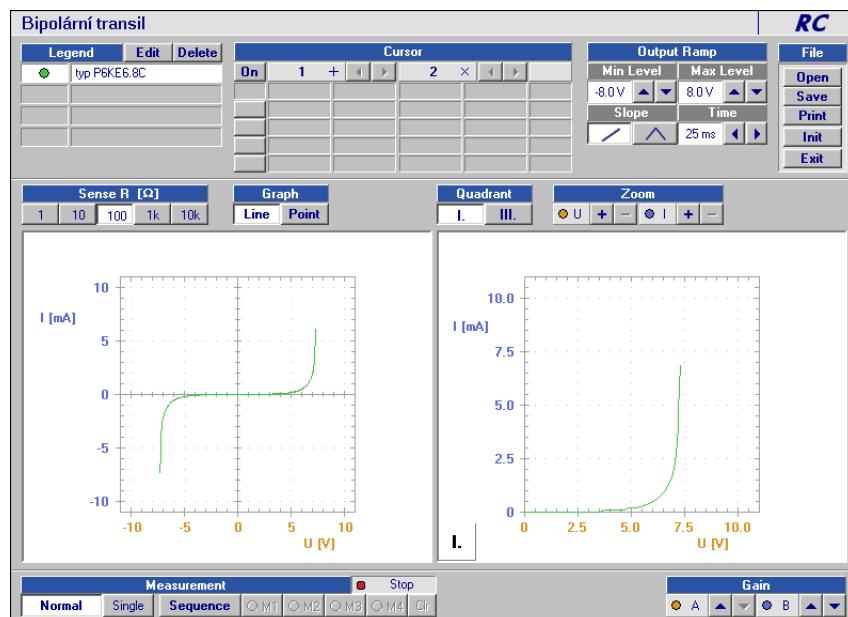
Display U-I characteristic of bipolar transil.

Schema



Fig. 1

Measurement



Bipolar transil

schema

Fig. 1

measuring mode

U-I characteristics

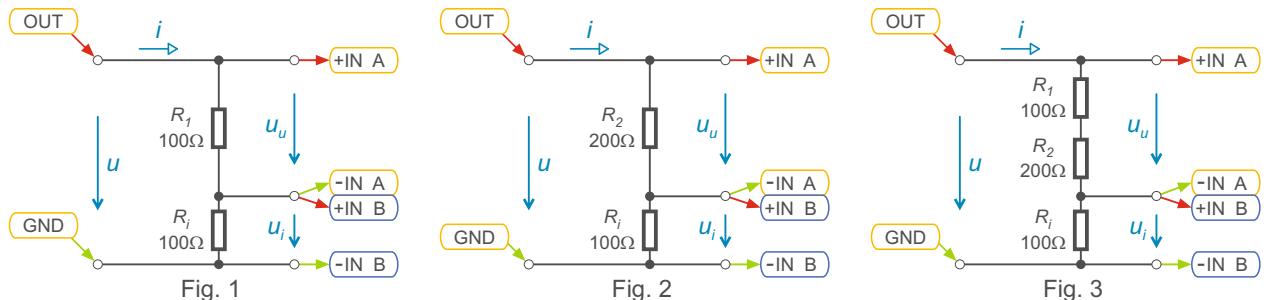
3.9

Linear Elements (Serial) - U-I characteristics

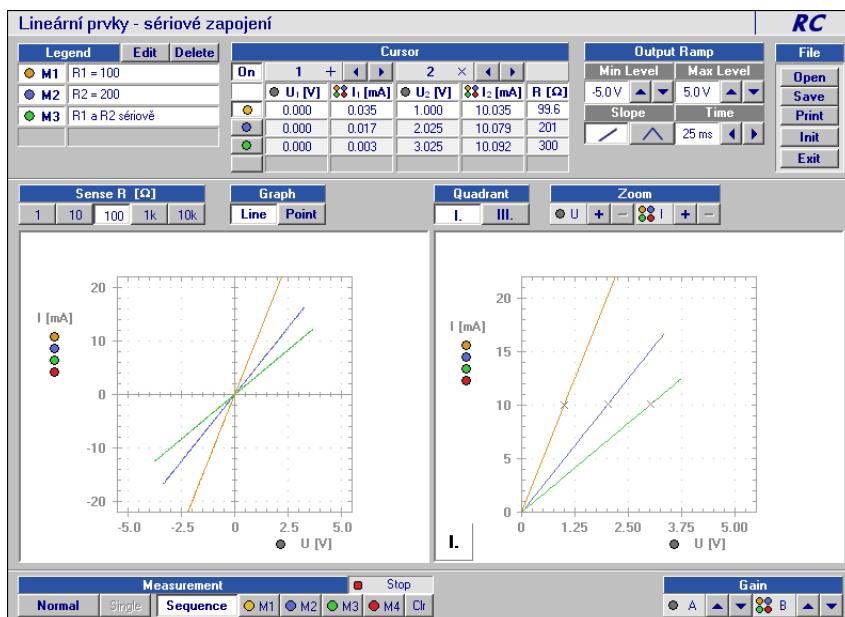
Exercise

Display U-I characteristics of two linear elements and their serial combination.

Schema



Measurement



Linear elements (serial)

schema

Fig. 1,2,3

measuring mode

U-I characteristics

- $u_u(t) = \frac{R_1}{R_i + R_1} u(t)$
- $u_u(t) = \frac{R_2}{R_i + R_2} u(t)$
- $u_u(t) = \frac{R_1 + R_2}{R_i + R_1 + R_2} u(t)$

3.10 Linear Elements (Parallel Circuit) - U-I characteristics

Exercise

Display U-I characteristics of two linear elements and their parallel combination.

Schema

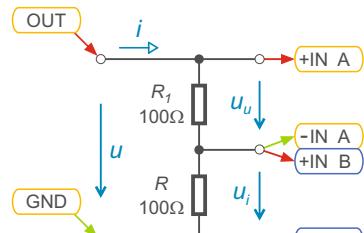


Fig. 1

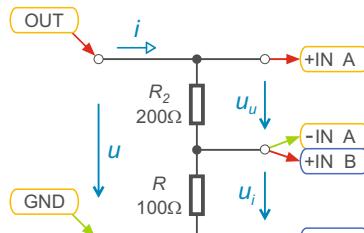


Fig. 2

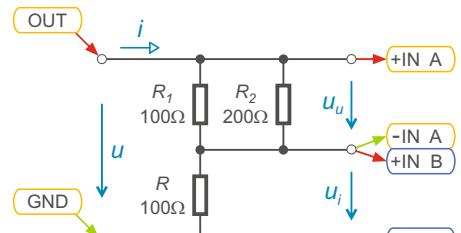
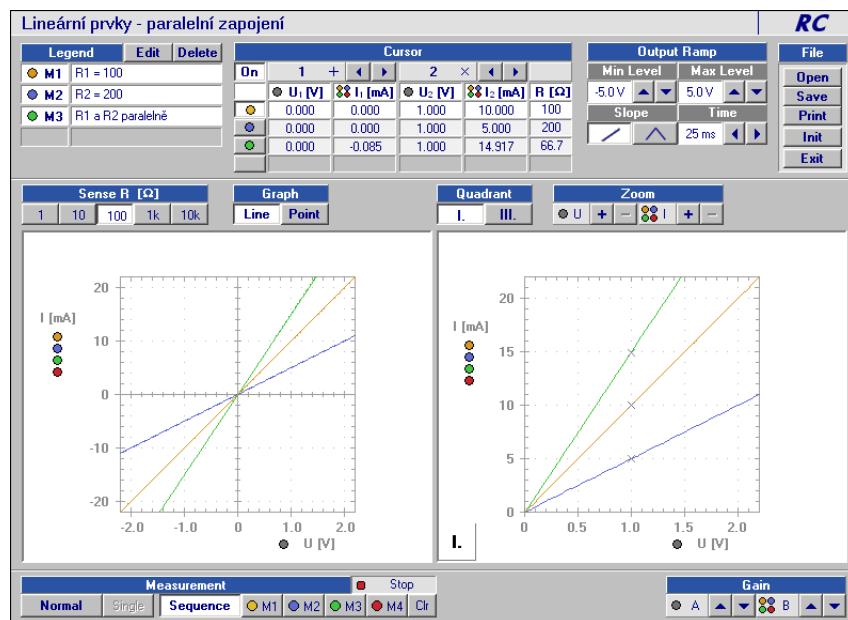


Fig. 3

Measurement



Linear elements (parallel)

schemata

Fig. 1,2,3

measuring mode

U-I characteristics

$$\bullet \quad u_u(t) = \frac{R_1}{R_i + R_1} u(t)$$

$$\bullet \quad u_u(t) = \frac{R_2}{R_i + R_2} u(t)$$

$$\bullet \quad u_u(t) = \frac{R_{1,2}}{R_i + R_{1,2}} u(t)$$

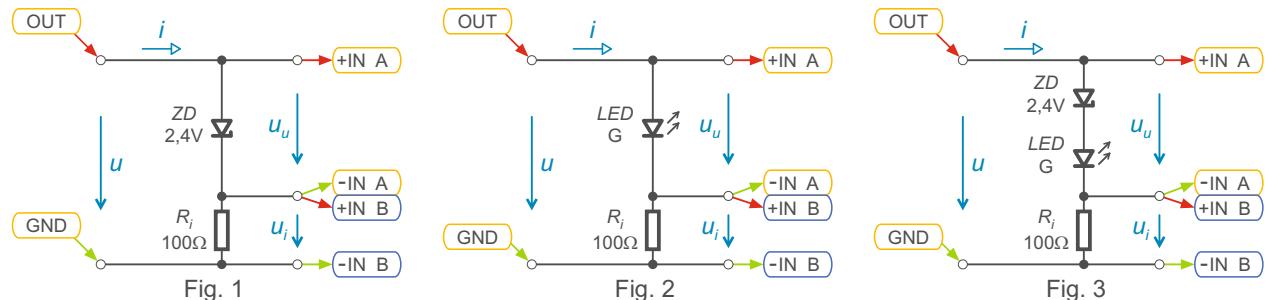
$$R_{1,2} = \frac{R_1 \cdot R_2}{R_i + R_2}$$

3.11 Nonlinear Elements (Serial Circuit) - U-I characteristics

Exercise

Display U-I characteristics of two nonlinear elements (diodes) and their serial combination.

Schema



Measurement



Nonlinear elements (serial)

schema

Fig. 1,2,3

measuring mode

U-I characteristics

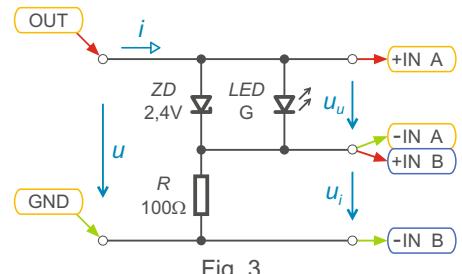
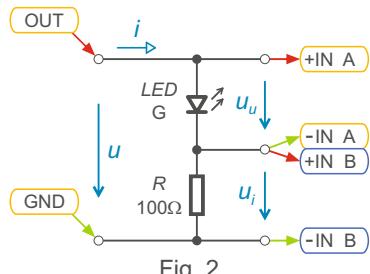
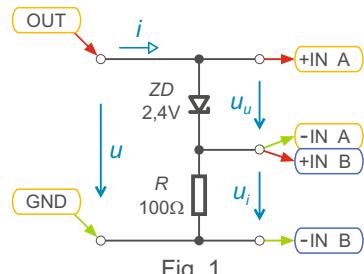
3.12

Nonlinear Elements (Parallel Circuit) - U-I Circuit

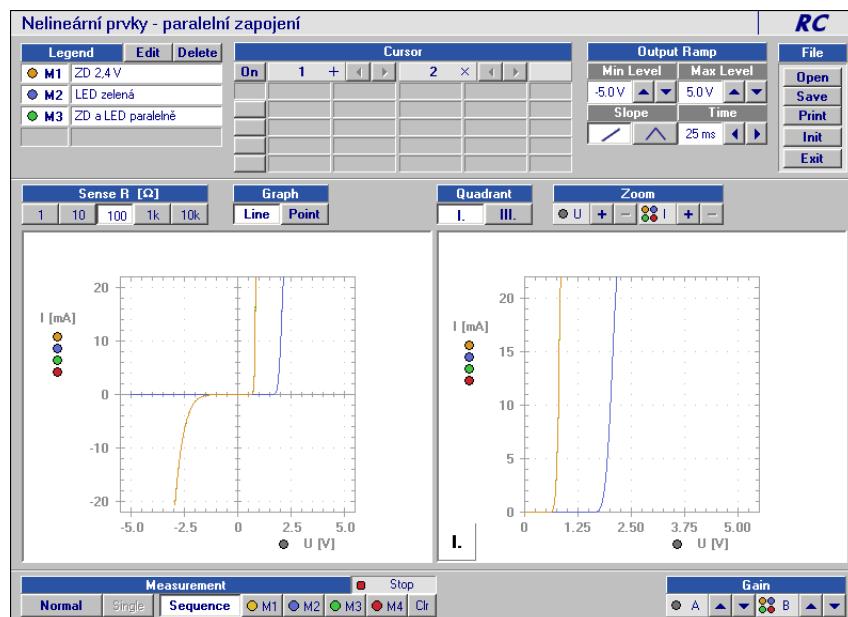
Exercise

Display U-I characteristics of two nonlinear elements (diodes) and their parallel combination.

Schema



Measurement



Nonlinear elements (parallel)

schemata

Fig. 1,2,3

measuring mode

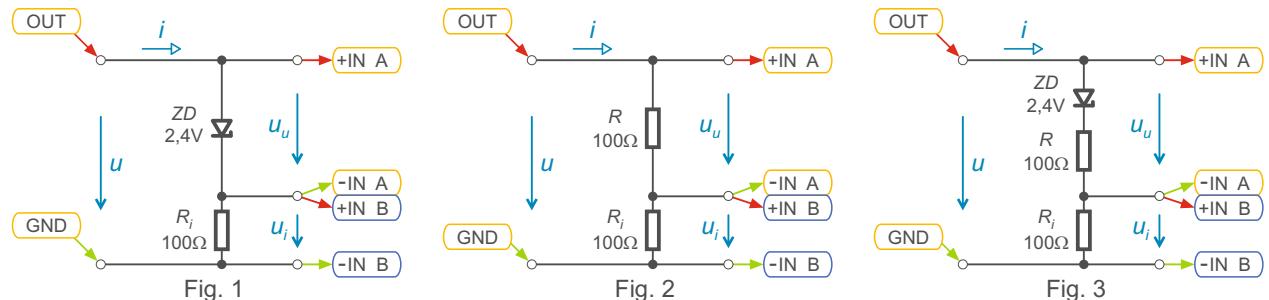
U-I characteristics

3.13 Nonlinear and Linear Elements (Serial Circuit) - U-I Characteristics

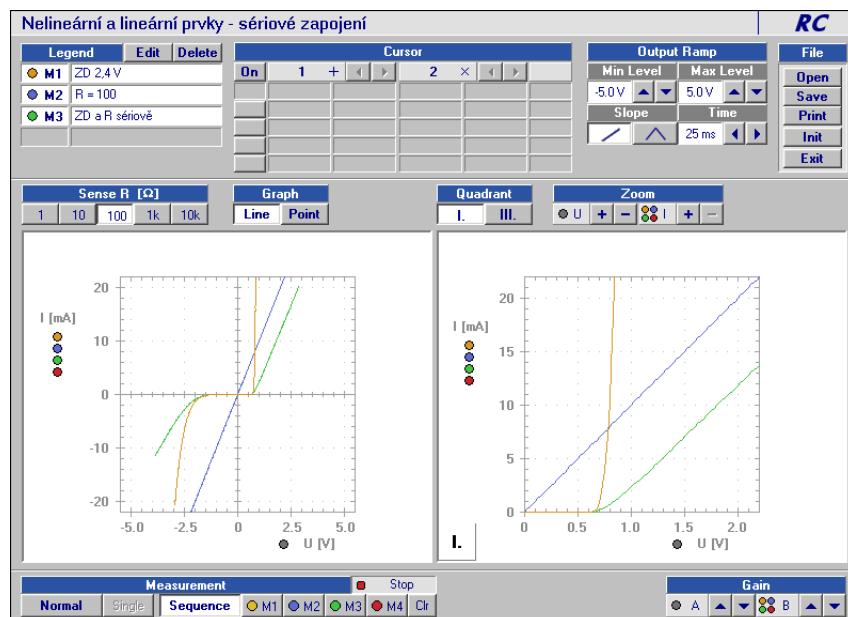
Exercise

Display U-I characteristics of serial combination of linear and nonlinear element.

Schema



Measurement



Nonlinear and linear elements

schema

Fig. 1,2,3

measuring mode

U-I characteristics

3.14 Nonlinear and Linear Elements (Parallel Circuit) - U-I Characteristics

Exercise

Display U-I characteristics of parallel combination of linear and nonlinear element.

Schema

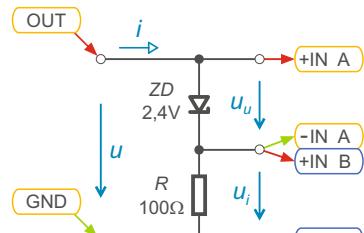


Fig. 1

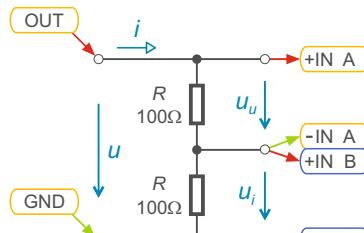


Fig. 2

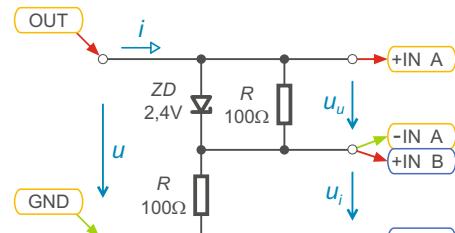
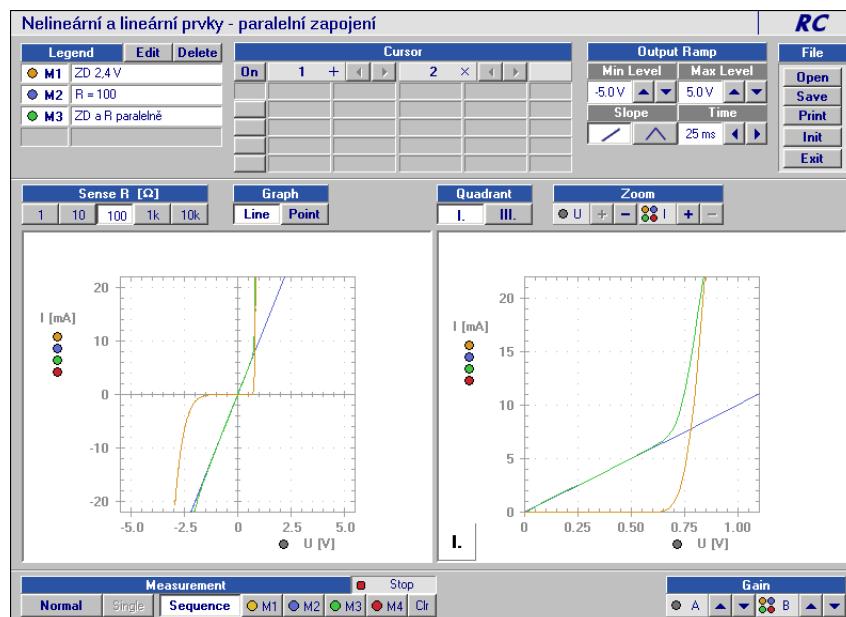


Fig. 3

Measurement



Nonlinear and linear elements

schema

Fig. 1,2,3

measuring mode

U-I characteristics

3.15

Input Characteristics of Bipolar Transistor NPN

Exercise

Measure and display input characteristics of transistor BC546B.

Schema

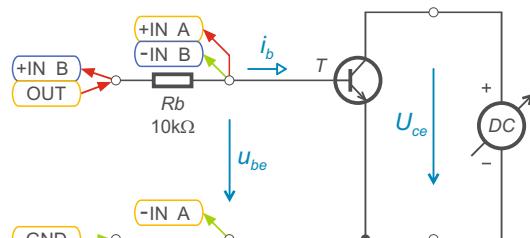


Fig. 1

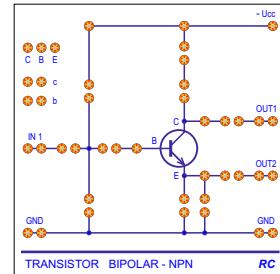
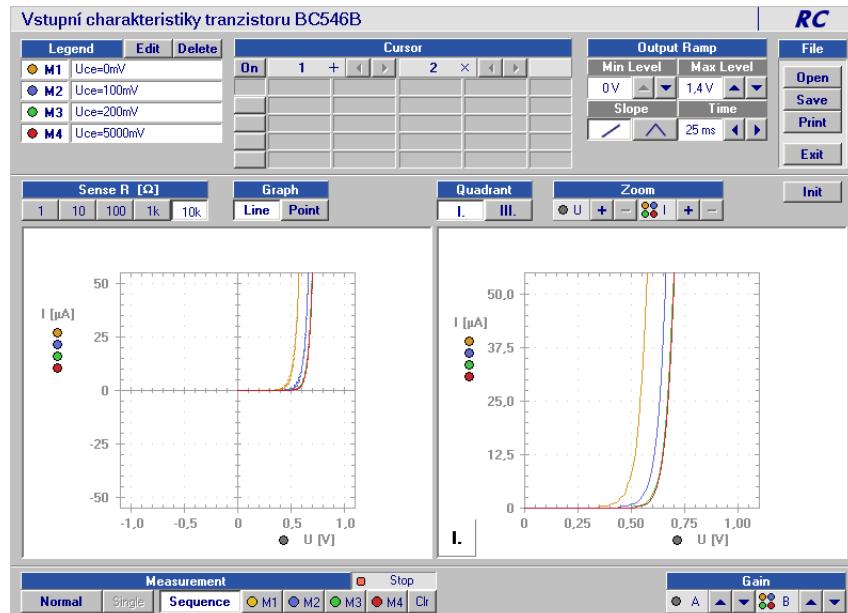


Fig. 2

Measurement



Input characteristics

schema

Fig. 1

measuring mode

V-A characteristics

Notice

- plug 3-pin element **BC546B** into a **module of bipolar transistor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safeties **b** and **c** with a couplings
- in a program (Block Output Ramp) we set output signal in a range **0V - 1,4V**

3.16

Output Characteristics of Bipolar Transistor NPN

Exercise

Measure and display output characteristics of NPN transistor BC546B.

Schema

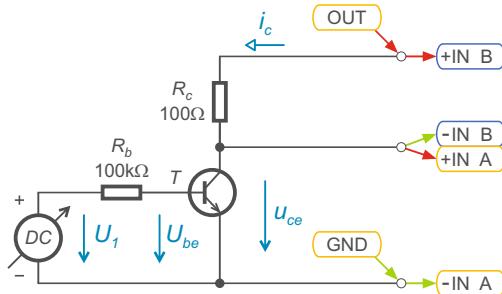


Fig. 1

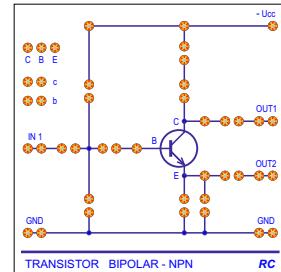
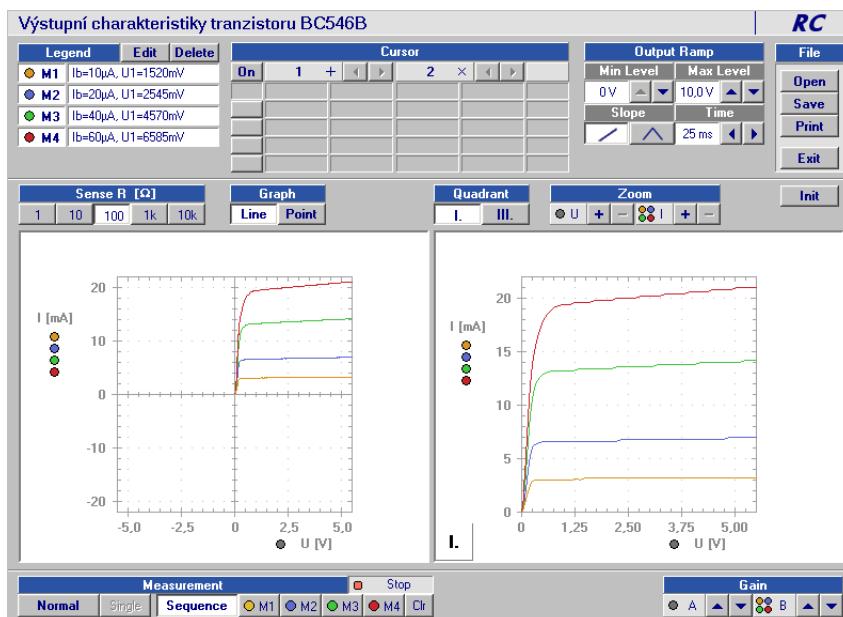


Fig. 2

Measurement



Output characteristics

schema

Fig. 1

measuring mode

V-A characteristics

Notice

- plug 3-pin element **BC546B** into a **module of bipolar transistor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safety **c** with a coupling
- in a program (BlockOutput Ramp) we set output signal in a range **0V - 10V**

3.17

Output Characteristic of a Bipolar Transistor PNP

Exercise

Measure and display the output characteristics of the BC556B PNP transistor.

Schema

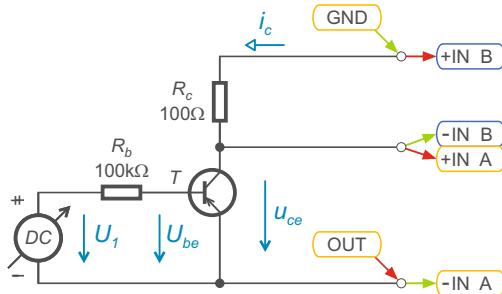


Fig. 1

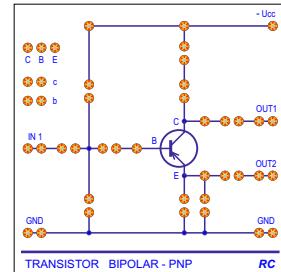
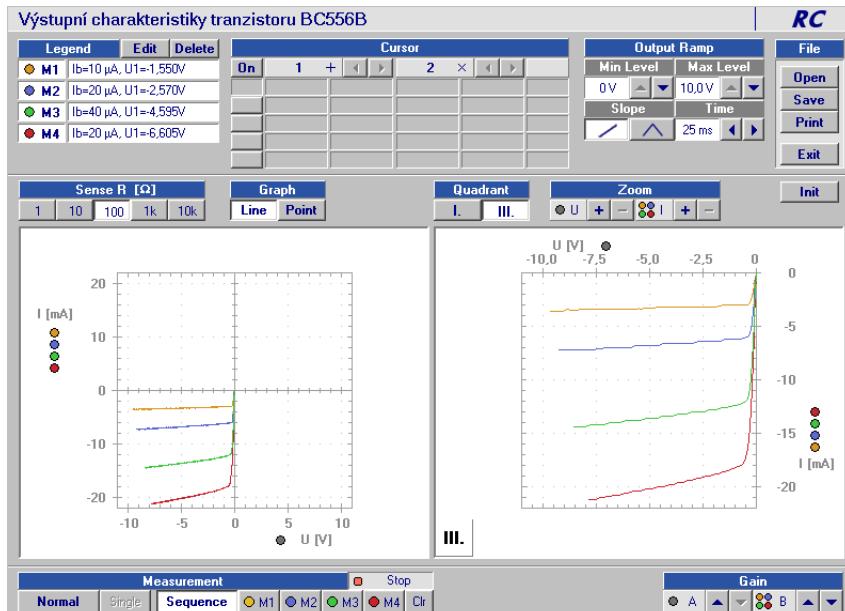


Fig. 2

Measurement



Output characteristics

schema

Fig. 1

measuring mode

V-A characteristics

Notice

- plug 3-pin element **BC556B** into a **Module of bipolar transistor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safety **c** with a coupling
- if the axis orientation of the diagram is maintained, the measured curves for the PNP transistor are "opposite" to the NPN transistor.
- in a program (BlockOutput Ramp) we set output signal in a range 0V - 10V
- the output curve of the voltage from the output ramp can only increase - so the voltage to the circuit is reversed...

3.18

Output Characteristic of a Unipolar Transistor J-FET

Exercise

Measure and display the output characteristics of transistor BF245B.

Schema

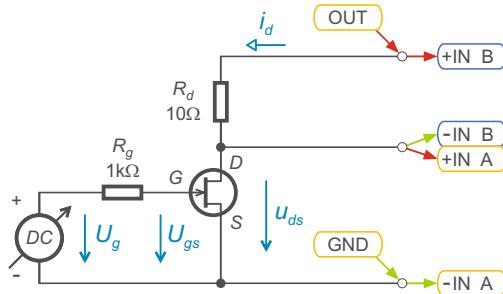


Fig. 1

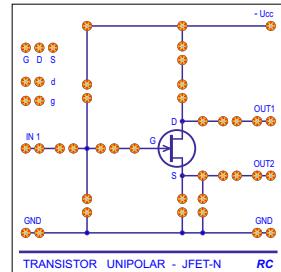
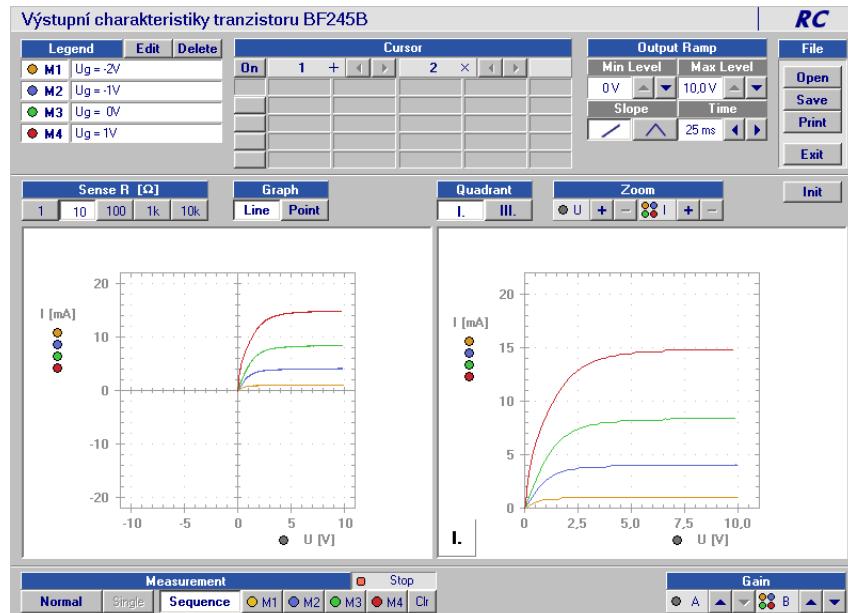


Fig. 2

Measurement



Output characteristics

schema

Fig. 1

measuring mode

V-A characteristics

Notice

- plug 3-pin element **BF245B** into a **Module of unipolar transistor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safety **d** with a coupling
- in a program (Block Output Ramp) we set output signal in a range **0V - 10V**

3.19

U-I Characteristic of the Thyristor

Exercise

Display the U-I characteristics of the thyristor.

Schema

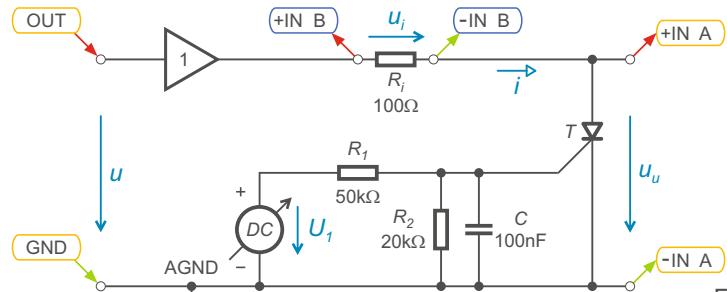


Fig. 1

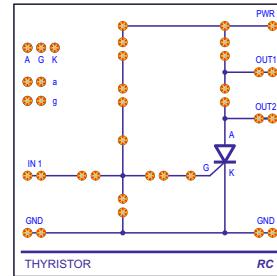
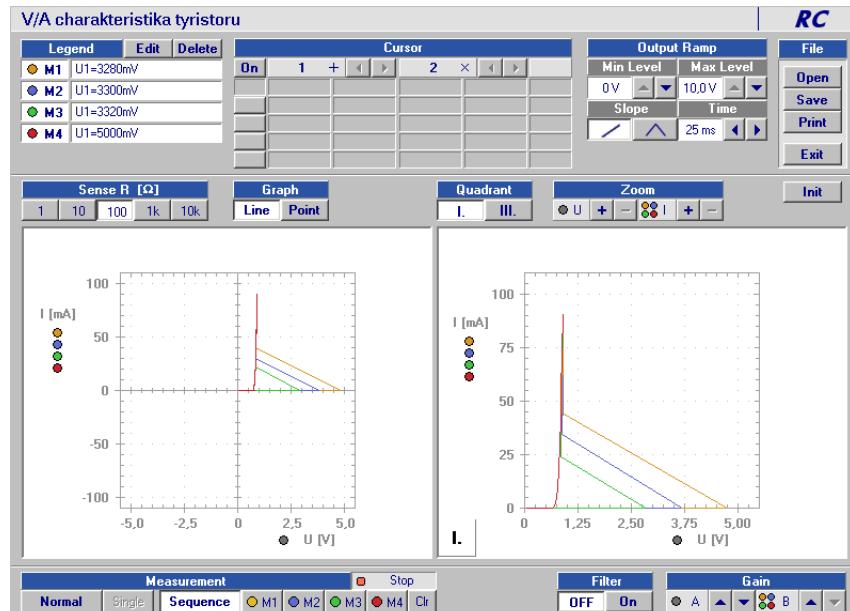


Fig. 2

Measurement



Output characteristics

schema

Fig. 1

measuring mode

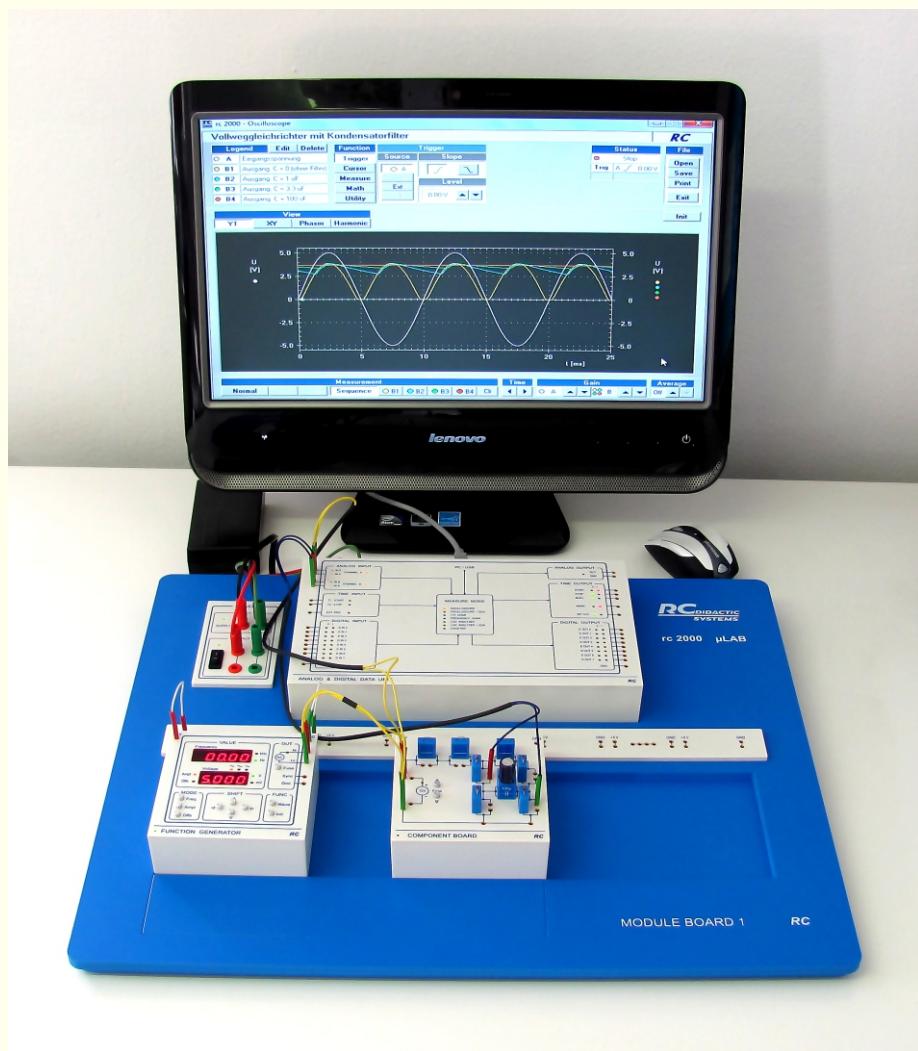
V-A characteristics

Notice

- plug 3-pin element **2N5060** into a **module of thyristor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safeties **a** and **k** with couplings
- v programu **V/A Charakteristiky** vypneme hlazení průběhu tlačítkem **Filter OFF**

Teaching System rc2000 - μ LAB

Components



RC společnost s r. o.
přístroje pro vědu a vzdělání
Cholupická 38
CZ - 142 00 Praha 4

Tel./Fax: 00420-244 464 176
Mobile: 00420-603 158 544
E-mail: info@rctidactic.cz
Web: www.rctidactic.cz

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4.1

Half-Wave Rectifier

Exercise

Display the input and output voltage of the half-wave rectifier without (Fig. 1) and with capacitor filter (Fig. 2). Use the values of filter capacitor $C = 1 \mu\text{F}$ a $10 \mu\text{F}$.

Schema

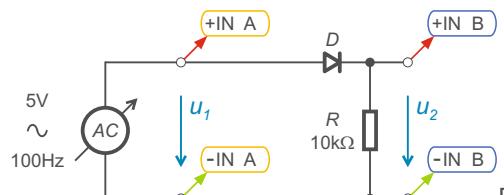


Fig. 1

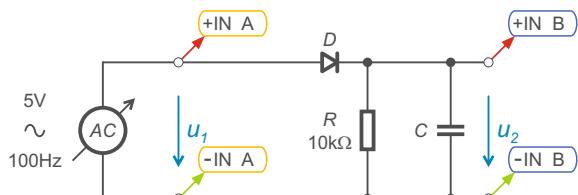
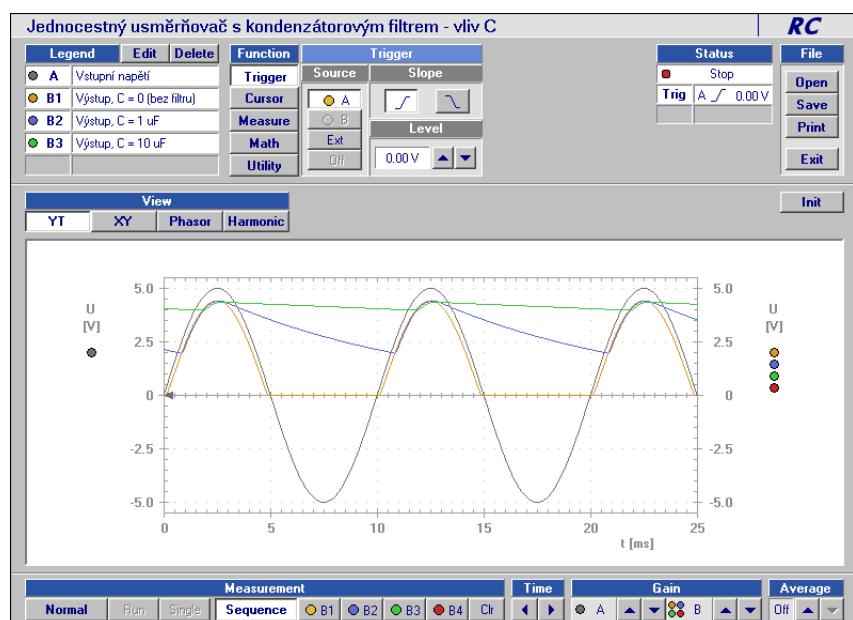
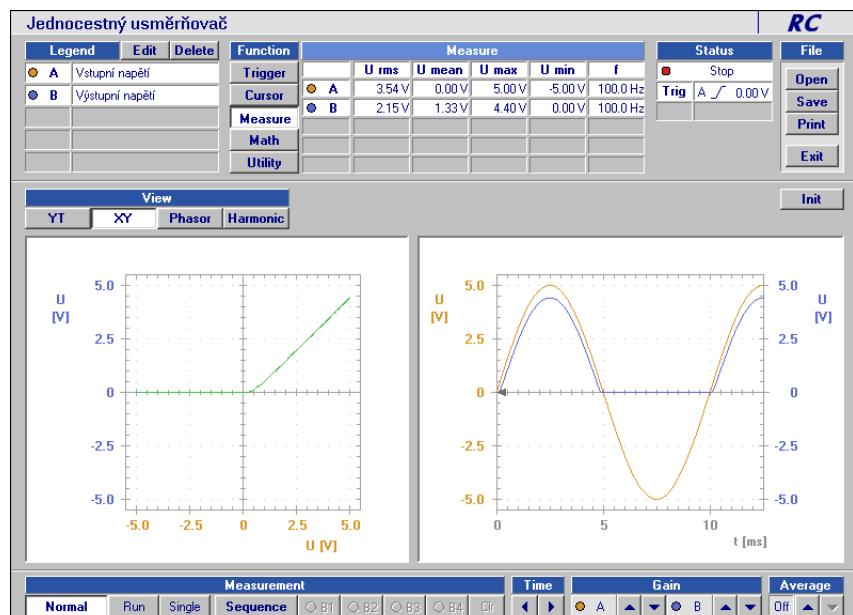


Fig. 2

Measurement



4.2

Half-Wave Rectifier - Diode Current

Exercise

Display diode current of half-wave rectifier without filter (Fig. 1) and with capacitor filter (Fig. 2).

Schema

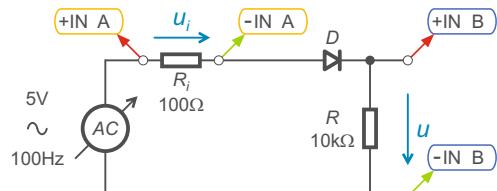


Fig. 1

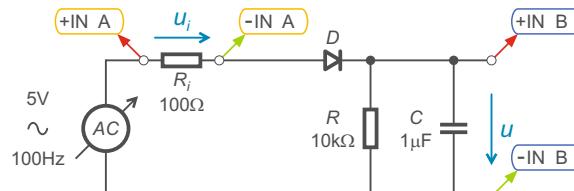
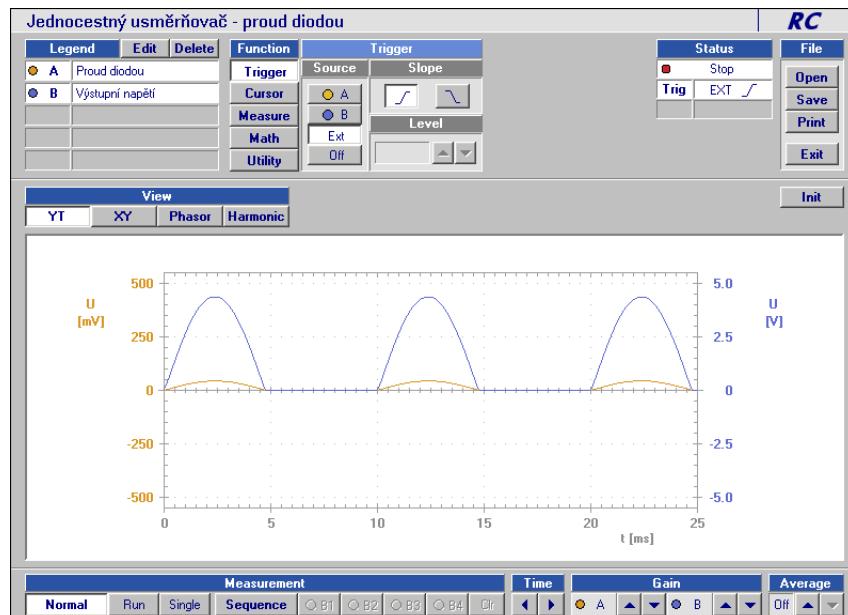


Fig. 2

Measurement



Rectifier without filter

schema

Fig. 1

measuring mode

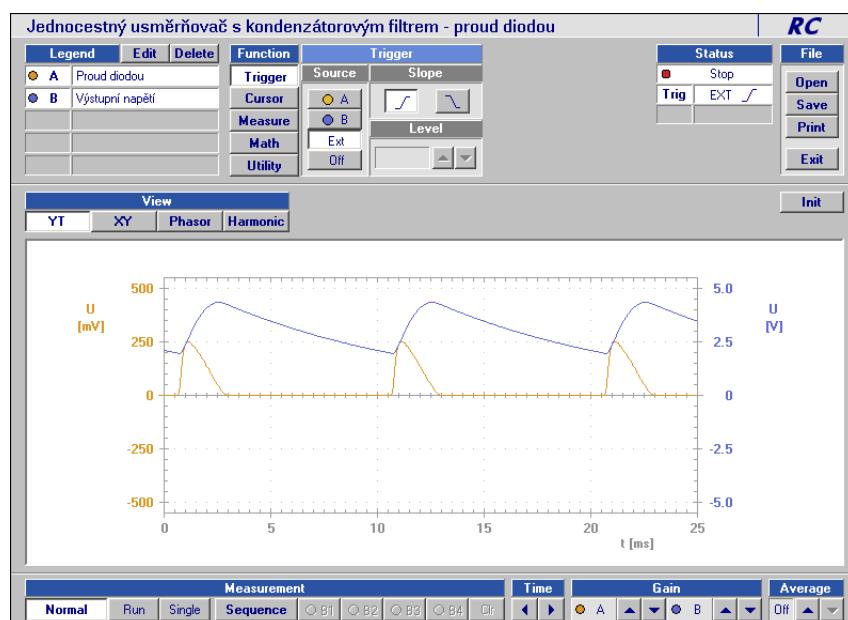
oscilloscope

connection of trigger



measured waveforms

- $i(t) = \frac{1}{R_j} u_i(t)$ (mA, kΩ, V)
- $u(t)$ (V)



Rectifier with filter

schema

Fig. 2

measuring mode

oscilloscope

connection of trigger



measured waveforms

- $i(t) = \frac{1}{R_j} u_i(t)$ (mA, kΩ, V)
- $u(t)$ (V)

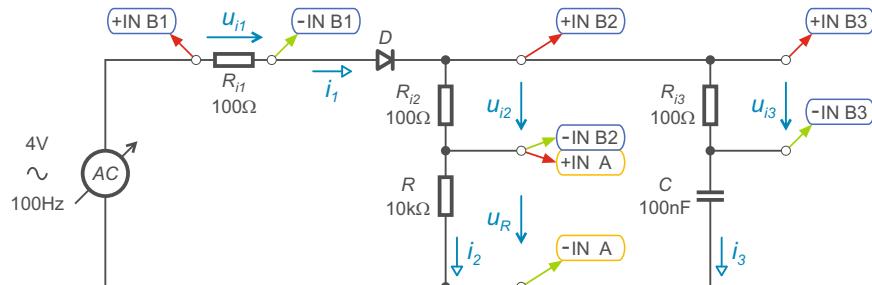
4.3

Half-Wave Rectifier with Capacitor Filter - Currents

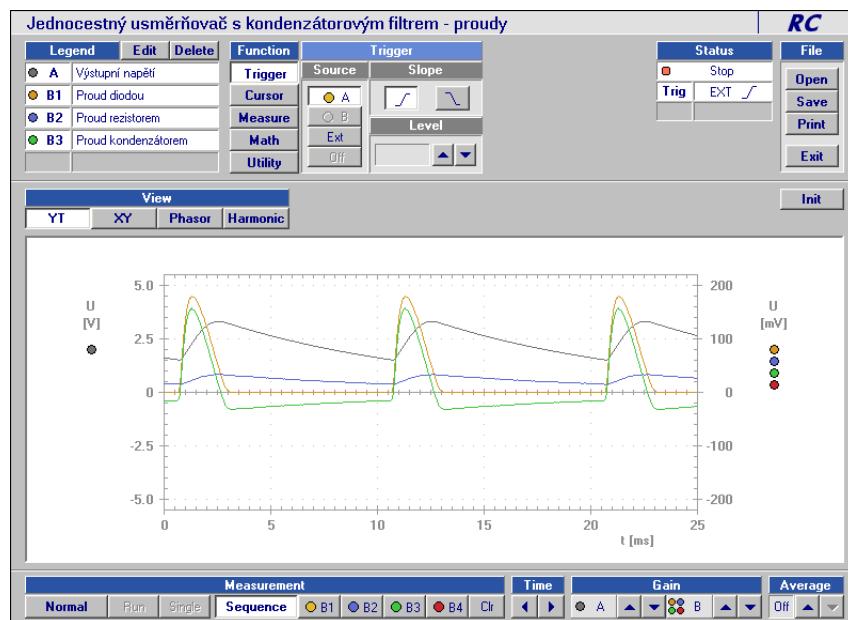
Exercise

Display currents in different parts of the half-wave rectifier with capacitor filter.

Schema



Measurement



Currents in rectifier

schema

Fig. 1

measuring mode

oscilloscope

connection of trigger



measured waveforms

$$\bullet \quad u_R(t) \quad (V)$$

$$\bullet \quad i_1(t) = \frac{1}{R_{i1}} u_{i1}(t) \quad (\text{mA, k}\Omega, \text{V})$$

$$\bullet \quad i_2(t) = \frac{1}{R_{i2}} u_{i2}(t) \quad (\text{mA, k}\Omega, \text{V})$$

$$\bullet \quad i_3(t) = \frac{1}{R_{i3}} u_{i3}(t) \quad (\text{mA, k}\Omega, \text{V})$$

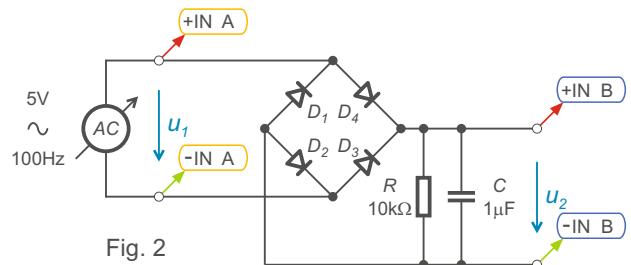
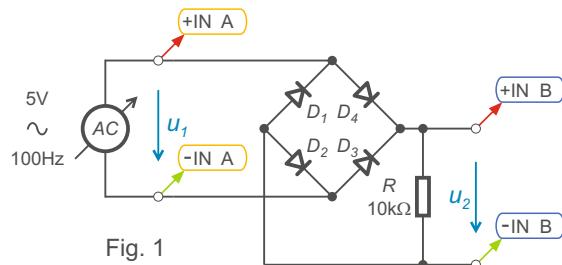
4.4

Full-Wave Rectifier

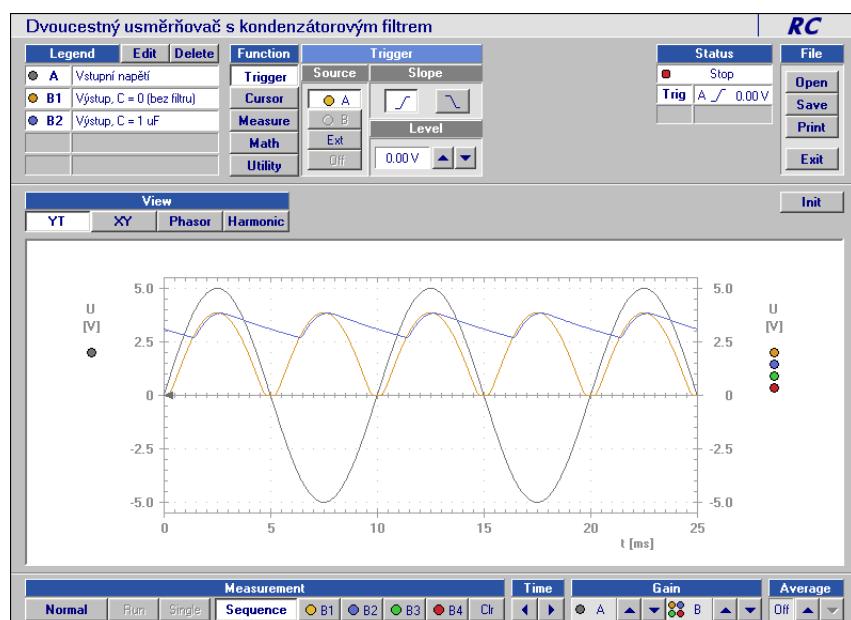
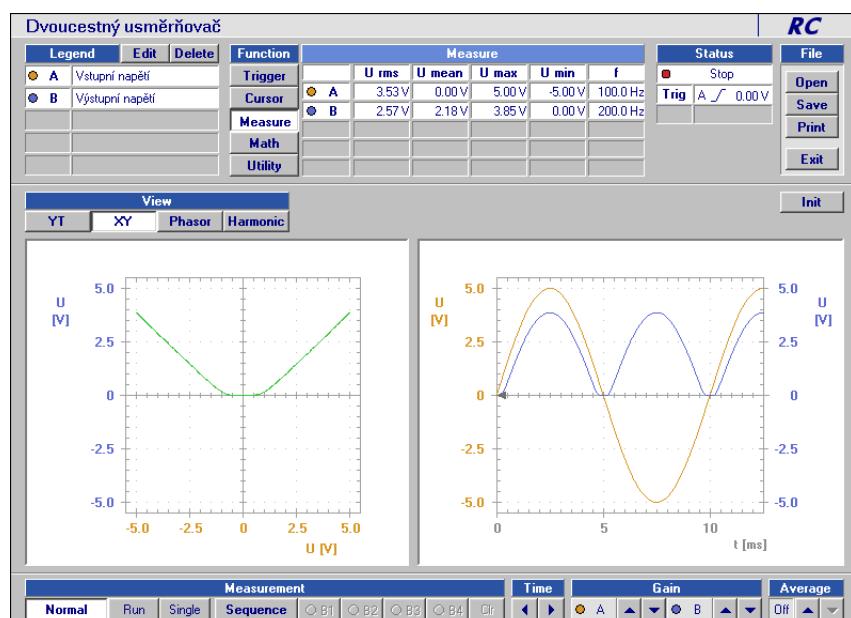
Exercise

Display the input and output voltage of the full-wave rectifier without (Fig. 1) and with capacitor filter (Fig. 2).

Schema



Measurement



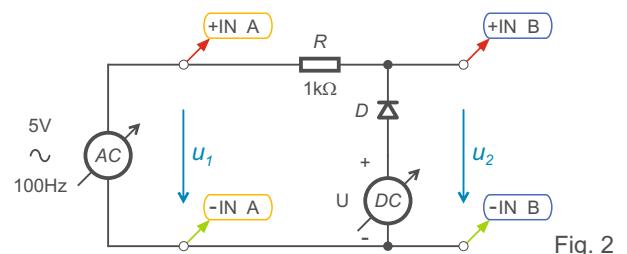
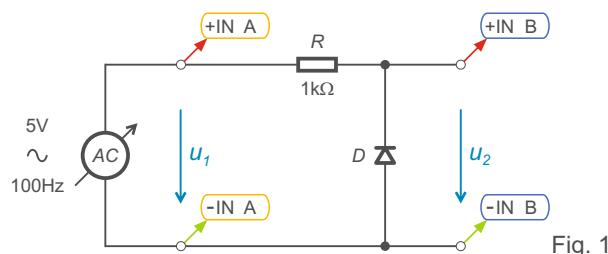
4.5

Diode Limiter

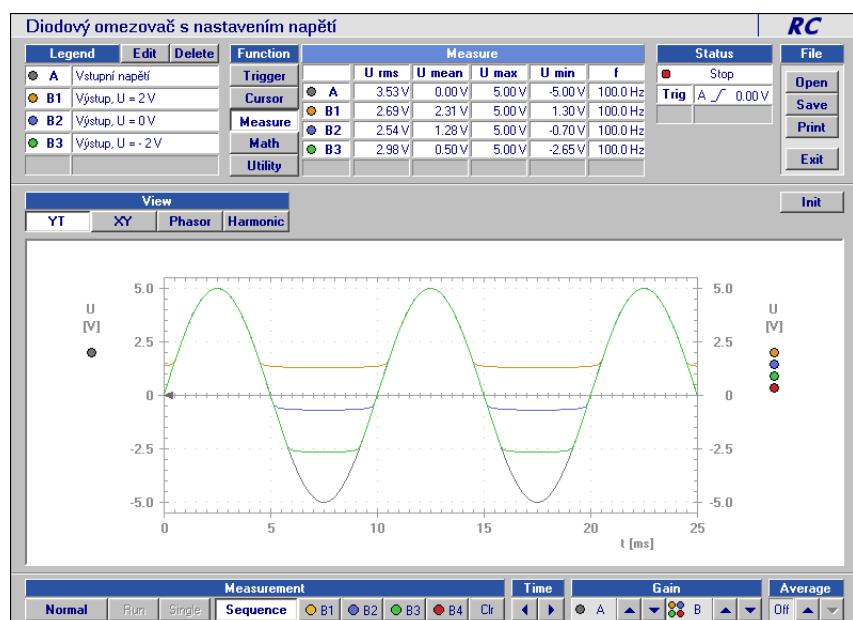
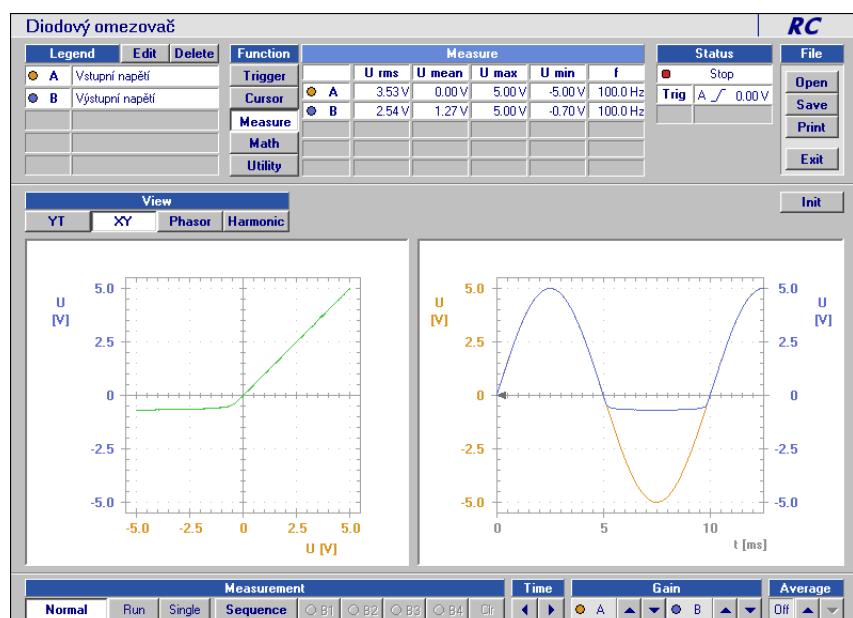
Exercise

Display the input and output voltage of the diode limiter (Fig. 1) and the diode limiter with the adjustable voltage (Fig. 2). Compare output waveforms for different voltage settings.

Schema



Measurement

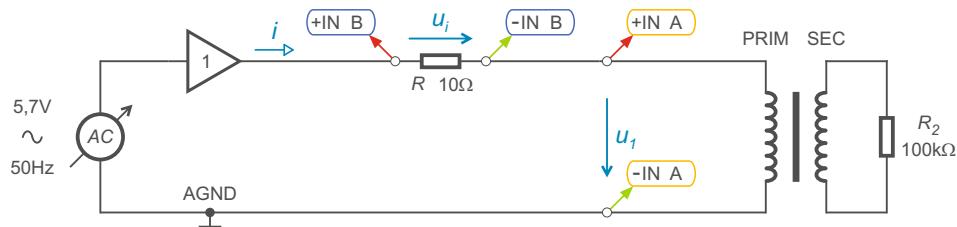


4.6 Transformer - Voltage and Current in Primary Winding

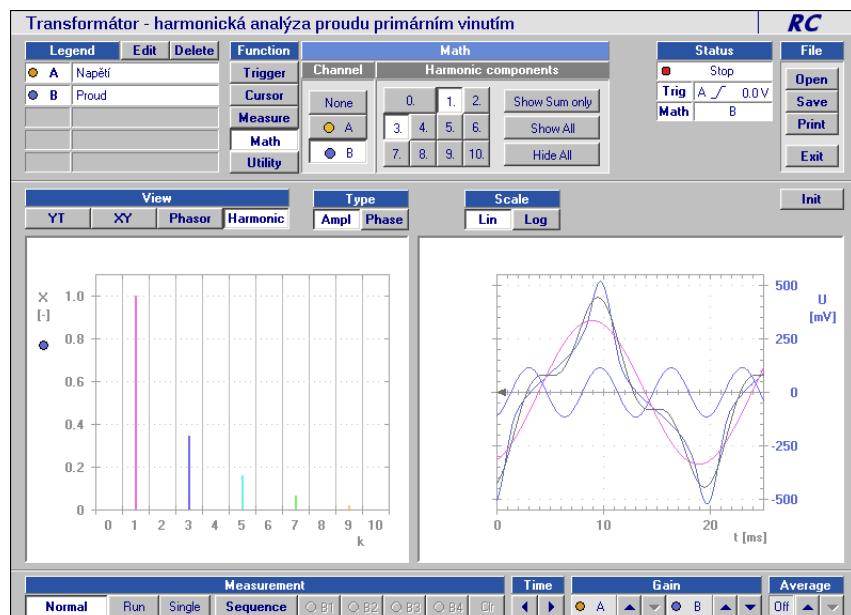
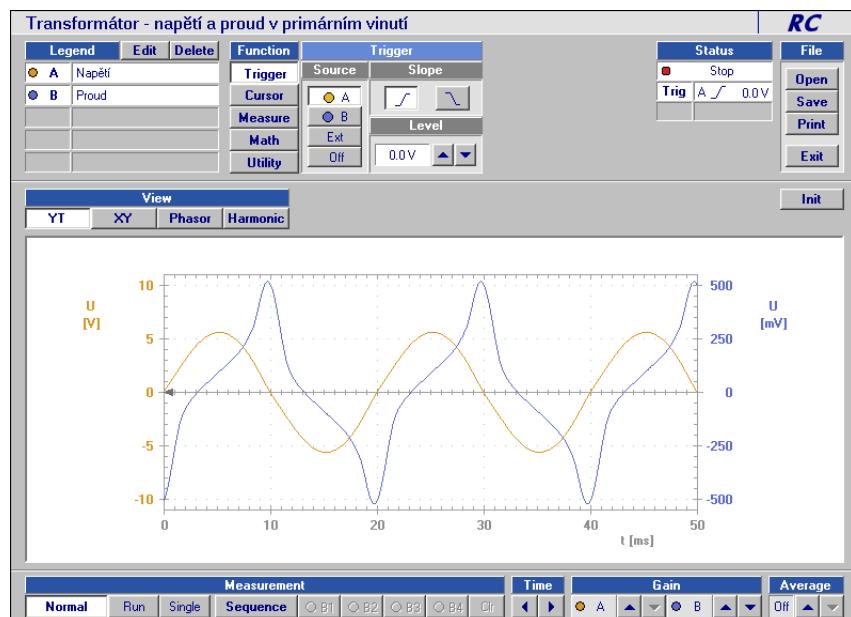
Exercise

Display current and voltage in the primary winding of the transformer.

Schema



Measurement



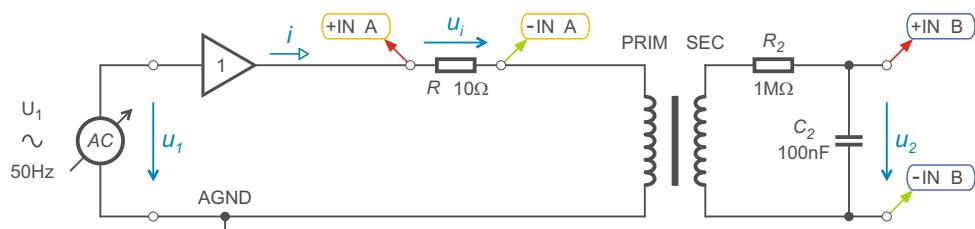
4.7

Transformer - Hysteresis Curve

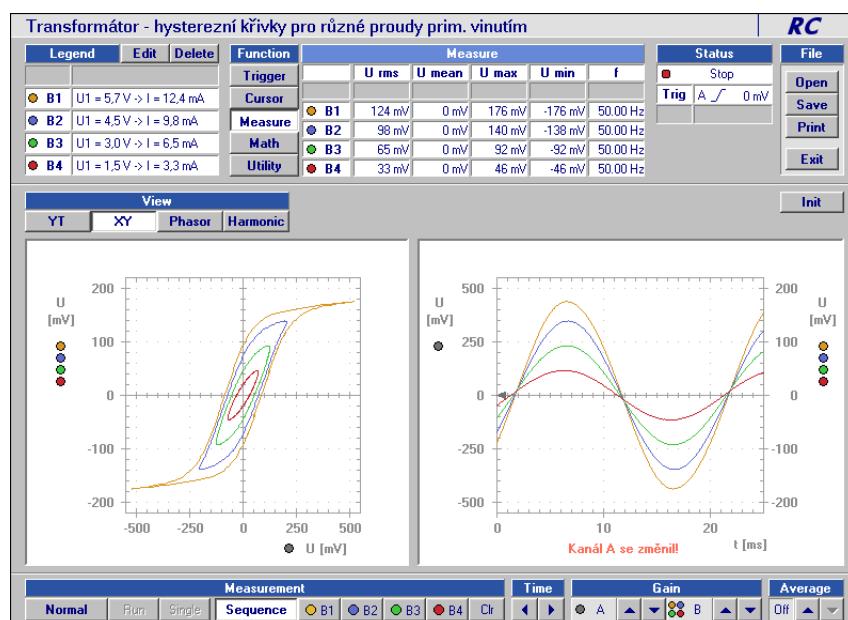
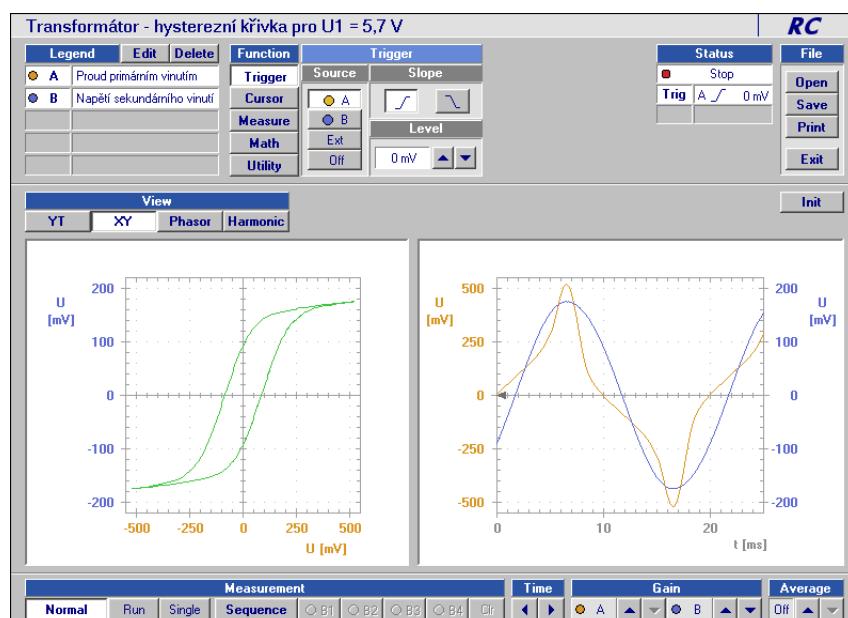
Exercise

Display the hysteresis curve of the transformer. Compare hysteresis curves for various currents of the primary winding of the transformer.

Schema



Measurement



4.8

Bipolar Transistor as Amplifier with Common Emitter

Exercise

Display the input and output voltage of the transistor amplifier.

Schema

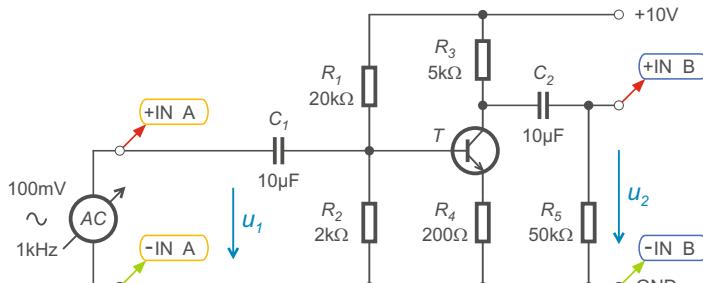


Fig. 1

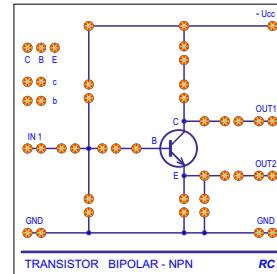
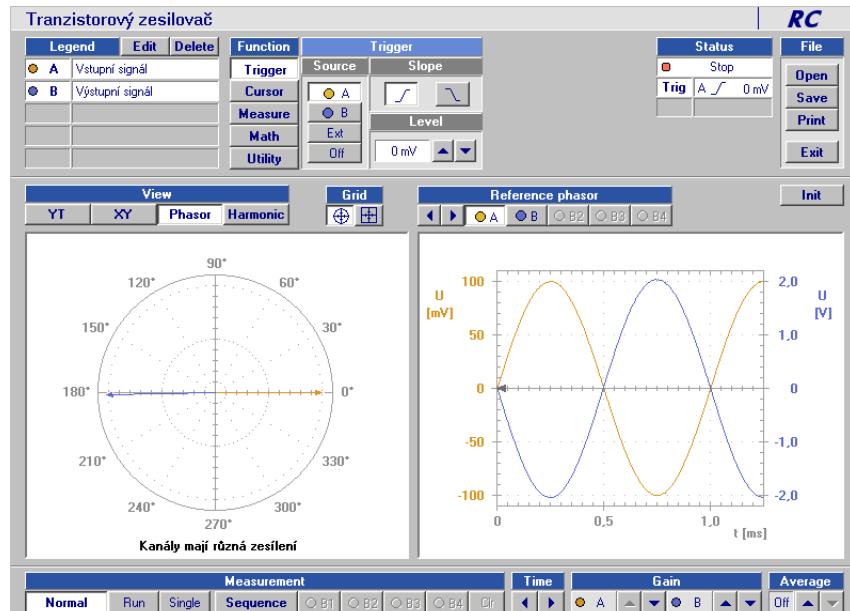


Fig. 2

Measurement



Vector diagram

schema

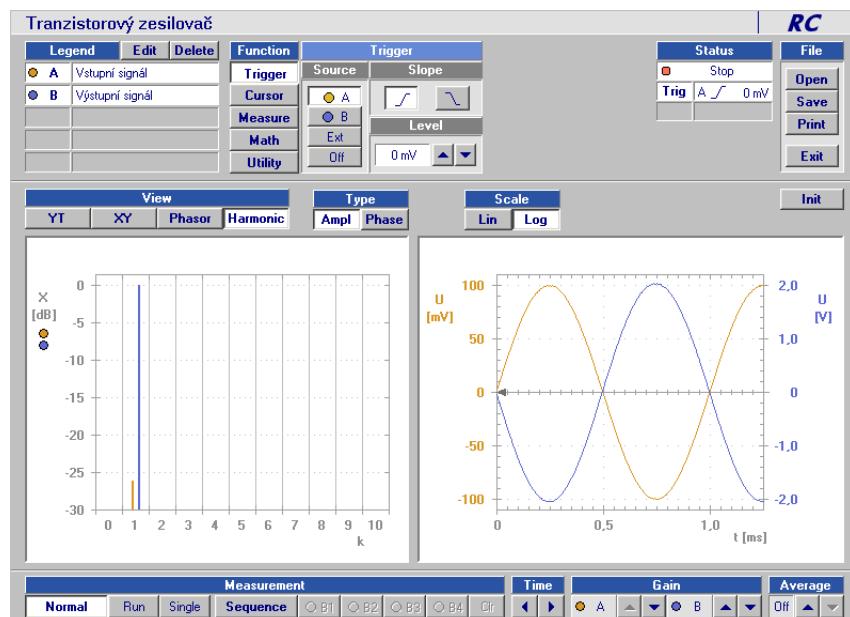
Fig. 1

measuring mode

Oscilloscope

notices

- we plug 3-pin element **BC546B** into the module (Fig. 2)
- we bridge safeties **b** and **c** with couplings
- supply voltage 10V we get from **Component Board**



Harmonic analysis

schema

Fig. 1

measuring mode

Oscilloscope

Fig. 1

4.9 Frequency Characteristic of the Amplifier with Bipolar Transistor

Exercise

Measure the frequency characteristics of the transistor amplifier and consider the effect of the coupling capacitor C_2

Schema

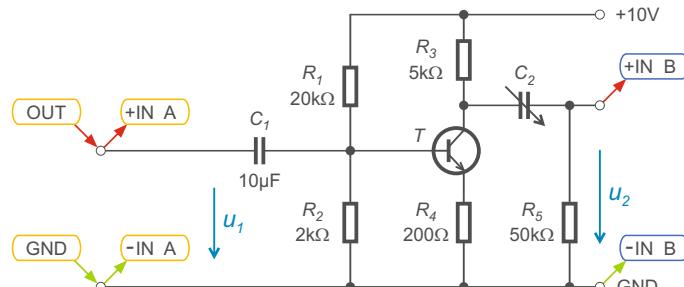


Fig. 1

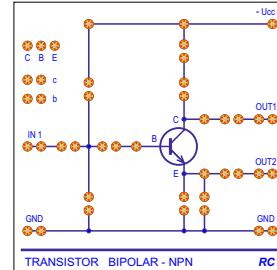


Fig. 2

Measurement



Amplitude characteristics

schema

Fig. 1

measuring mode

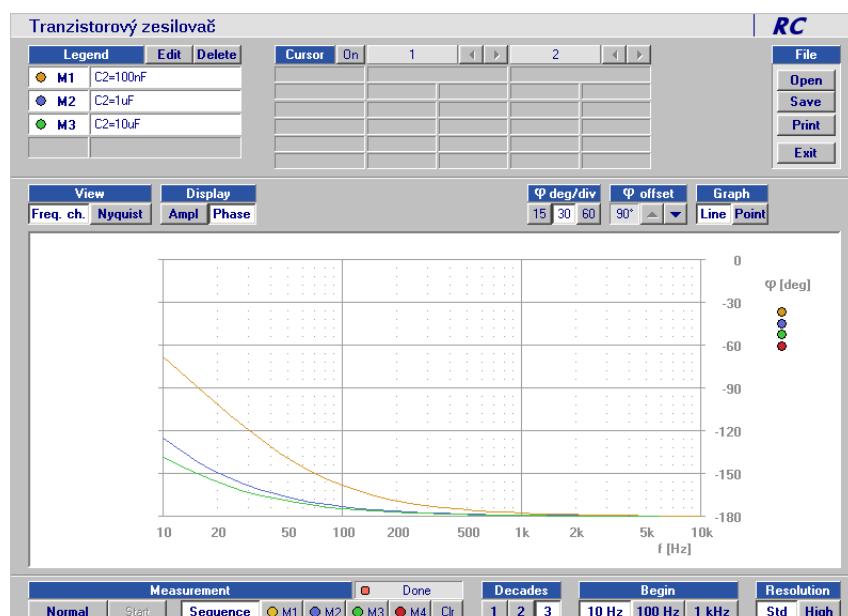
Frequency characteristics

notices

- we plug 3-pin element **BC546B** into the module (Fig. 2)

- we bridge safeties **b** and **c** with couplings

- supply voltage 10V we get from **Component Board**



Phase characteristics

schema

Fig. 1

measuring mode

Frequency characteristics

4.10

Multivibrator with Bipolar Transistor

Exercise

Turn on an astable multivibrator using two NPN transistors.

Schema

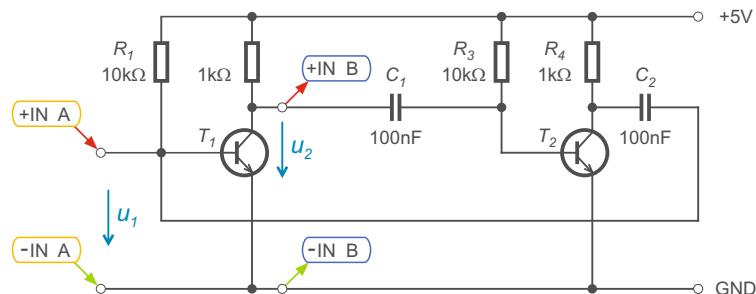


Fig. 1

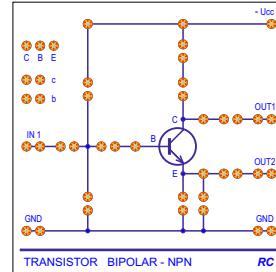
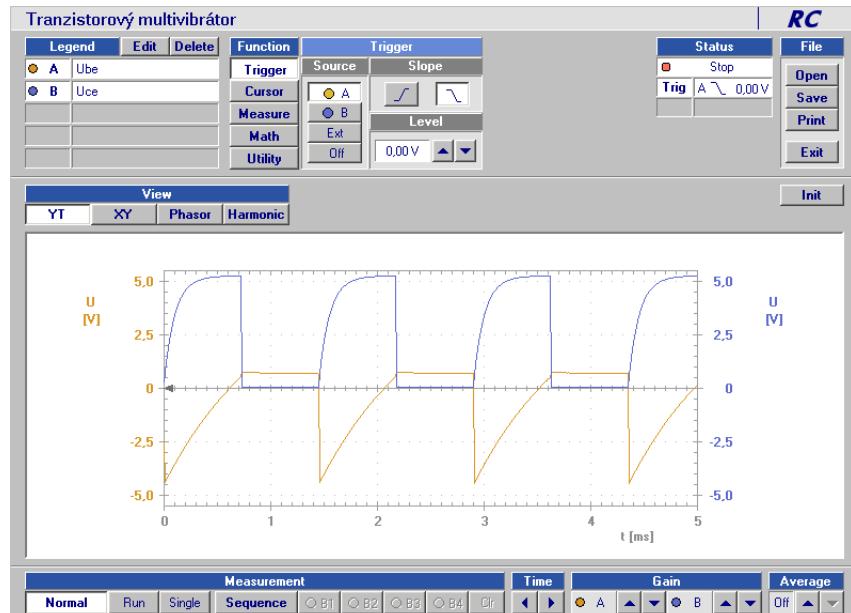


Fig. 2

Measurement



Mutivibrator

schema

Fig. 1

measuring mode

Oscilloscope

Notice

- plug 3-pin element **BC546B** into a **Module of bipolar transistor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safeties **b** and **c** with couplings

4.11

Thyristor Control of the Output Voltage

Exercise

Check the options of thyristor control.

Schema

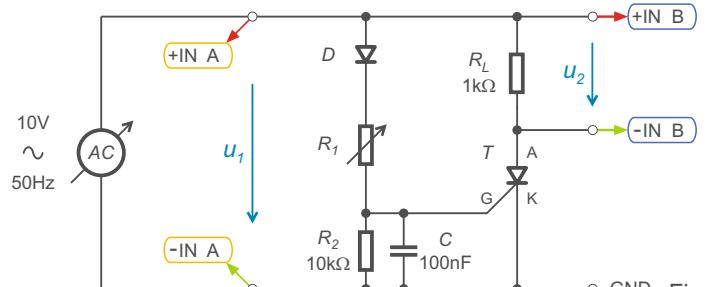


Fig. 1

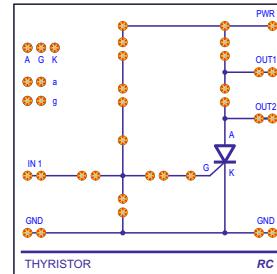
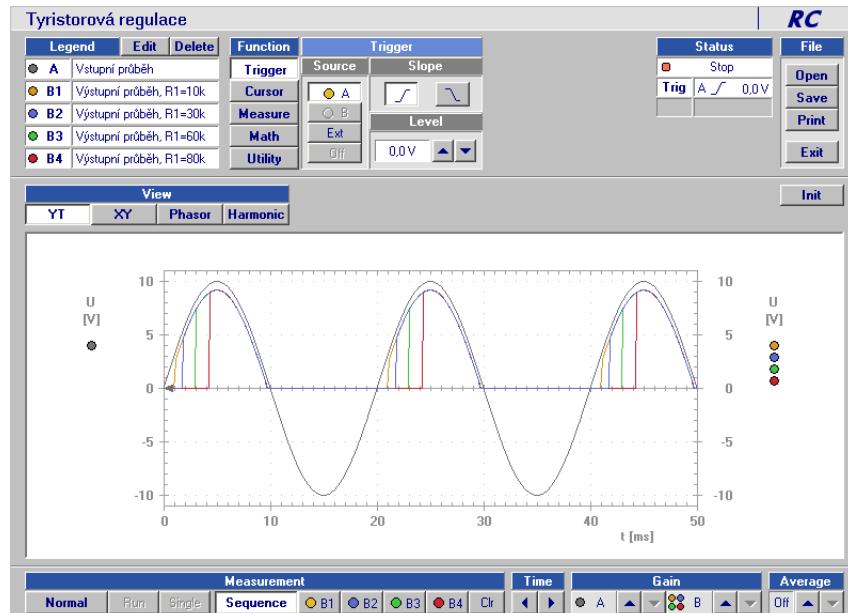


Fig. 2

Measurement



Thyristor control

schema

Fig. 1

measuring mode

Oscilloscope

Notice

- plug 3-pin element **2N5060** into a **module of thyristor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safety **a with coupling**

4.12

Thyristor Control - Voltage Curves

Exercise

Display the individual voltage profiles during thyristor control.

Schema

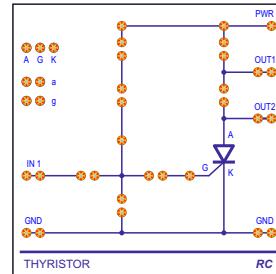
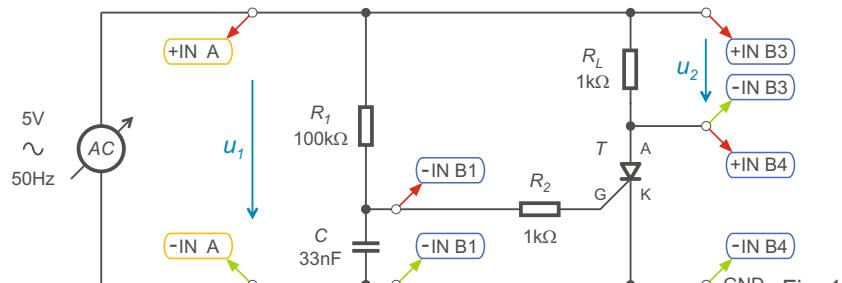
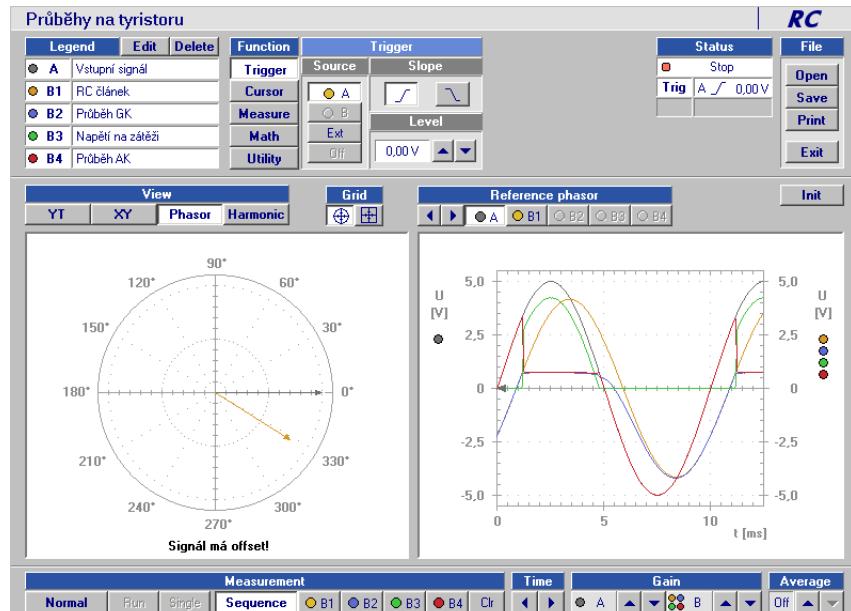


Fig. 1

Fig. 2

Measurement



Thyristor control

schema

Fig. 1

measuring mode

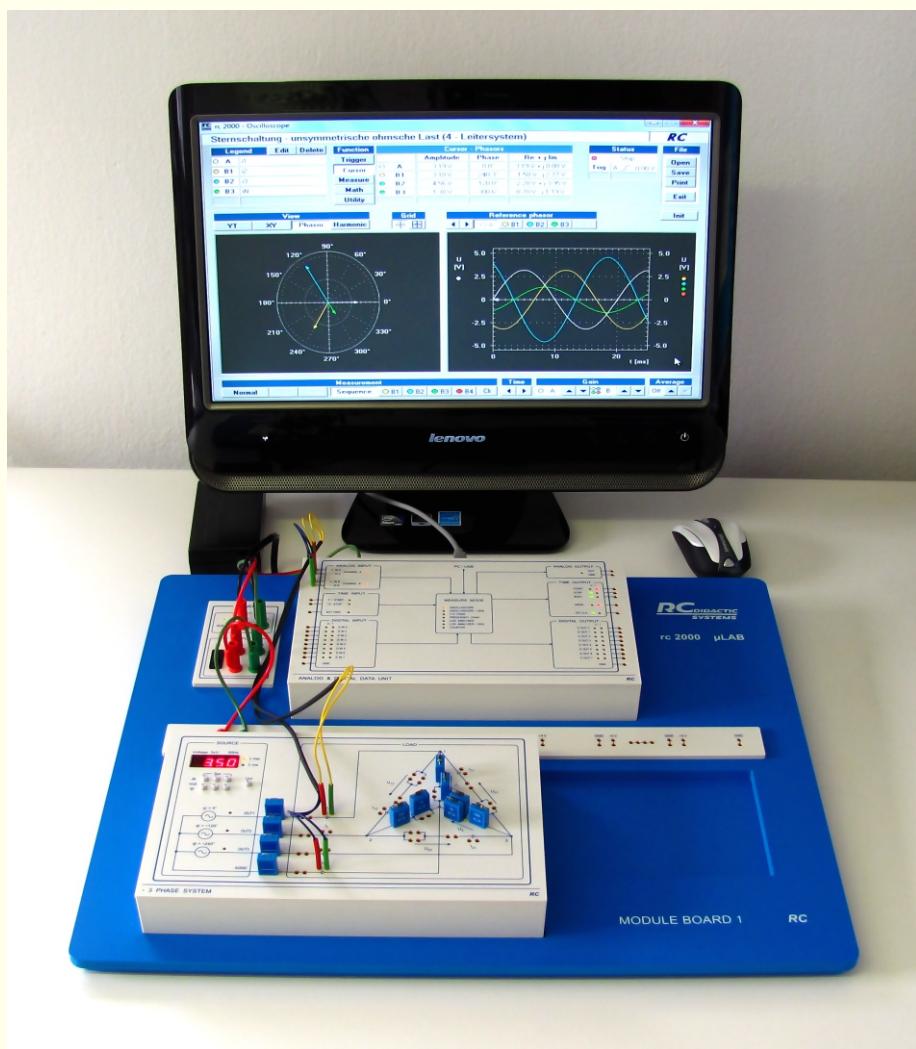
Oscilloscope

Notice

- plug 3-pin element **2N5060** into a **module of thyristor** (Fig. 2)
- after checking that the circuit is correctly connected, we bridge the safety **a** with a coupling
- we change curve **B1** by plugging-out the resistor **R₁**
- curve **B2** is measured on the same spot as **B1**, but with plugged-in resistor **R₂**

Teaching System rc2000 - μ LAB

Three-Phase System



RC společnost s r. o.
přístroje pro vědu a vzdělání
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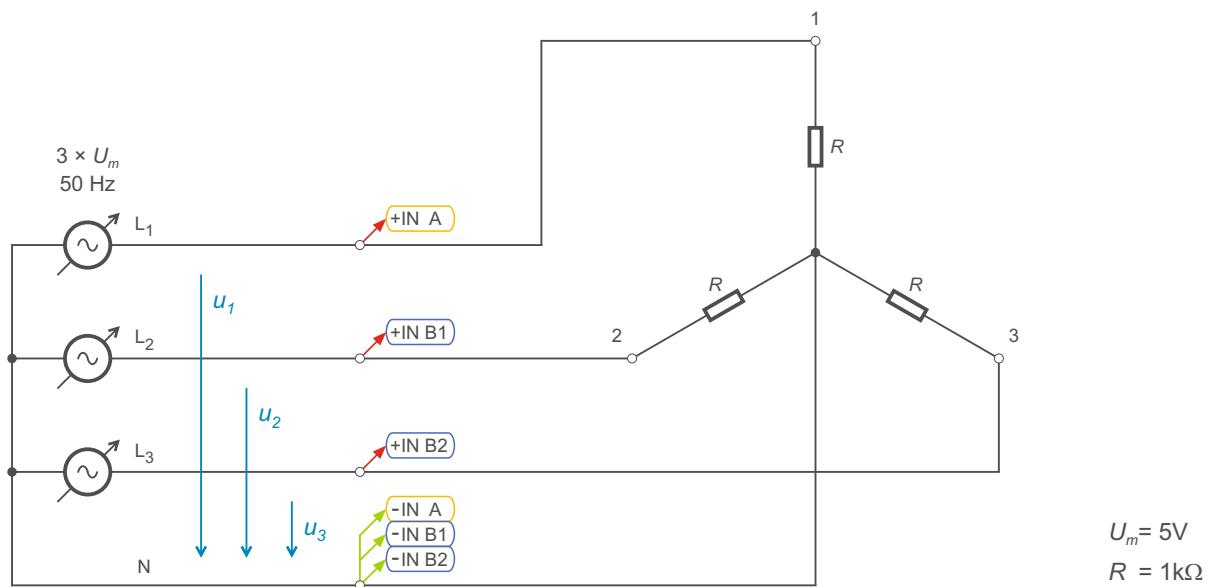
5.1

Star Connection - Phase Voltages

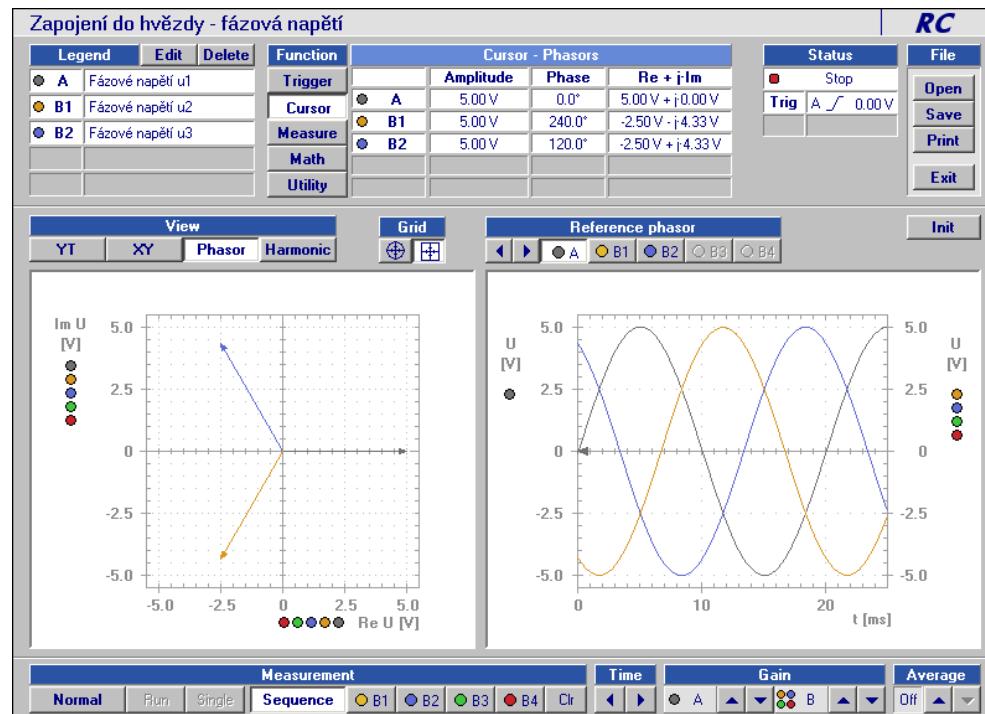
Exercise

Display individual phase voltages u_1, u_2, u_3 in a four-wire system with symmetrical ohmic load.

Schema



Measurement



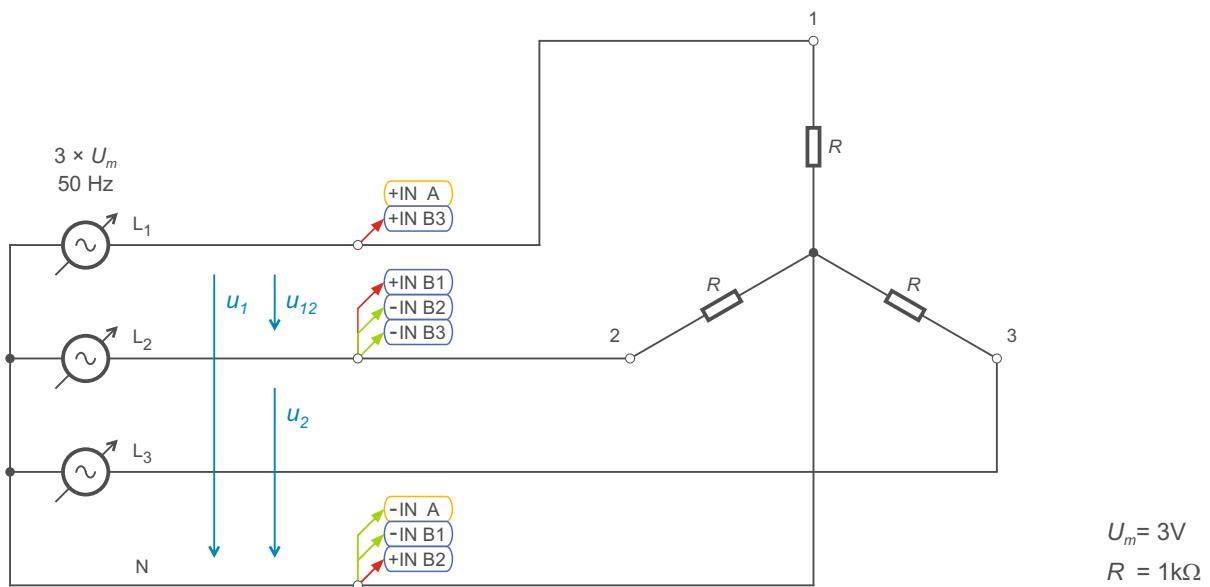
5.2

Star Connection - Phase and Collective Voltages

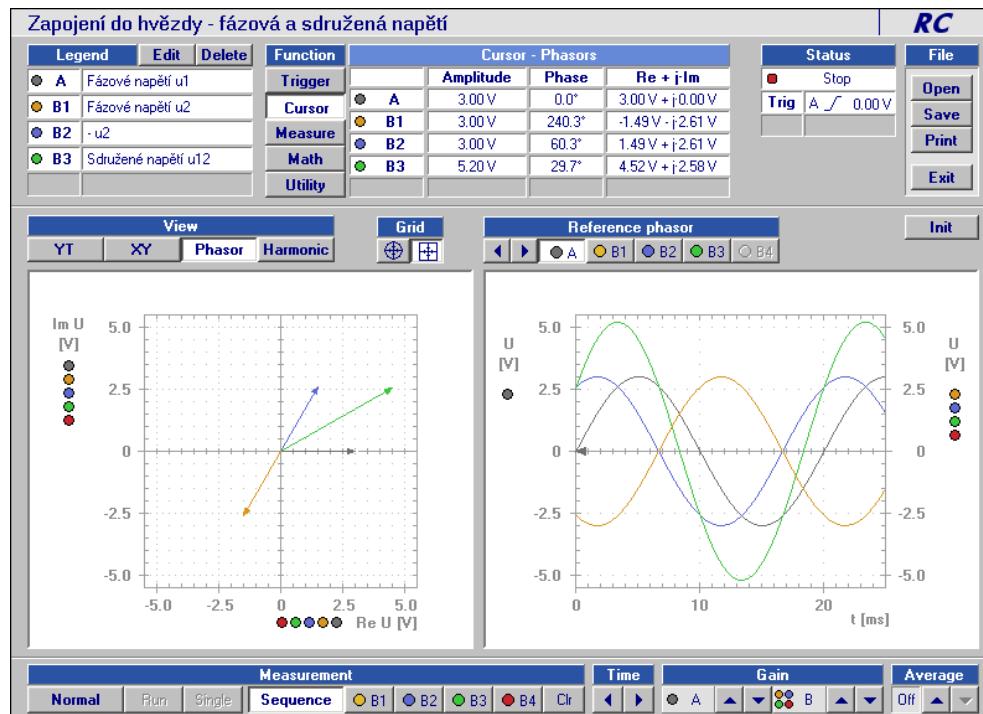
Exercise

Display relation between phase voltages u_1 , u_2 and collective voltage u_{12} in a four-wire system with symmetrical ohmic load.

Schema



Measurement



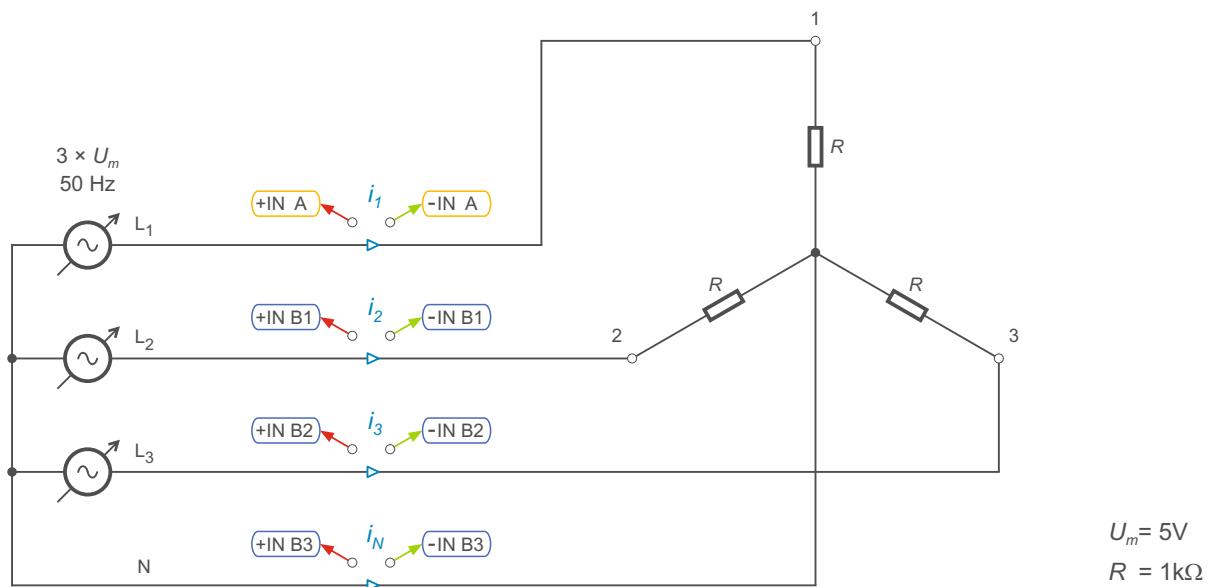
5.3

Star Connection - Symmetrical Ohmic Load

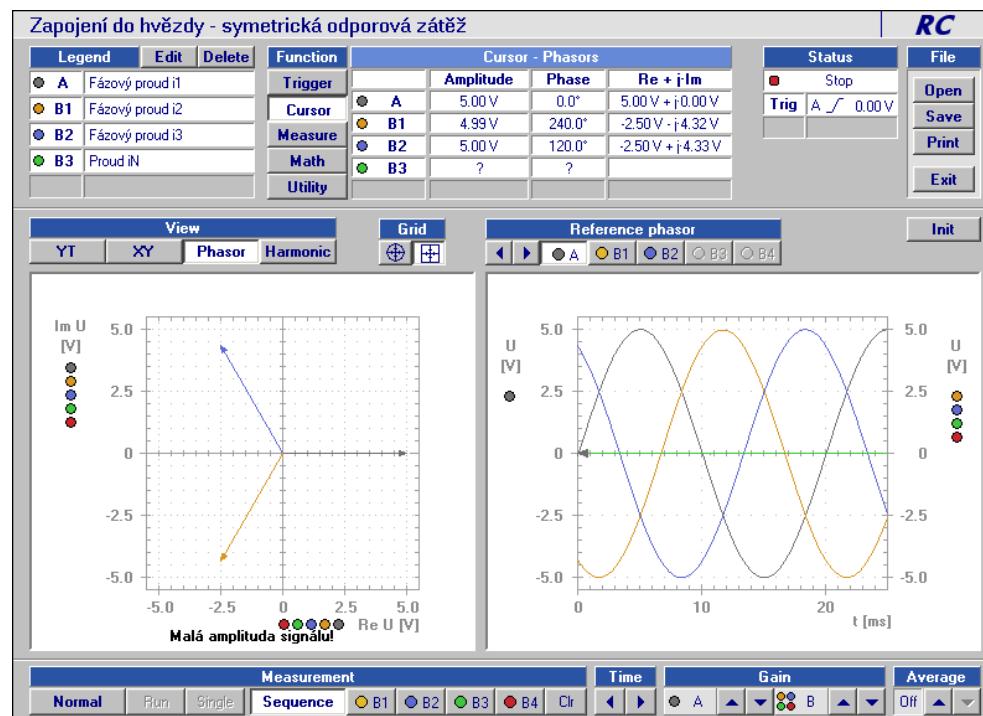
Exercise

Display individual phase currents i_1, i_2, i_3 and current i_N in a four-wire system with symmetrical ohmic load.

Schema



Measurement

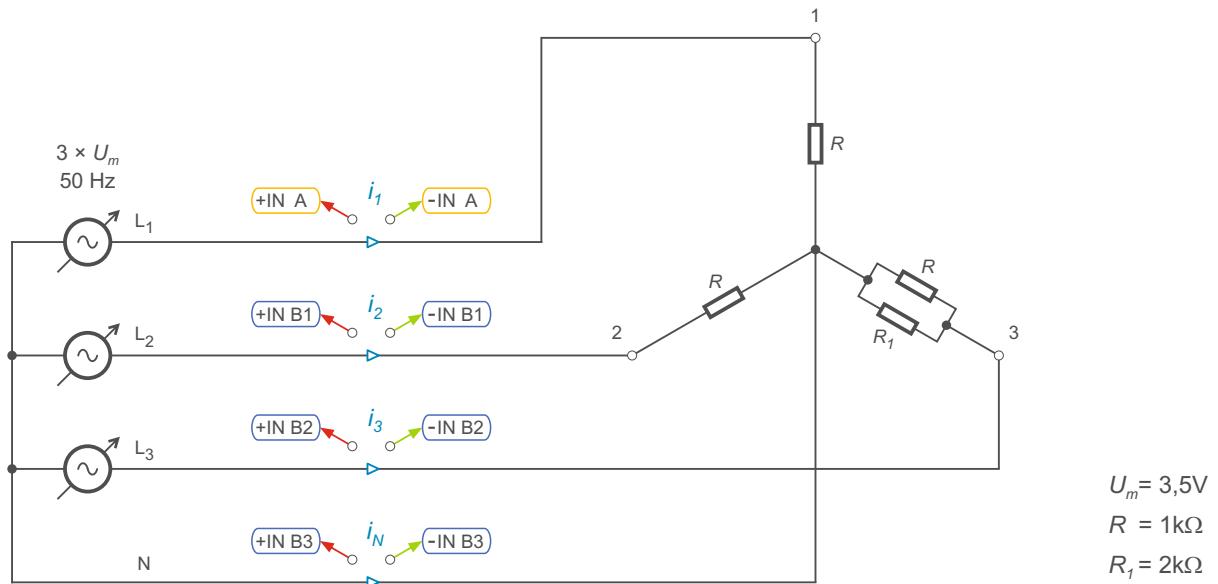


5.4 Star Connection - Asymmetrical Resistance Load (four-wire)

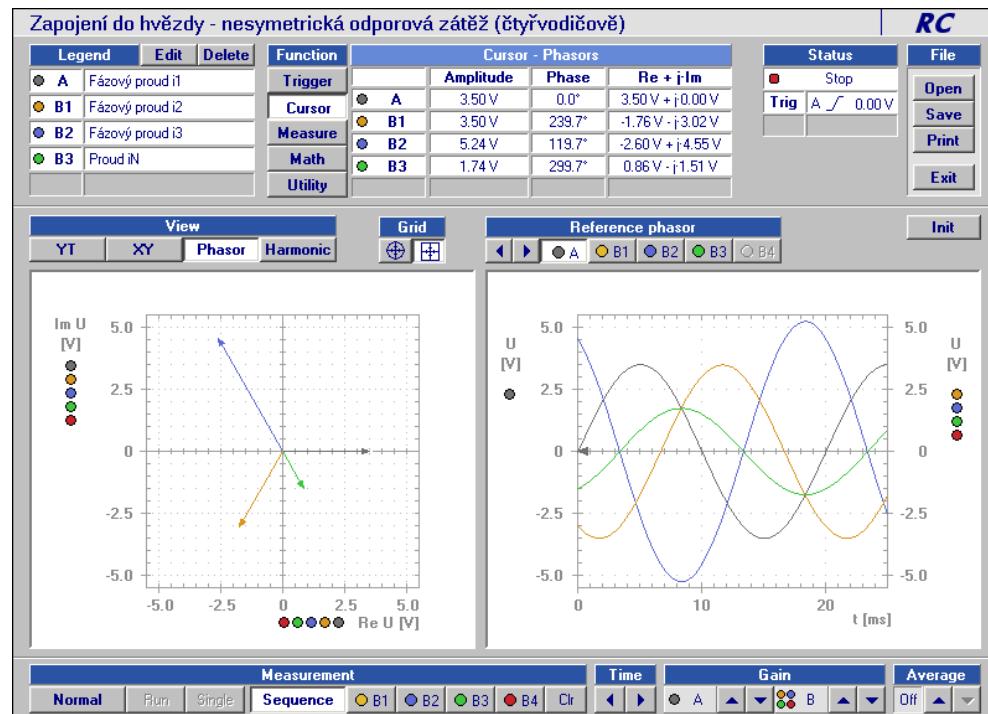
Exercise

Display individual phase currents i_1, i_2, i_3 and neutral current i_N in a four-wire system with asymmetrical ohmic load.

Schema



Measurement

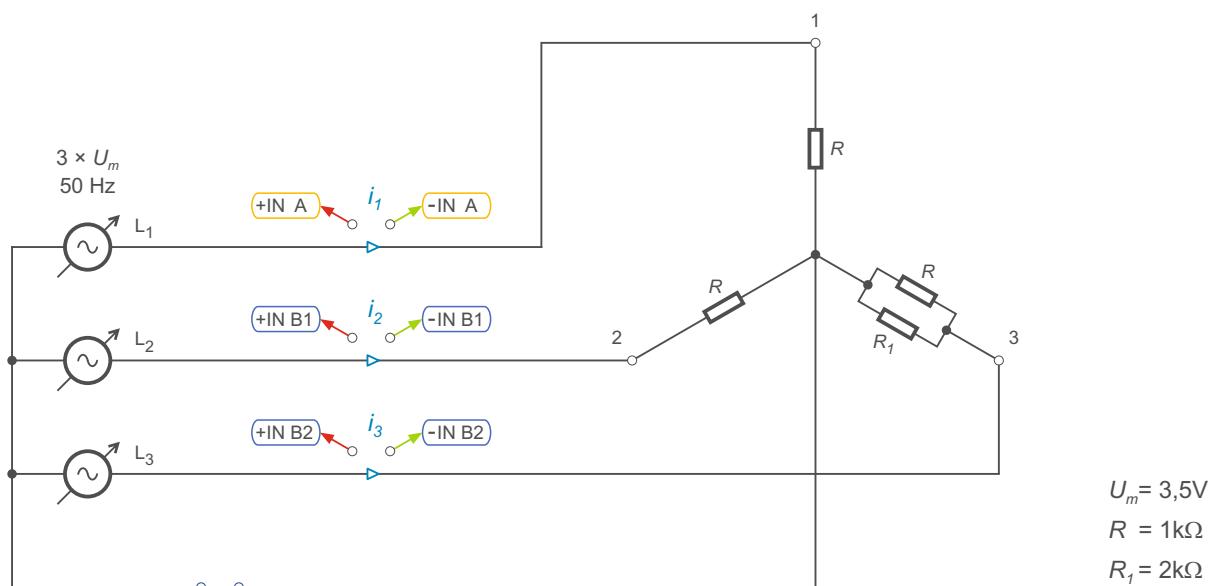


5.5 Star Connection - Asymmetrical Resistance Ohmic Load (three-wire)

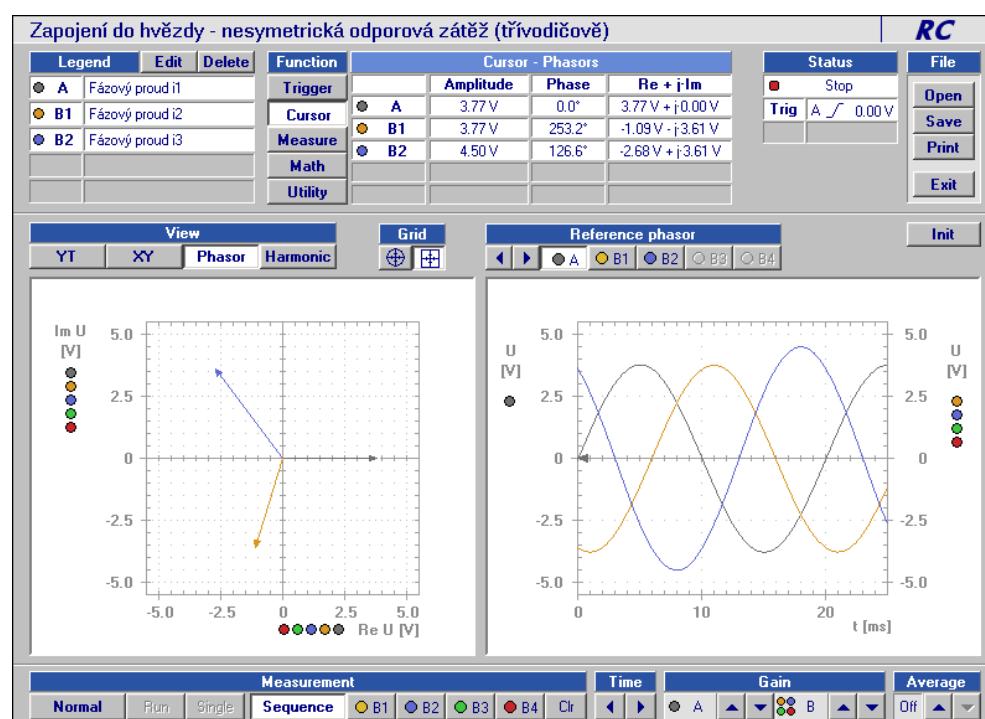
Exercise

Display individual phase currents i_1, i_2, i_3 in a three-wire system with asymmetrical ohmic load.

Schema



Measurement



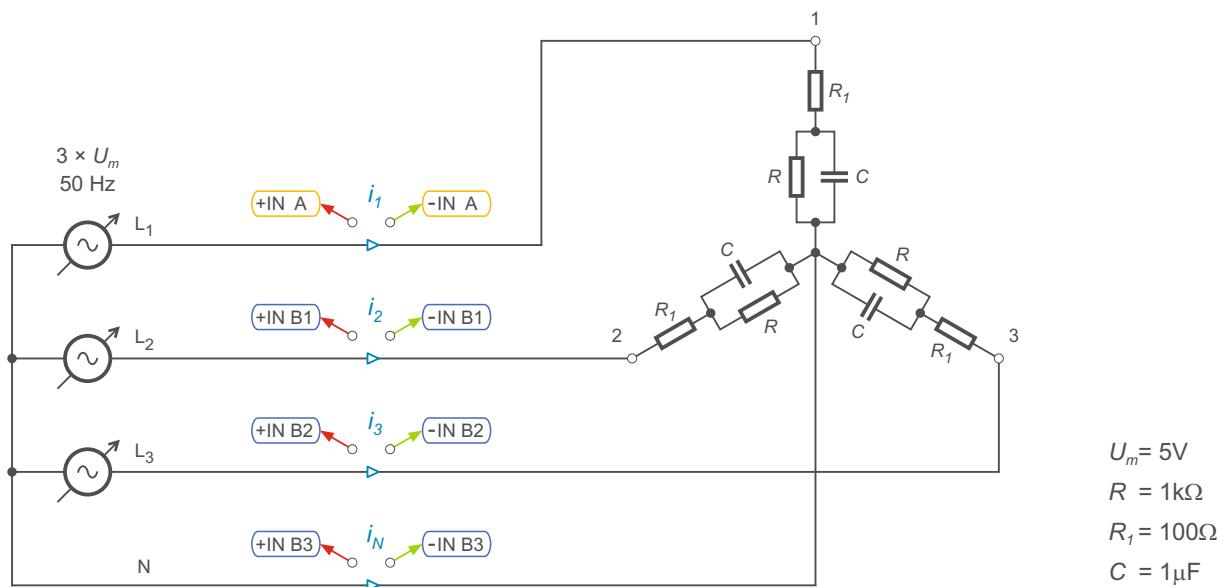
5.6

Star Connection - Symmetrical Impedance Load

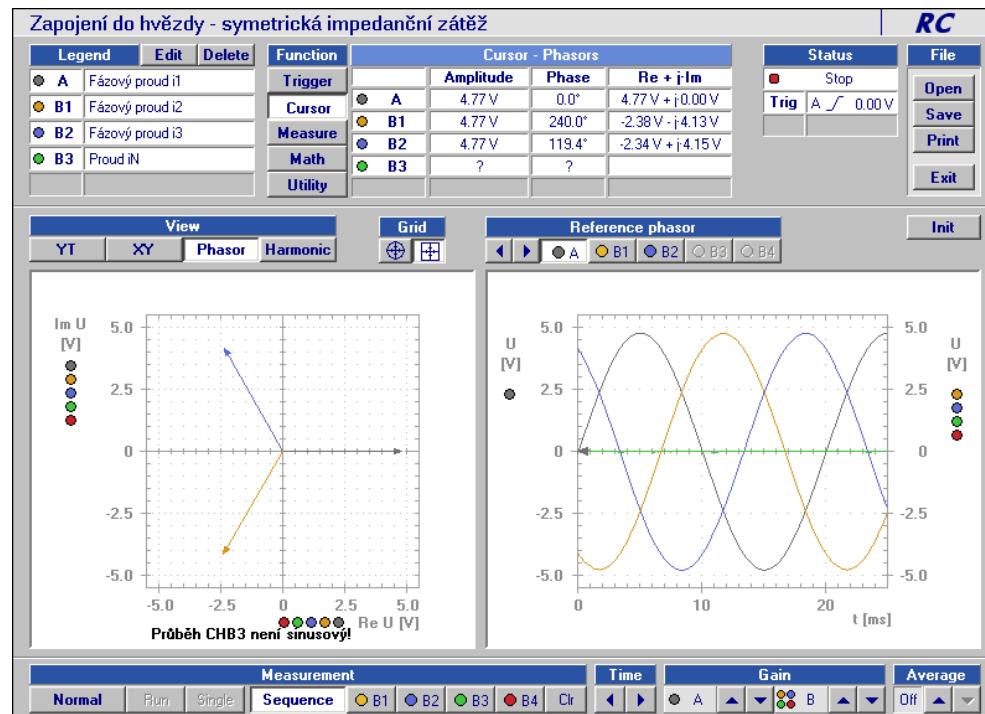
Exercise

Display individual phase currents i_1, i_2, i_3 and neutral current i_N in a four-wire system with symmetrical impedance load.

Schema



Measurement



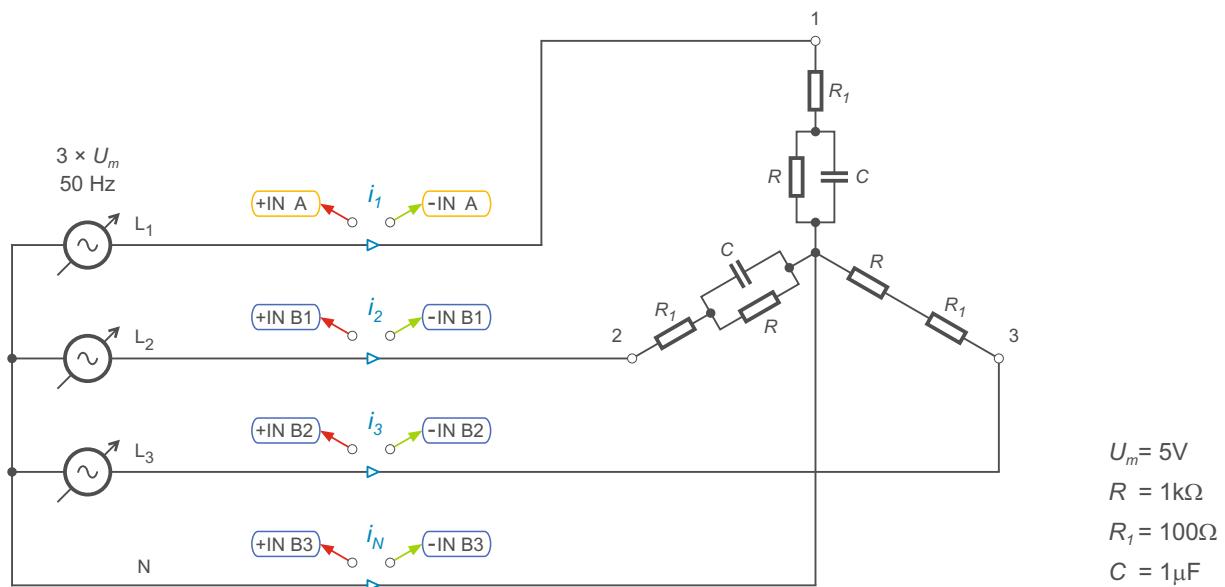
5.7

Star Connection - Asymmetrical Impedance Load

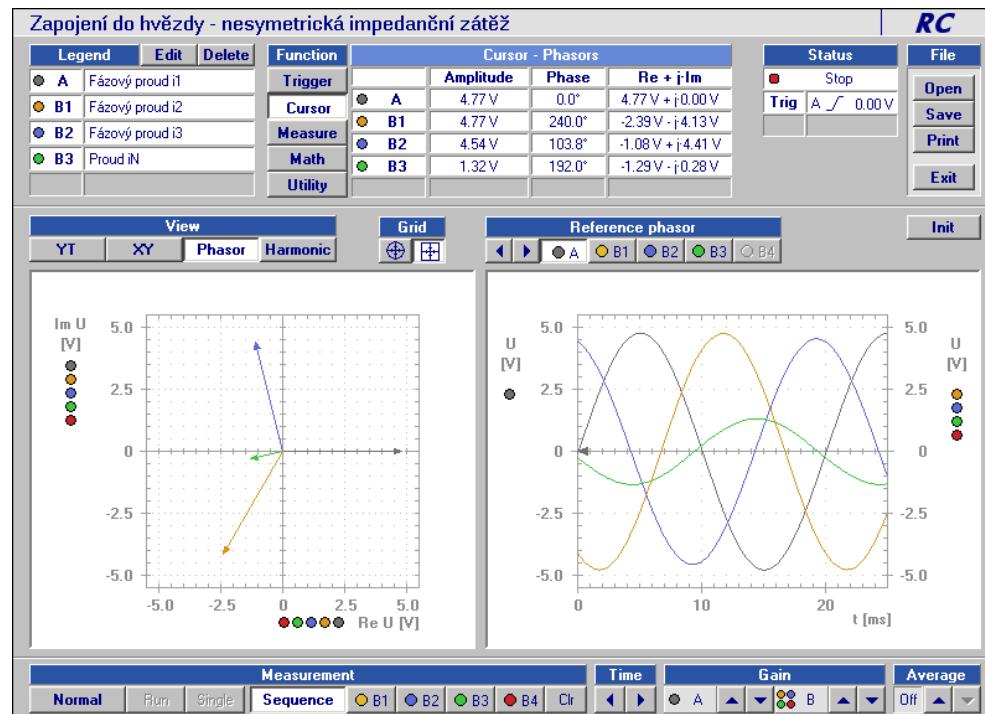
Exercise

Display individual phase currents i_1, i_2, i_3 and neutral current i_N in a four-wire system with asymmetrical impedance load.

Schema



Measurement



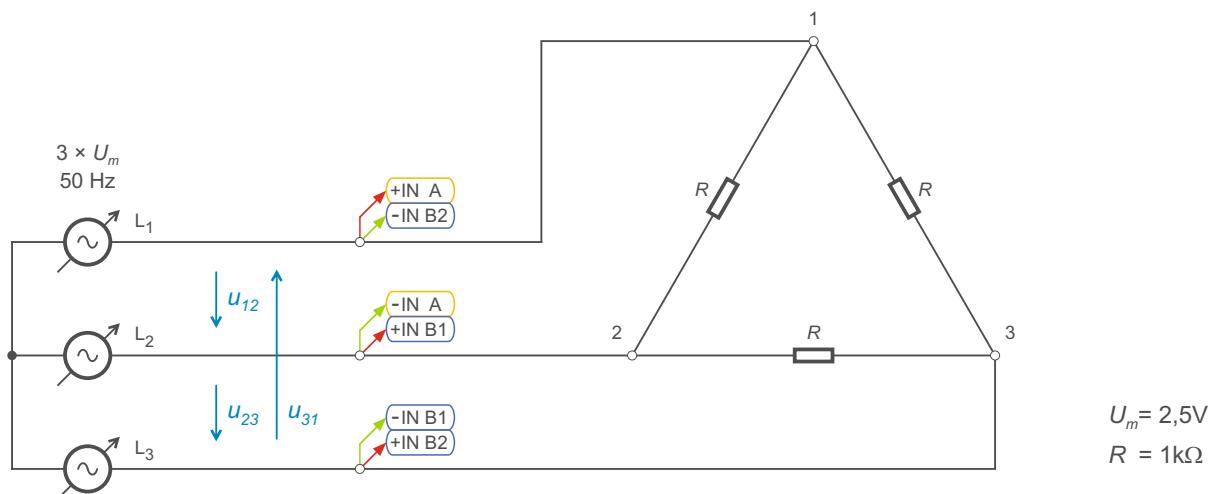
5.8

Delta Connection - Collective Voltages

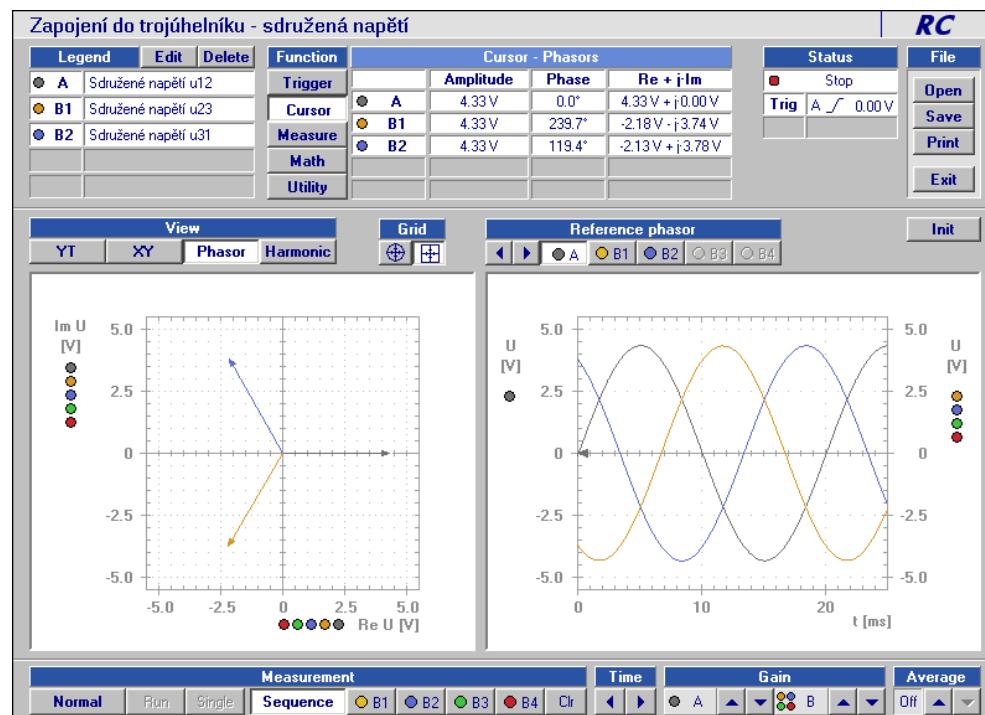
Exercise

Display individual collective voltages u_{12} , u_{23} and u_{31} for symmetrical ohmic load in delta connection.

Schema



Measurement



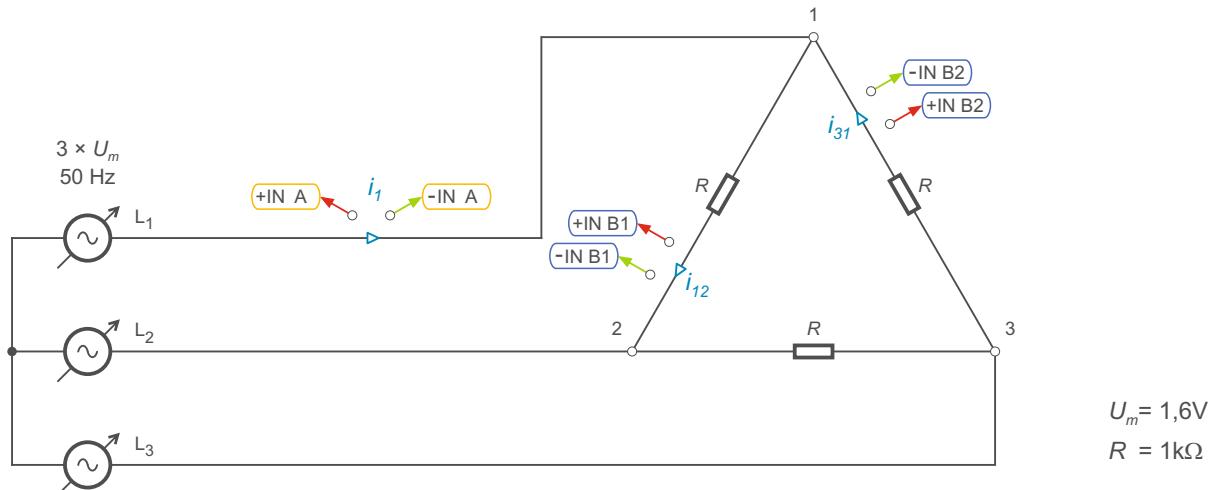
5.9

Delta connection - Phase Collective Current

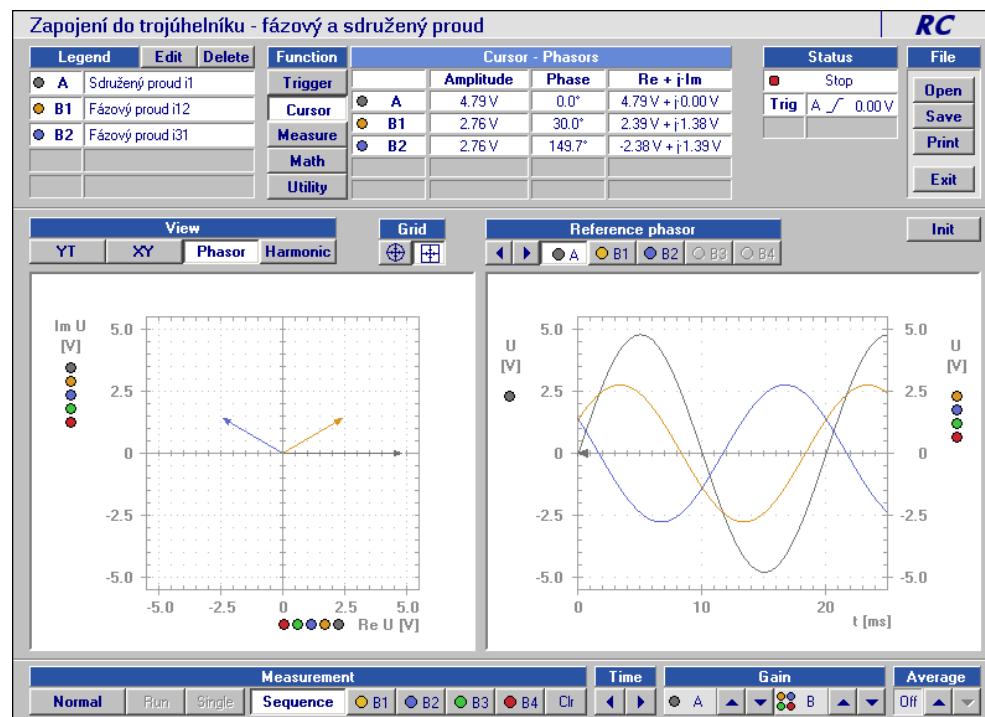
Exercise

Display relation between collective current i_1 and corresponding phase currents i_{12} and i_{31} for symmetrical ohmic load in delta connection.

Schema



Measurement



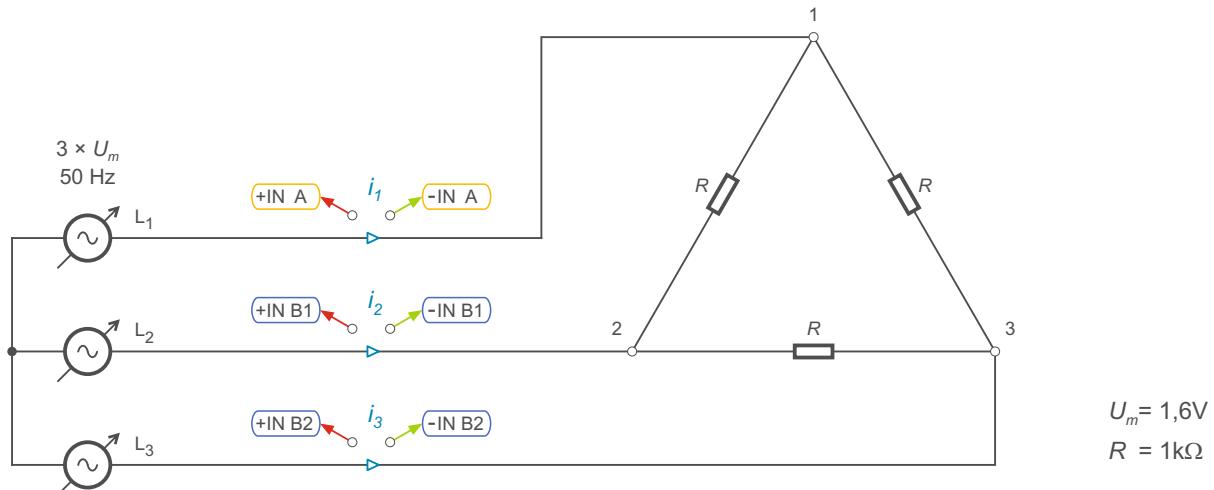
5.10

Delta Connection - Symmetrical Ohmic Load

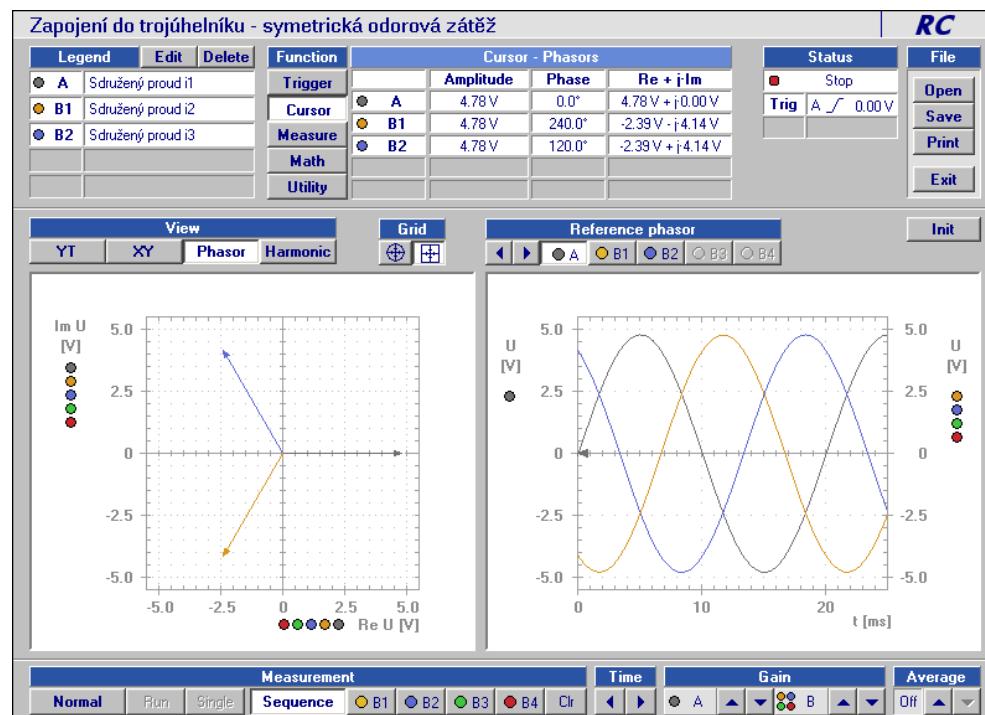
Exercise

Display collective currents i_1 , i_2 and i_3 for symmetrical ohmic load in delta connection.

Schema



Measurement



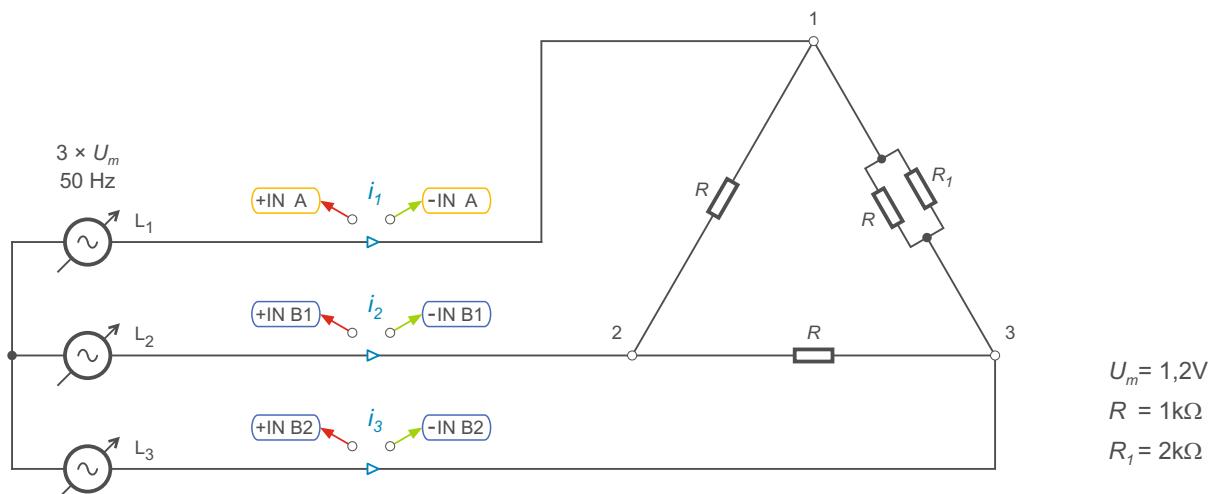
5.11

Delta Connection - Asymmetrical Ohmic Load

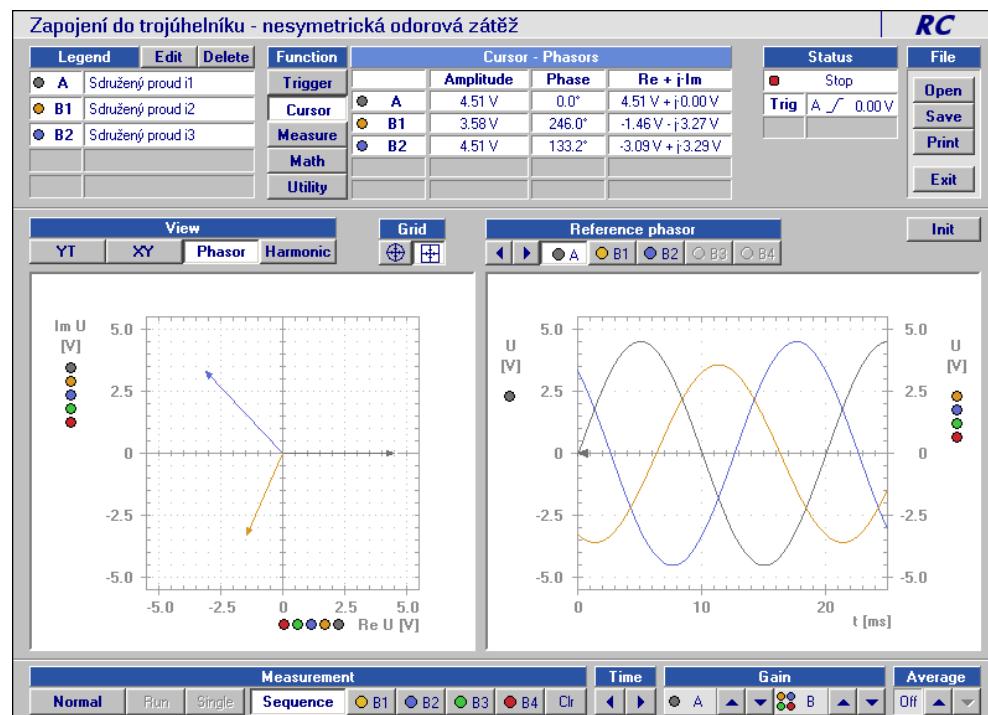
Exercise

Display collective currents i_1 , i_2 and i_3 for asymmetrical ohmic load in delta connection.

Schema



Measurement



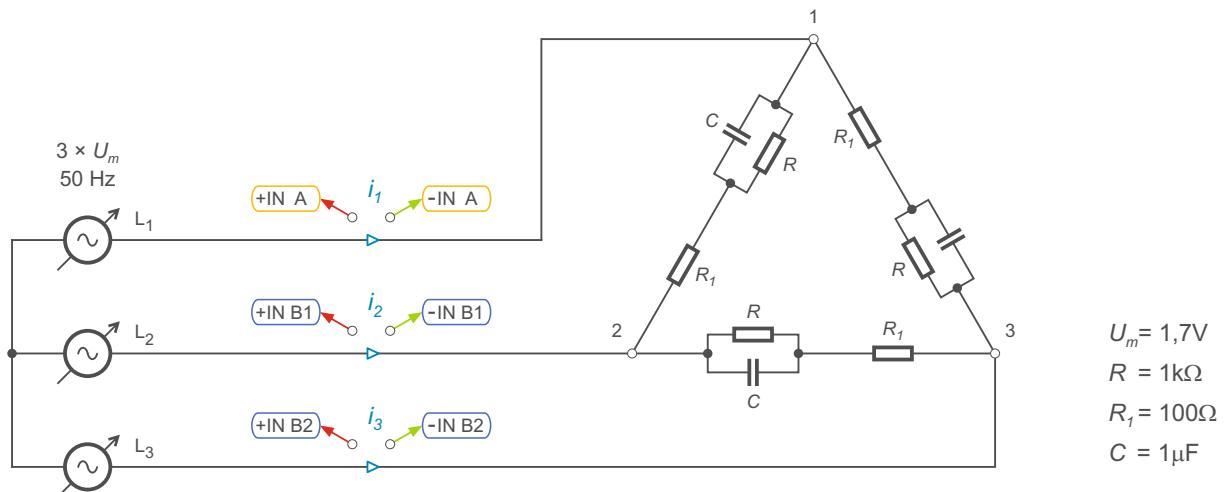
5.12

Delta Connection - Symmetrical Impedance Load

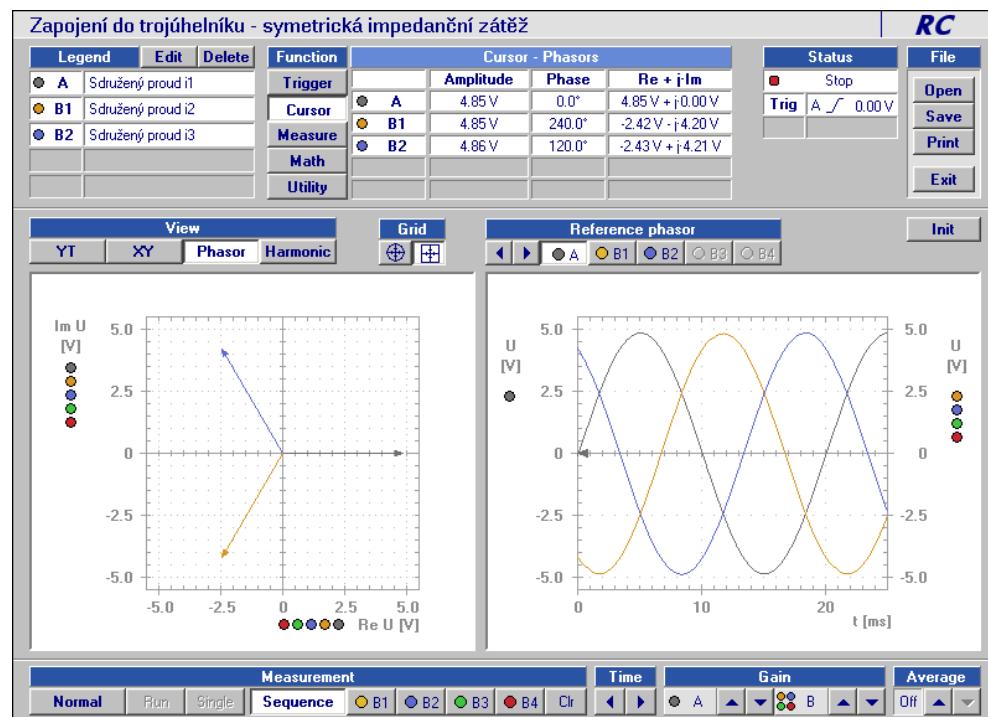
Exercise

Display collective currents i_1 , i_2 and i_3 for symmetrical impedance load in delta connection.

Schema



Measurement

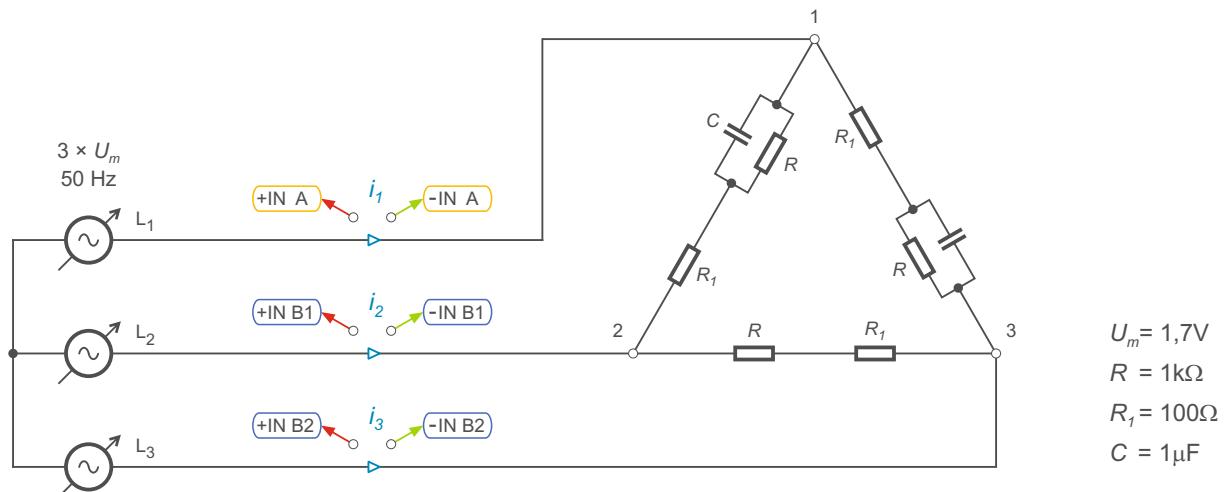


5.13 Delta Connection - Asymmetrical Impedance Load

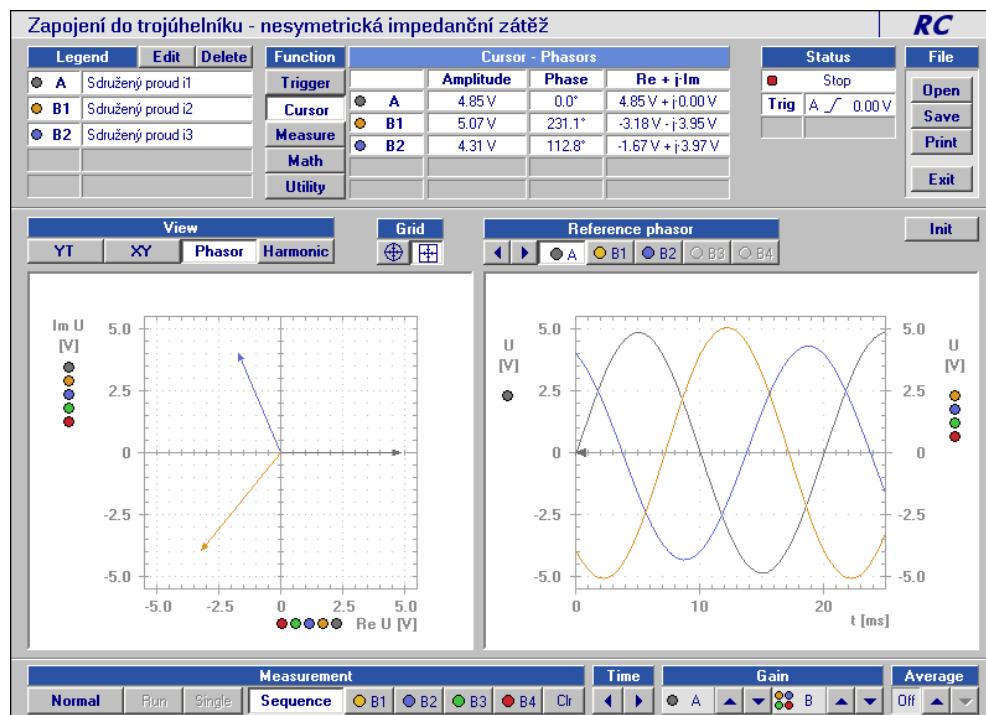
Exercise

Display collective currents i_1 , i_2 and i_3 for asymmetrical impedance load in delta connection.

Schema

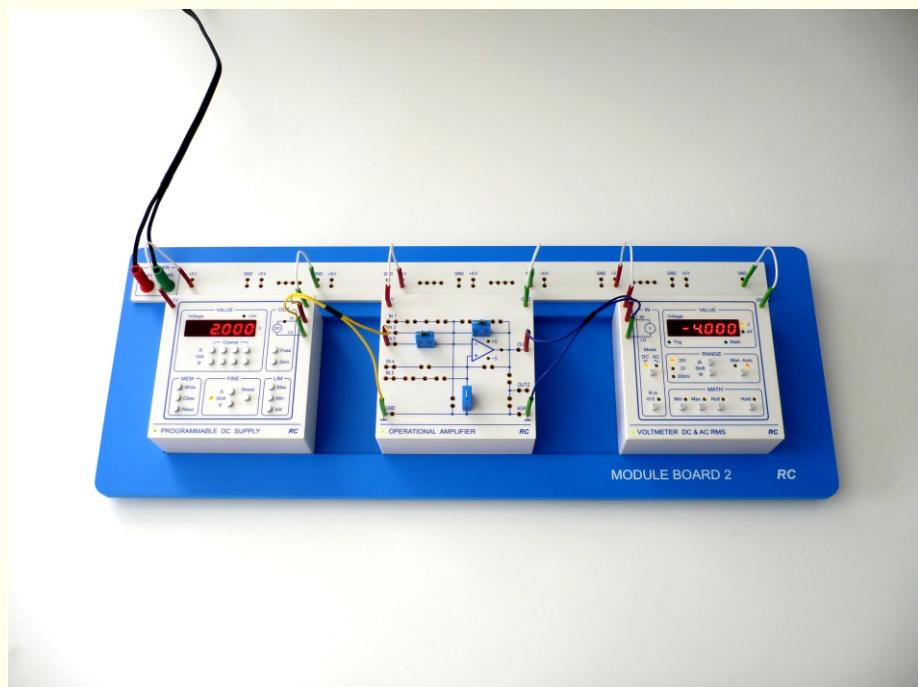


Measurement



Teaching System rc2000 - μ LAB

Operational Amplifier



Content

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Inverting Amplifier	6.1
Non-inverting Amplifier	6.2
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Differentiator	6.5
Comparator	6.6
Comparator with Hysteresis	6.7
Differential Amplifier	6.8
Phase Shifter	6.9
Astable Multivibrator	6.10

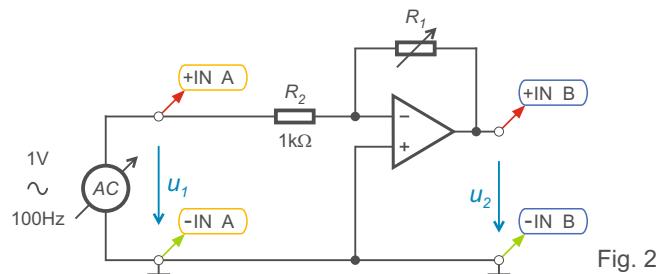
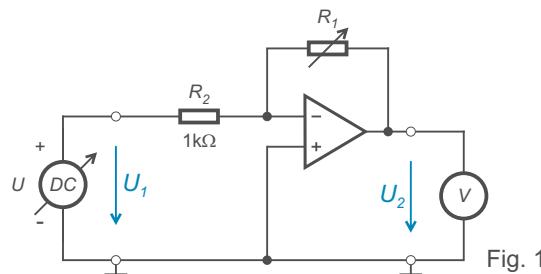
6.1

Inverting Amplifier

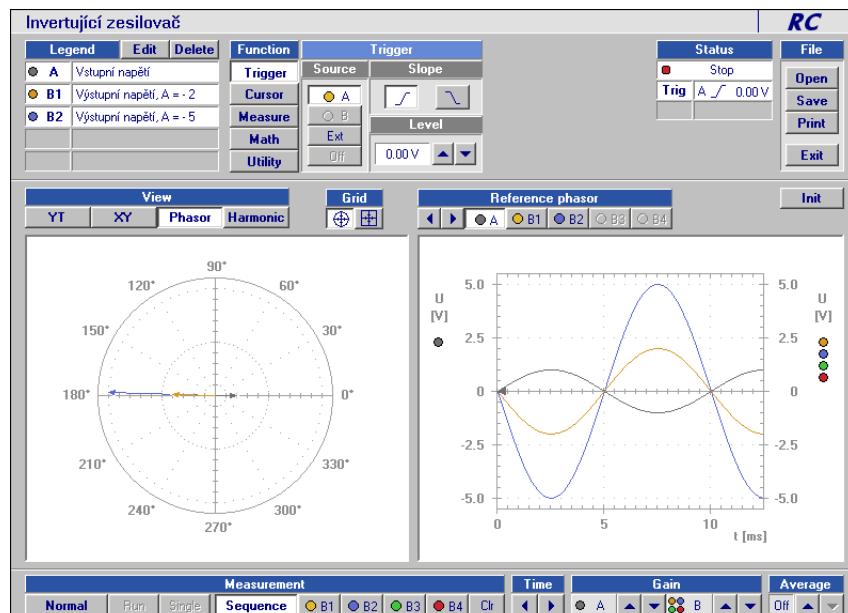
Exercise

Verify the connection of operational amplifier as a inverting amplifier. Make the measurement for direct and alternating voltage. Choose amplification $A = -2$ and $A = -5$.

Schema



Measurement



Inverting amplifier - AC voltage

schema

Fig. 2

mode

Oscilloscope

display

Phasor

formula

$$A = \frac{U_2}{U_1} = -\frac{R_1}{R_2}$$

values

- $A = -2 \dots R_2 = 2k\Omega$
- $A = -5 \dots R_2 = 5k\Omega$

modules

Measuring unit ADDU
Function generator
Voltmeter AC&DC

Inverting amplifier - DC voltage

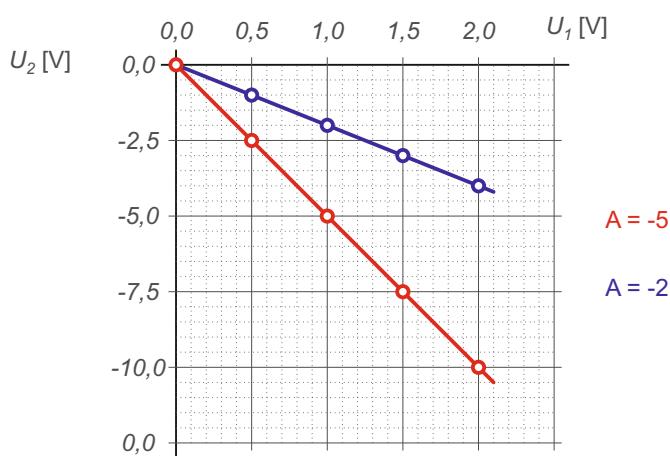
schema

Fig. 1

formula

$$A = \frac{U_2}{U_1} = -\frac{R_1}{R_2}$$

U_1 [V]	0,0	0,5	1,0	1,5	2,0	amplification
U_2 [V]	0,0	-1,0	-2,0	-3,0	-4,0	-2
U_2 [V]	0,0	-2,5	-5,0	-7,5	-10,0	-5



modules

Operational amplifier
Programmable DC supply
Voltmeter AC&DC

6.2

Non-inverting Amplifier

Exercise

Verify connection of operational amplifier as a non-inverting amplifier. Measure direct and alternating voltage. Choose amplification $A = 2$ and $A = 5$.

Schema

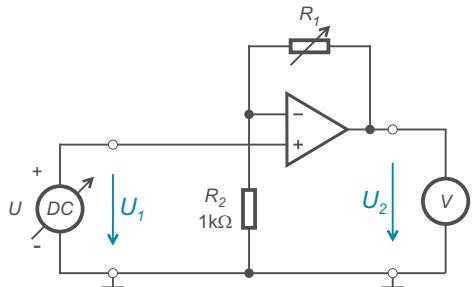
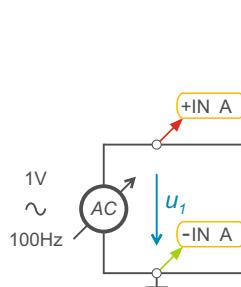


Fig. 1



1V
~
100Hz
 U_1

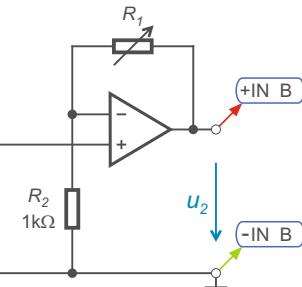
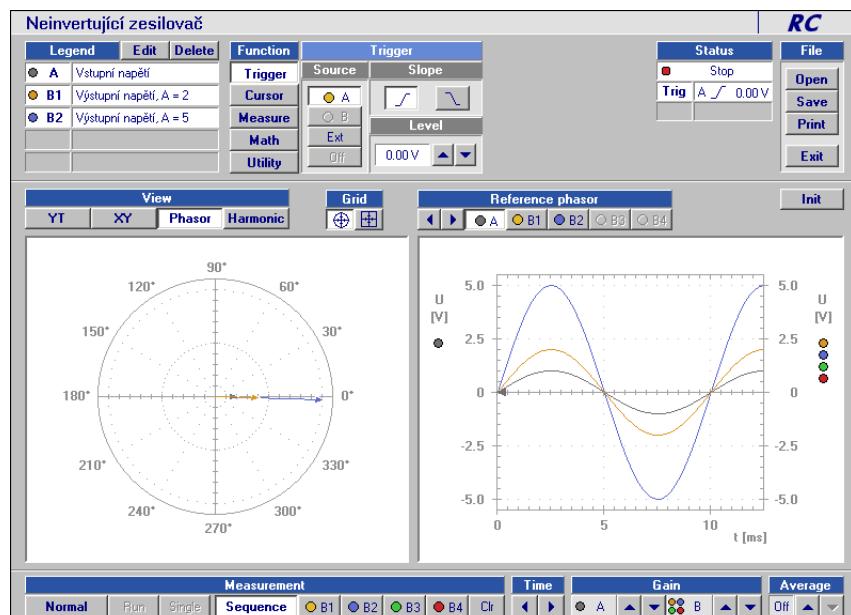


Fig. 2

Measurement



Non-inverting amplifier - AC

schema

Fig. 2

mode

Oscilloscope

display

Phasor

formula

$$A = \frac{U_2}{U_1} = \frac{R_1+R_2}{R_2}$$

values

- $A = 2 \dots R_2 = 1\text{k}\Omega$
- $A = 5 \dots R_2 = 4\text{k}\Omega$

modules

Measuring unit ADDU
Function generator
Voltmeter AC&DC

Non-inverting amplifier - DC

schema

Fig. 1

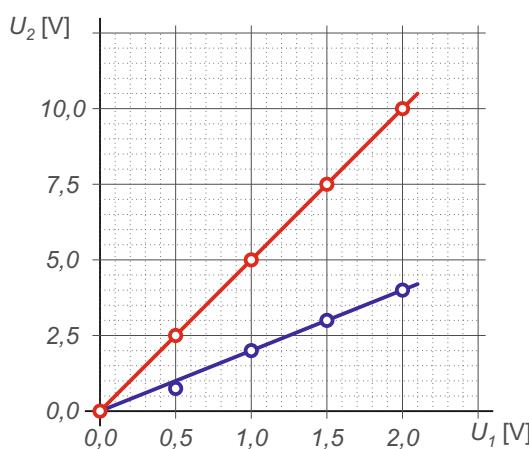
formula

$$A = \frac{U_2}{U_1} = \frac{R_1+R_2}{R_2}$$

modules

Operational amplifier
Programmable DC supply
Voltmeter AC&DC

U_1 [V]	0,0	0,5	1,0	1,5	2,0	amplification
U_2 [V]	0,0	1,0	2,0	3,0	4,0	2
U_2 [V]	0,0	2,5	5,0	7,5	10,0	5



6.3

Voltage Follower

Exercise

Verify the connection of operational amplifier as a voltage follower. Measure both direct and alternating voltage.

Schema

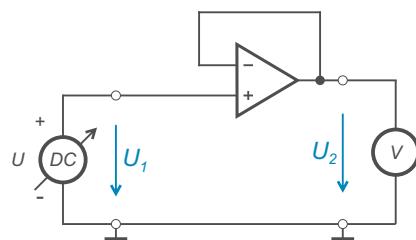


Fig. 1

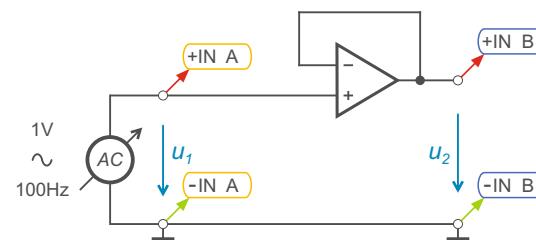
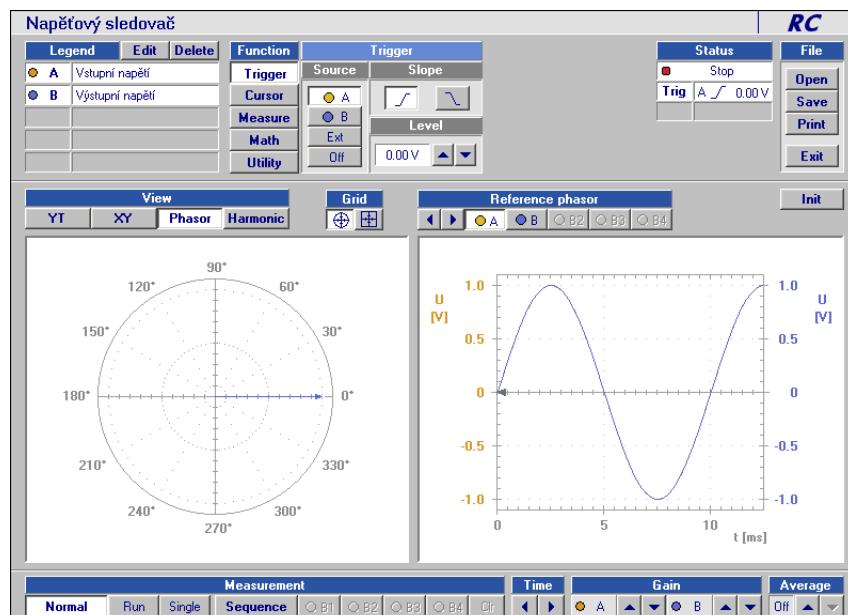


Fig. 2

Measurement



Voltage follower

schema
mode
display

Fig. 2
Oscilloscope
Phasor

formula $A = \frac{U_2}{U_1} = 1$

modules

Operational amplifier
Function generator
Measuring unit ADDU

U_1 [V]	0,0	2,5	5,0	7,5	10,0	amplification
U_2 [V]	0,0	2,5	5,0	7,5	10,0	1

Voltage follower

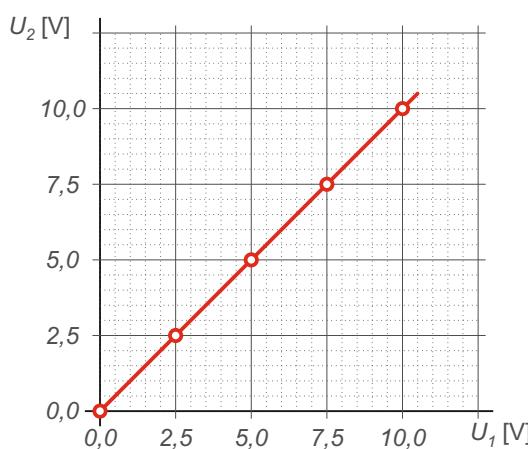
schema

Fig. 1

formula $A = \frac{U_2}{U_1} = 1$

modules

Operational amplifier
Programmable DC sourcej
Voltmeter AC&DC



6.4

Integrator

Exercise

Verify the connection of operational amplifier as an integrator. Choose different values of damping by resistor R_1 . Make the measurement in frequency domain.

Schema

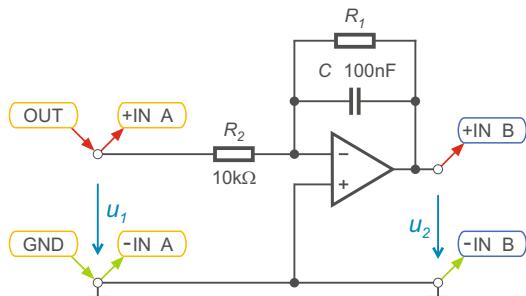


Fig. 1

Measurement



Amplitude characteristic

schema
mode
display

Fig. 1
Frequency char.
Amplitude

modules

Operational amplifier
Measuring unit ADDU



Phase characteristic

schema
mode
display

Fig. 2
Frequency char.
Phase

modules

Operational amplifier
Measuring unit ADDU

Exercise

Verify the connection of operational amplifier as a derivator. Make the measurement in frequency domain.

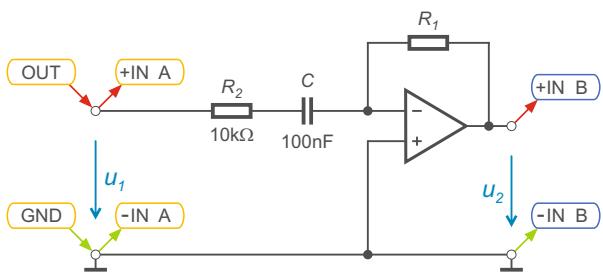
Schema

Fig. 1

Measurement

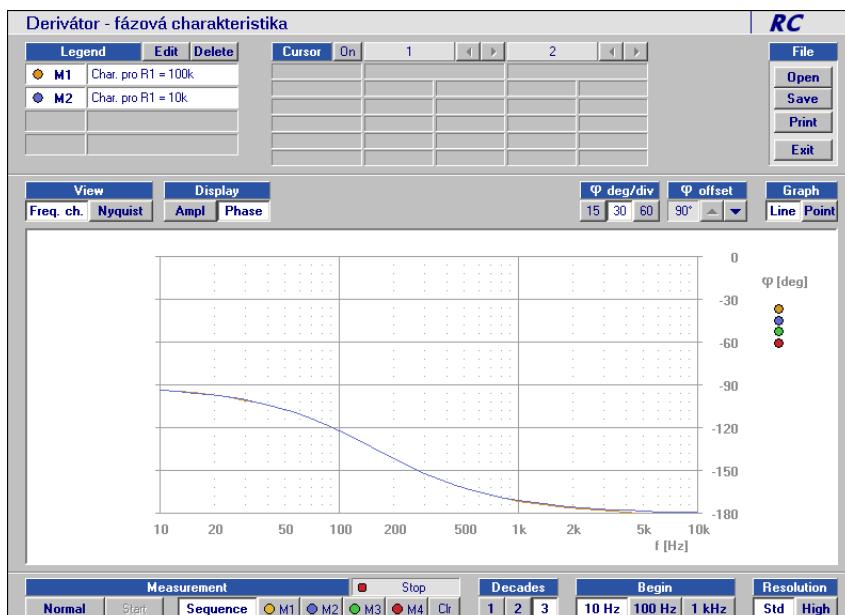
Amplitude characteristic

schema
mode
display

Fig. 1
Frequency char.
Amplitude

modules

Operational amplifier
Measuring unit ADDU



Phase characteristic

schema
mode
display

Fig. 2
Frequency char.
Phase

modules

Operational amplifier
Measuring unit ADDU

6.6

Comparator

Exercise

Display course of input and output voltage of comparator. Make the measurement for zero level of comparation (Fig. 1) and for non-zero reference level of comparation (Fig. 2).

Schema

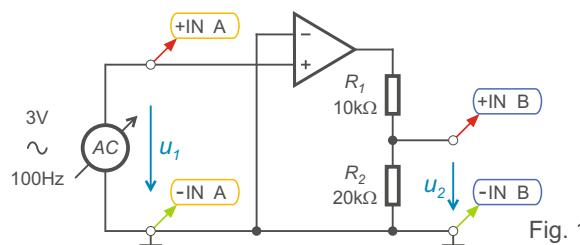


Fig. 1

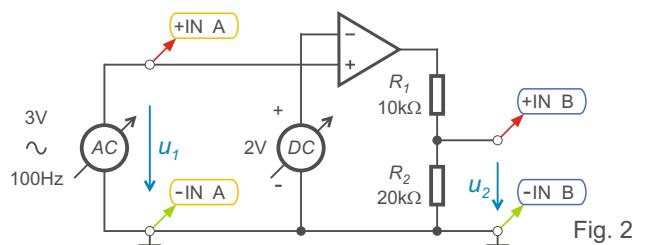
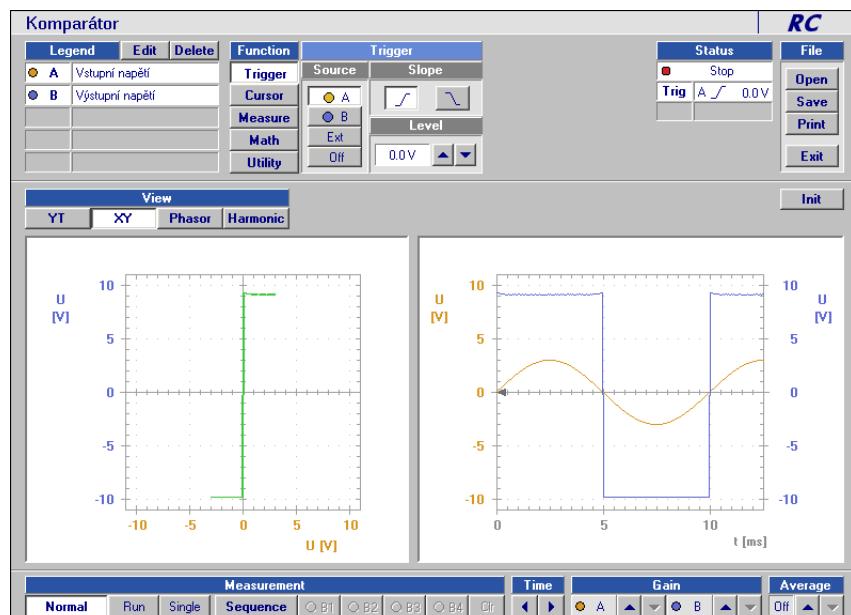


Fig. 2

Measurement



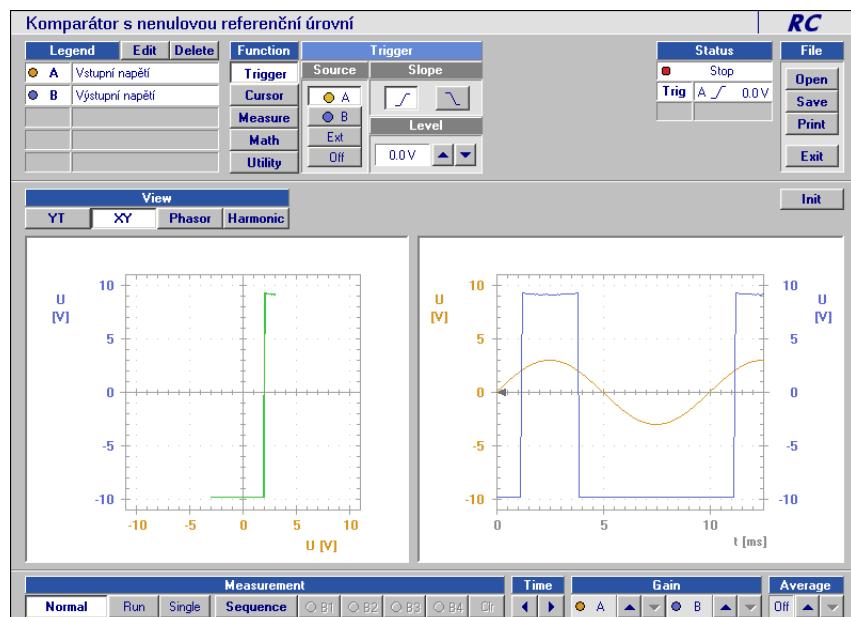
Comparator

schema
mode
display

Fig. 1
Oscilloscope
XY

modules

Operational amplifier
Measuring unit ADDU
Function generator



Comparator with non-zero level

mode
schema
display

Fig. 2
Oscilloscope
XY

modules

Operational amplifier
Measuring unit ADDU
Function generator
Programmable DC supply

Notice Thanks to output divider consisting of R_1 and R_2 we display saturation voltage bigger than 10V.

6.7

Comparator with Hysteresis

Exercise

Display course of input and output voltage of comparator with hysteresis. Make the measurement for zero level of comparation (Fig. 1) and for non-zero reference level of comparation (Fig. 2).

Schema

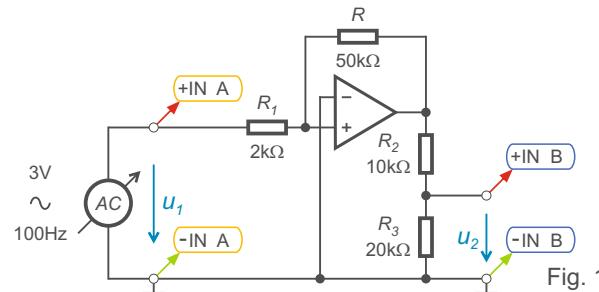


Fig. 1

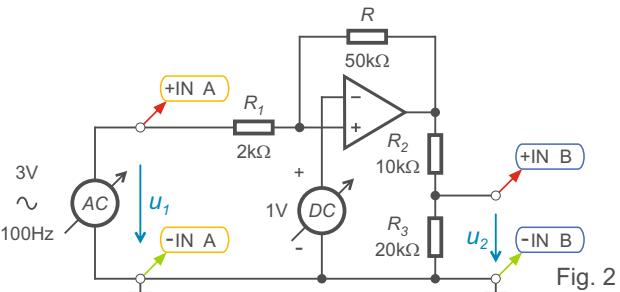
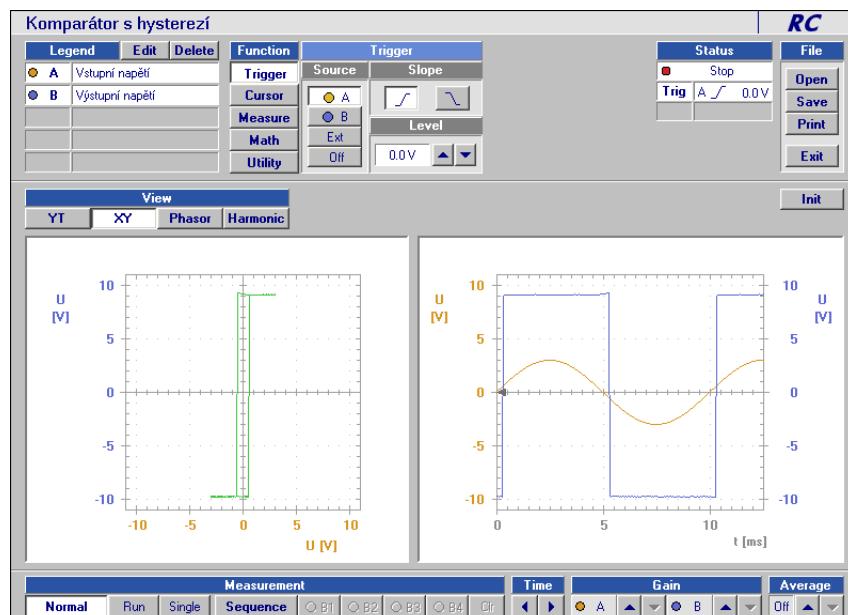


Fig. 2

Measurement



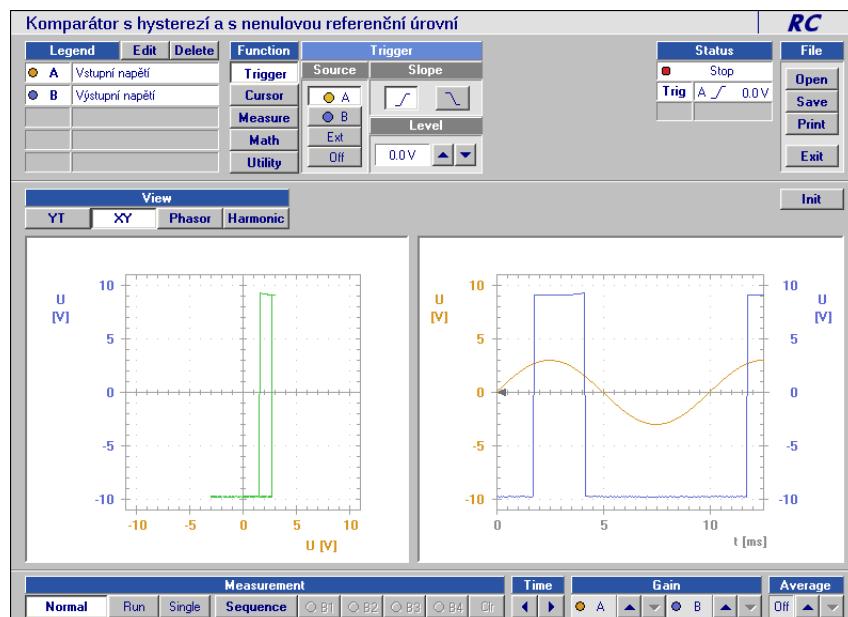
Comparitor with hysteresis 1

schema
mode
display

Fig. 1
Oscilloscope
XY

modules

Operational amplifier
Measuring unit ADDU
Function generator



Comparitor with hysteresis 2

mode
schema
display

Fig. 2
Oscilloscope
XY

modules

Operational amplifier
Measuring unit ADDU
Function generator
Programmable DC supply

Notice Thanks to output divider consisting of R_1 and R_2 we display saturation voltage bigger than 10V.

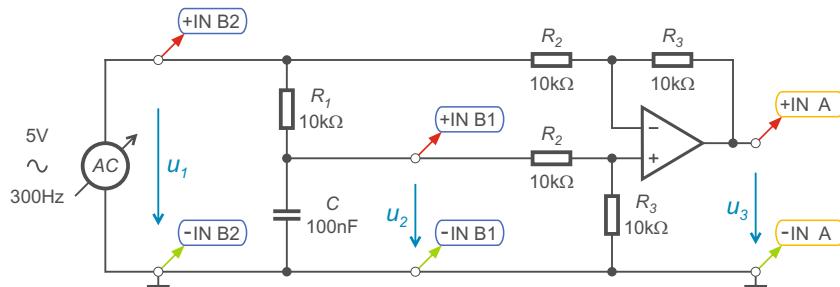
6.8

Differential Amplifier

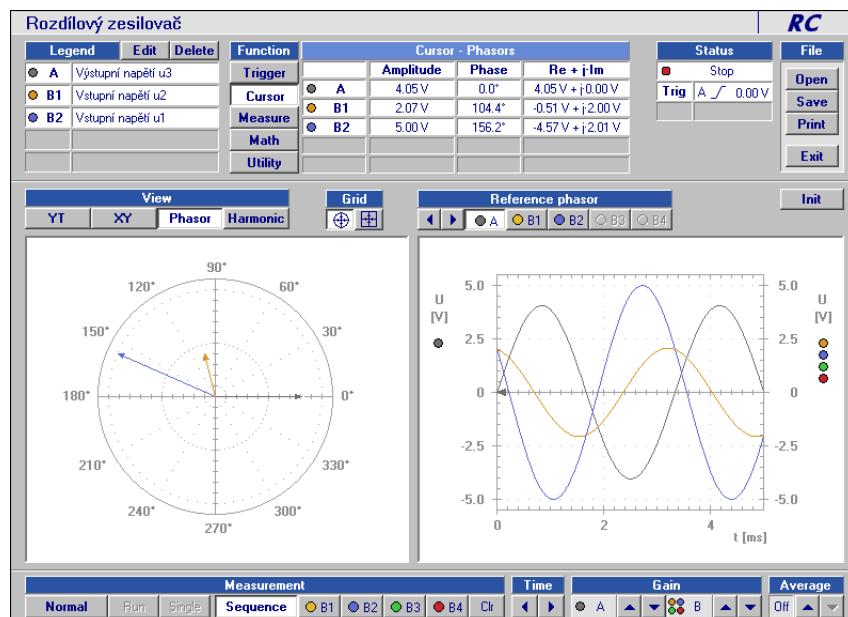
Exercise

Display courses of input voltages of differential amplifier u_1, u_2 and its output voltage u_3 . With the help of cursors prove the validity of formula $u_3 = u_2 - u_1$.

Schema



Measurement



Differential amplifier

schema
mode
display

Fig. 1
Oscilloscope
Phasor

modules

Operational amplifier
Measuring unit ADDU
Function generator

Exercise

Display the amplitude and phase frequency characteristics for two variations of connecting the Phasenglied.

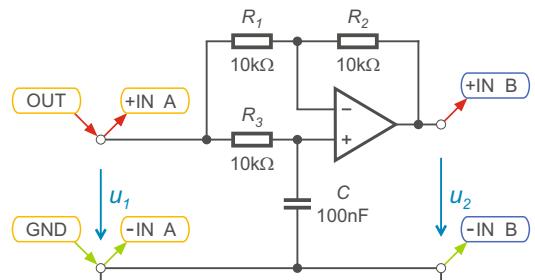
Schema

Fig. 1

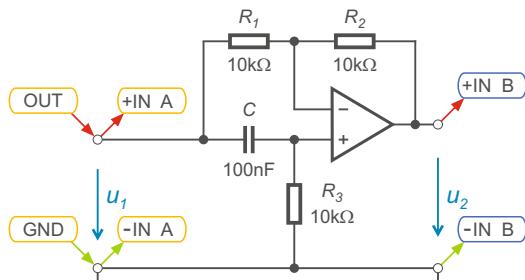
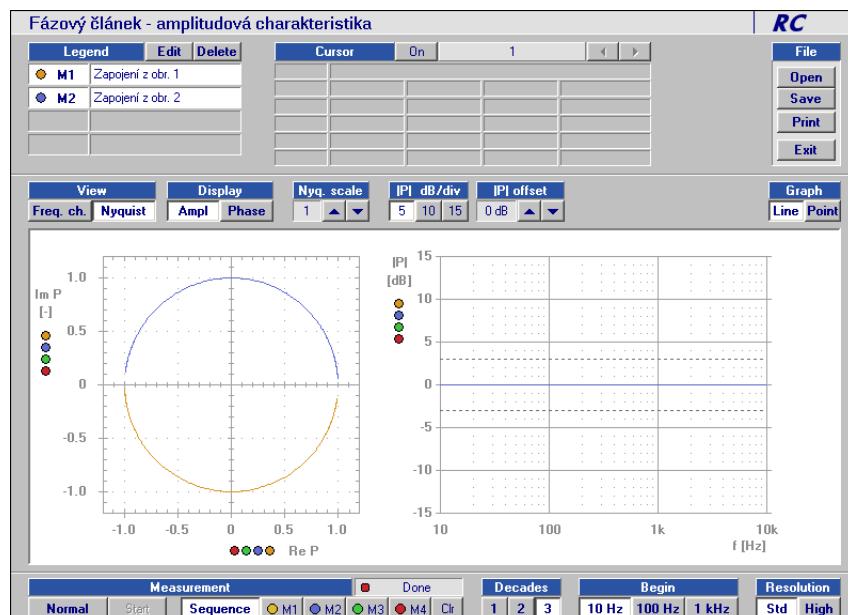


Fig. 2

Measurement

schema

Fig. 1

mode

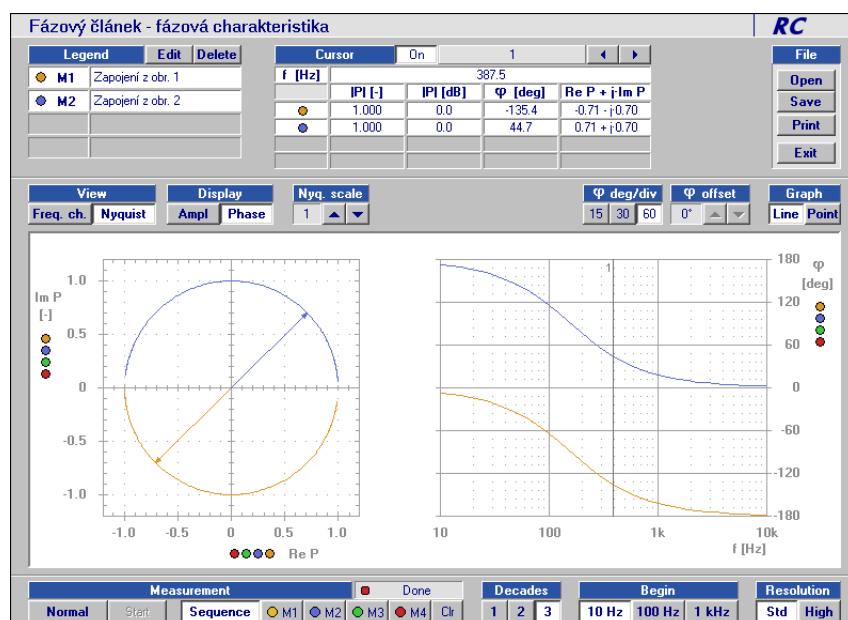
Frequency char.

display

Amplitude

modules

Operational amplifier
Measuring unit ADDU



schema

Fig. 2

mode

Frequency char.

display

Phase

modules

Operational amplifier
Measuring unit ADDU

6.10

Astable Multivibrator

Exercise

Display the voltage on capacitor C and on the output of the circuit. Output period is given by the formula 1). To simplify the calculation of generated frequency 2) choose $R_2 = 0,86 R_1$.

Schema

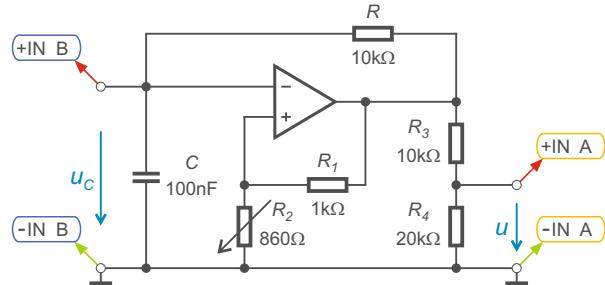


Fig. 1

$$T = 2.R.C \cdot \ln\left(1 + \frac{2.R_2}{R_1}\right) \quad 1)$$

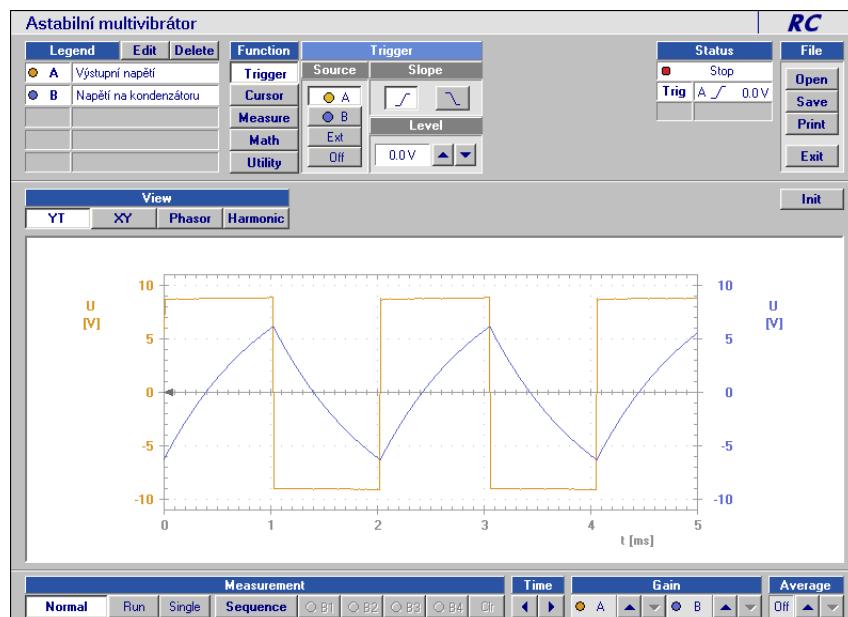
$$\ln\left(1 + \frac{2.R_2}{R_1}\right) = 1.0006 \doteq 1$$

$$R_1 = 1000\Omega \quad R_2 = 860\Omega$$

$$f \doteq \frac{1}{2.R.C} \quad 2)$$

$$f \doteq \frac{1}{2 \cdot 10^4 \cdot 10^{-7}} = 500 \text{ Hz}$$

Measurement



Astable

schema

Fig. 1

mode

Oscilloscope

display

YT

modules

Operational amplifier

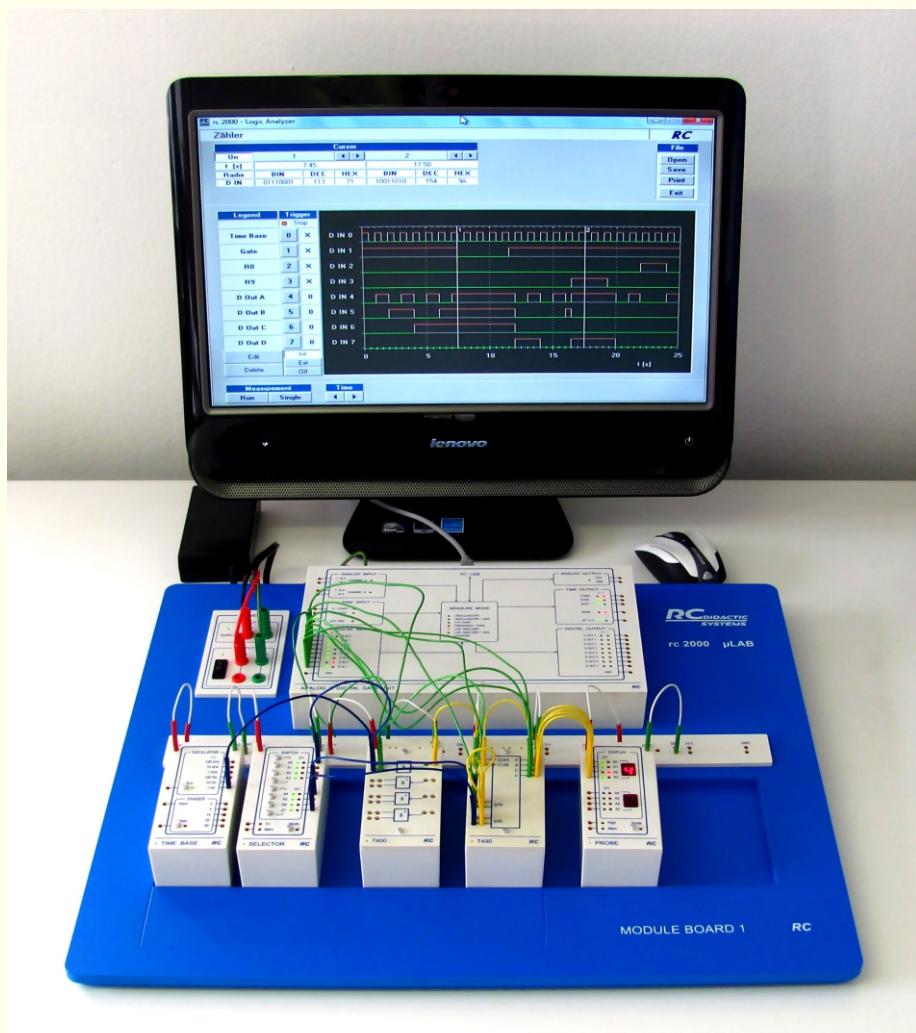
Measuring unit ADDU

Resistor decade R1

Notice Thanks to output divider consisting of R_1 and R_2 we display saturation voltage bigger than 10V.

Teaching System rc2000 - µLAB

Digital Techniques



RC společnost s r. o.
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Mobile: 00420-603 158 544
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Web: www.rctdidactic.cz

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Boolean Algebra - Function Transformation (NAND)	7.2
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Fan Control	7.7
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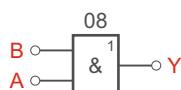
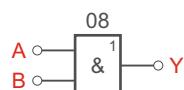
7.1

Boolean Algebra - Laws

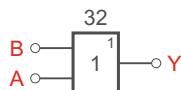
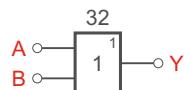
Exercise

Verify the validity of the laws of Boolean algebra.

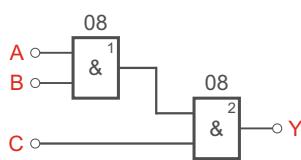
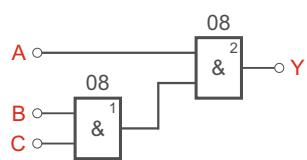
Schema



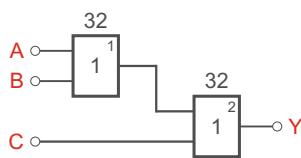
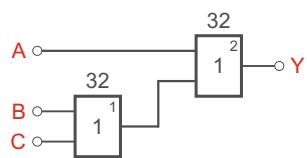
$$Y = A \cdot B \\ = B \cdot A$$



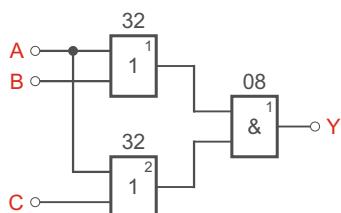
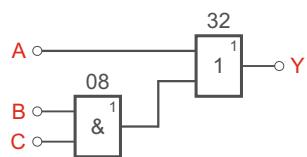
$$Y = A + B \\ = B + A$$



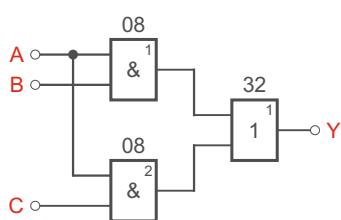
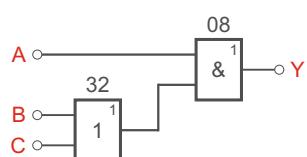
$$Y = A \cdot (B \cdot C) \\ = (A \cdot B) \cdot C$$



$$Y = A + (B + C) \\ = (A + B) + C$$

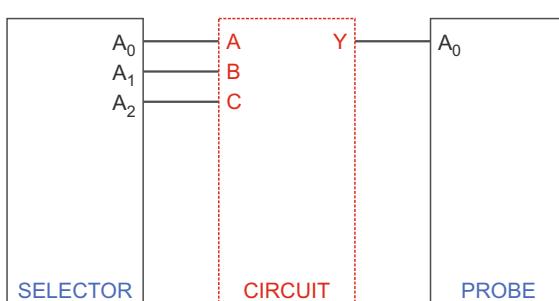


$$Y = A + (B \cdot C) \\ = (A + B) \cdot (A + C)$$



$$Y = A \cdot (B + C) \\ = (A \cdot B) + (A \cdot C)$$

Circuit



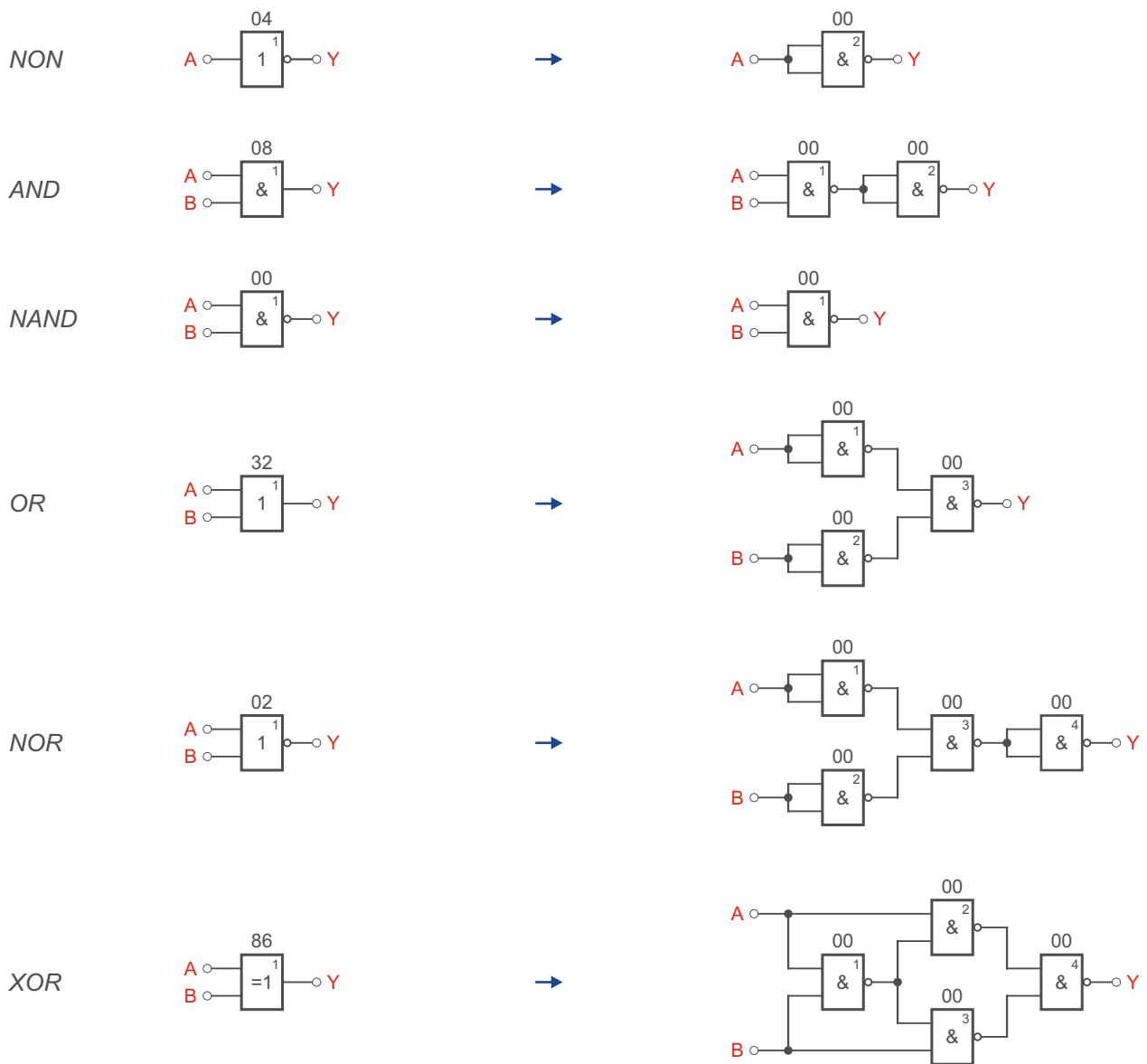
7.2

Boolean Algebra - Function Transformation (NAND)

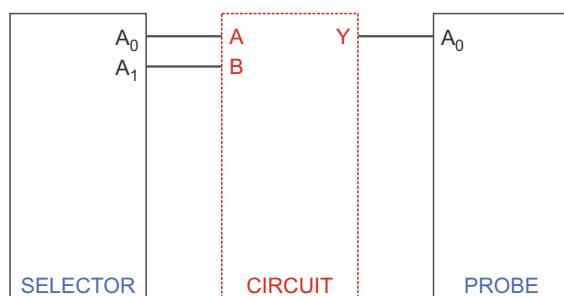
Exercise

Design and implement circuiting of basic logic functions NON, AND, NAND, OR, NOR and XOR using NAND function.

Schema



Circuit



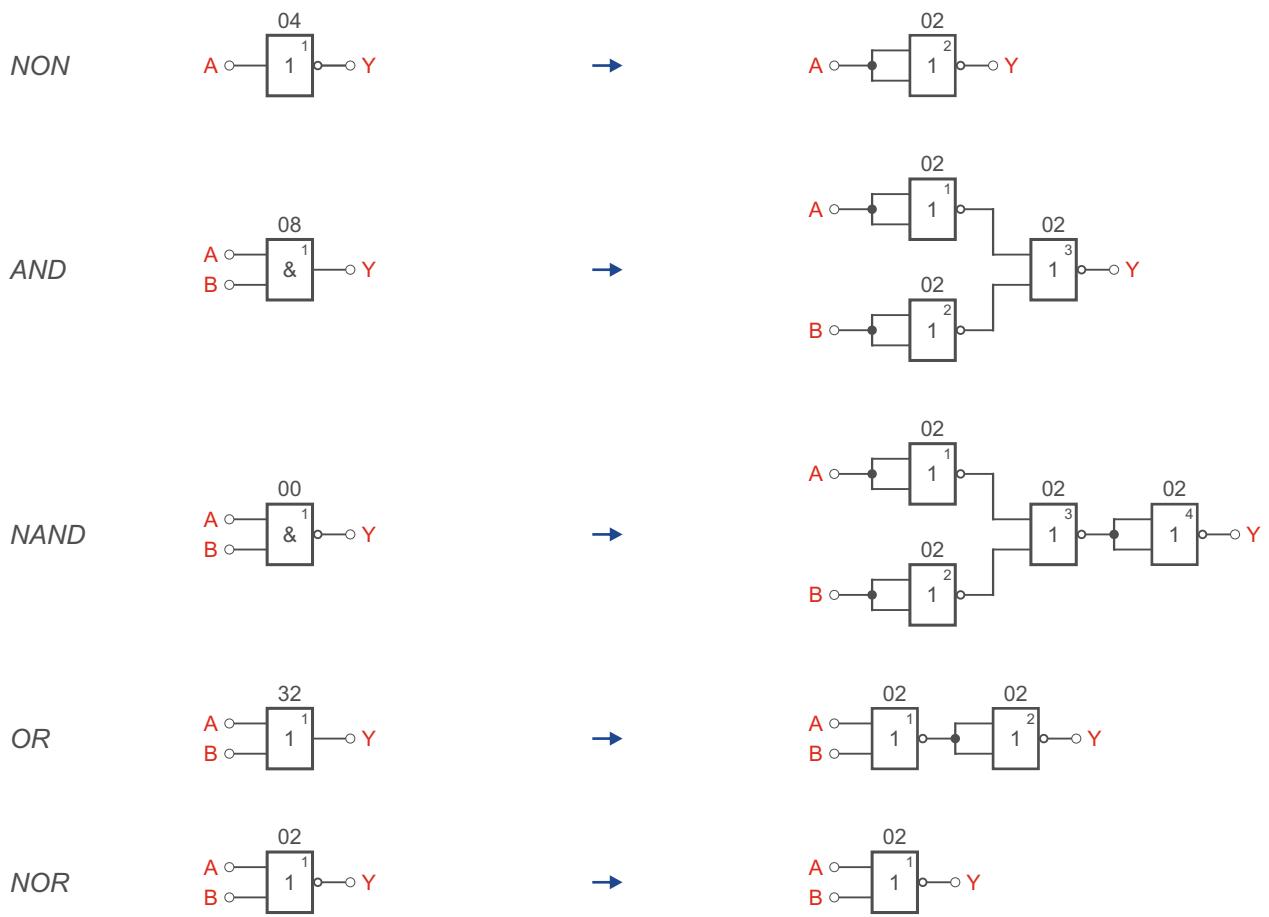
7.3

Boolean Algebra - Function Transformation (NOR)

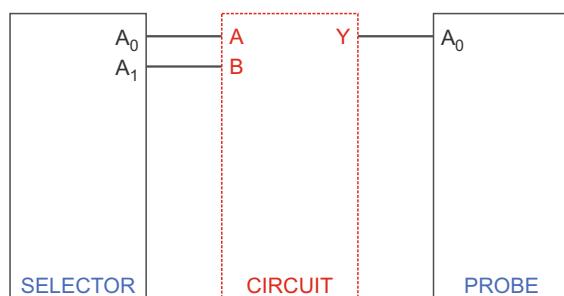
Exercise

Design and implement circuiting of basic logic functions NON, AND, NAND, OR and NOR using NOR function.

Schema



Circuit



7.4

Logic Function - Minimization

Exercise

Minimize the specified logical function and verify the results by measurement.

Schema

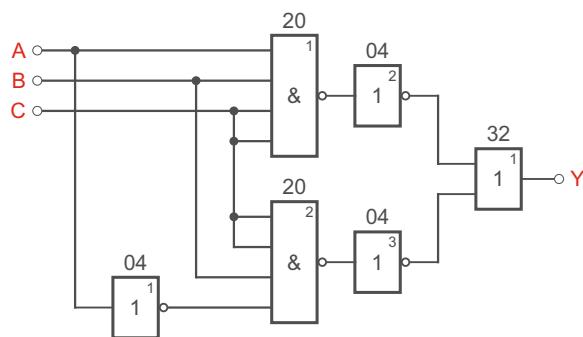


Fig. 1

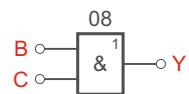


Fig. 2

Circuit

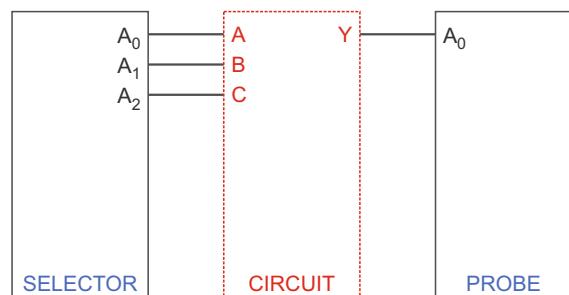


Fig. 1

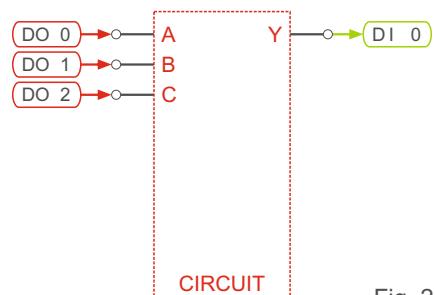
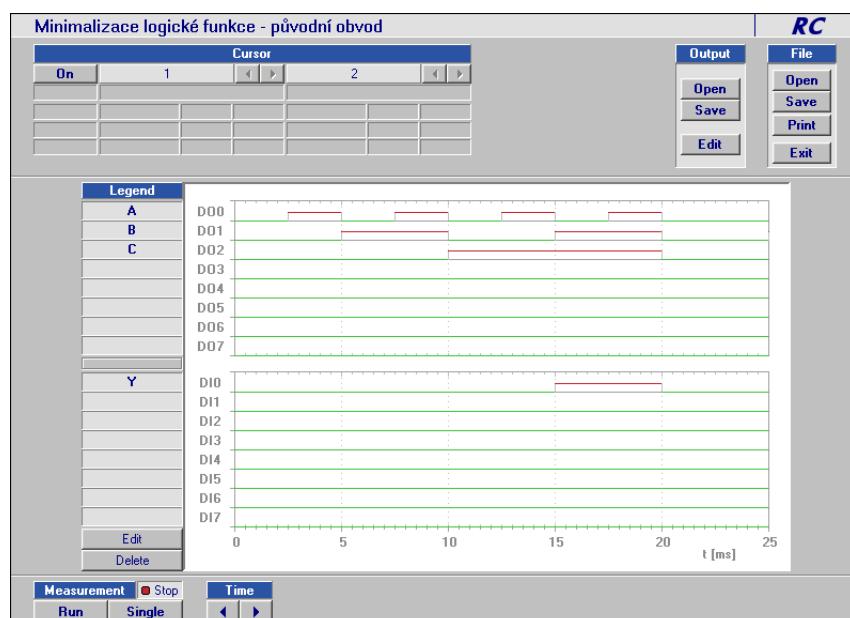


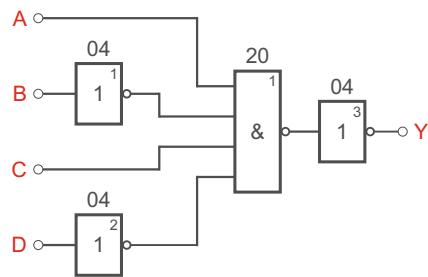
Fig. 2

Measurement

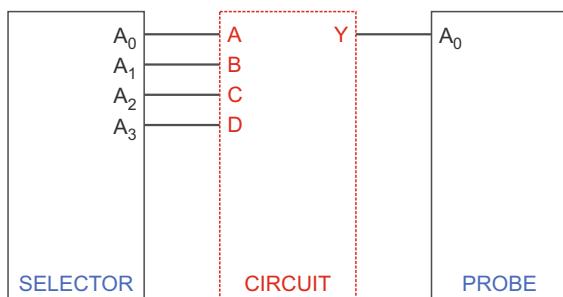


Exercise

Design and implement a logical function for elevator control. The motor starts when the floor choice button is pressed and simultaneously the stop button is not, the doors are closed and the elevator is not overloaded.

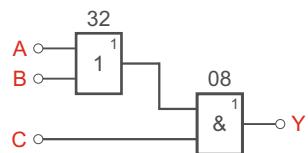
Schema

A	0	The floor selection key is not pressed
	1	The floor selection key is pressed
B	0	The emergency button STOP is not pressed
	1	The emergency button STOP is pressed
C	0	The doors are not closed
	1	The doors are closed
D	0	The lift is not overloaded
	1	The lift is overloaded
Y	0	The lift motor is not running
	1	The lift motor is running

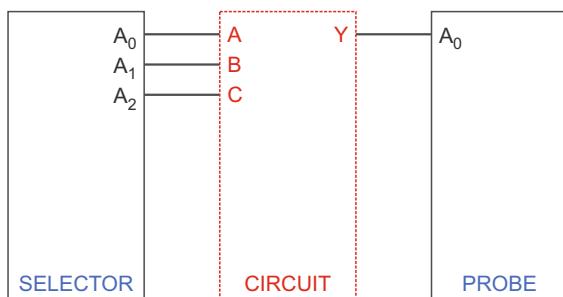
Circuit

Exercise

Design and implement the logical function of a safety device to monitor the window and the door of the building. When the device is switched on, a window, a door or both are triggered at the same time.

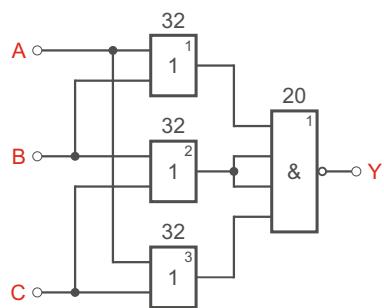
Schema

A	0	The window is closed
	1	The window is opened
B	0	The doors are closed
	1	The doors are opened
C	0	Device switched off
	1	Device switched on
Y	0	The siren does not howl
	1	The siren howles

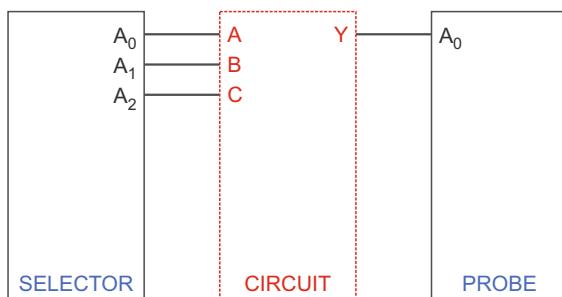
Circuit

Exercise

Design and implement the logic function of the signaling of the fan operation in the tunnel. The indicator light starts to light when less than two (ie one or none) of the three installed fans are working.

Schema

A	0	Fan 1 is not running
	1	Fan 1 is running
B	0	Fan 2 is not running
	1	Fan 2 is running
C	0	Fan 3 is not running
	1	Fan 3 is running
Y	0	The signaling is switched off
	1	The signaling is switched on

Circuit

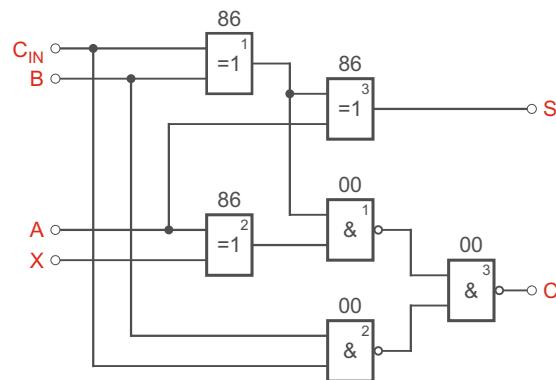
7.8

Adders and Subtractors

Exercise

Make a circuit connection for addition and subtraction of two one-bit numbers with a transmission from low-order and into higher-order.

Schema



Circuit

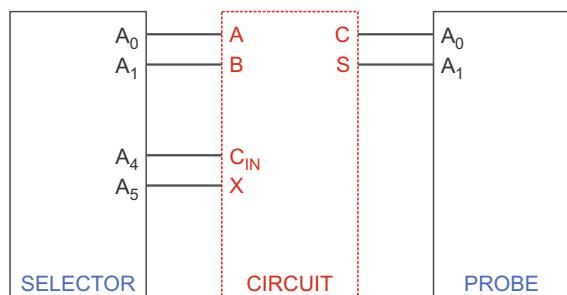


Fig. 1

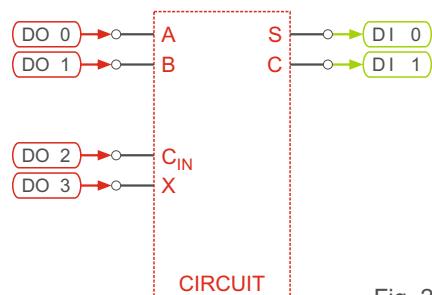
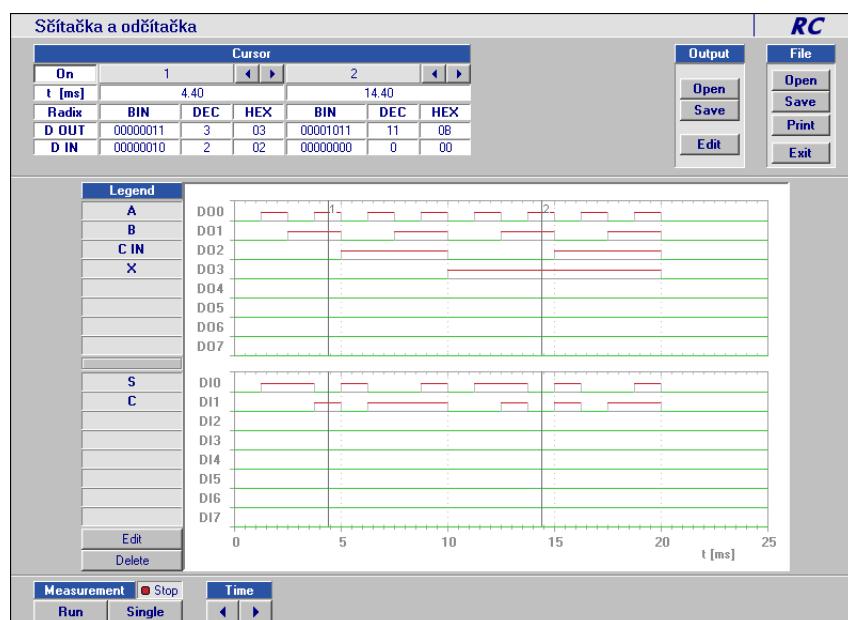


Fig. 2

Measurement



7.9

Half Adders and Full Adders

Exercise

Make a circuit connection to add two one-bit numbers without transmission (half-adders) and with transmission (full adders).

Schema

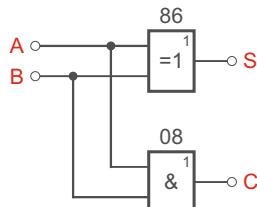


Fig. 1

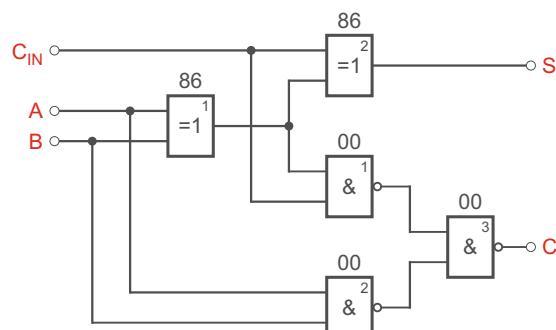


Fig. 2

Circuit

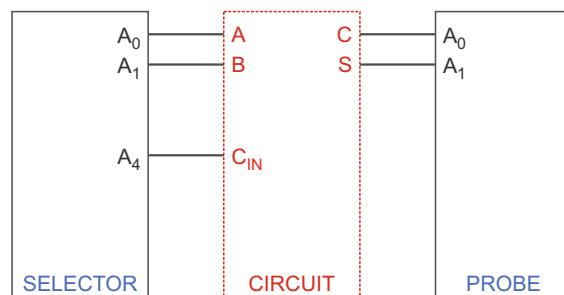


Fig. 1

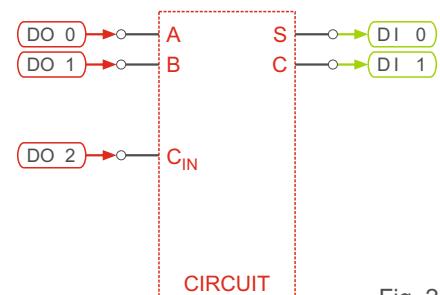
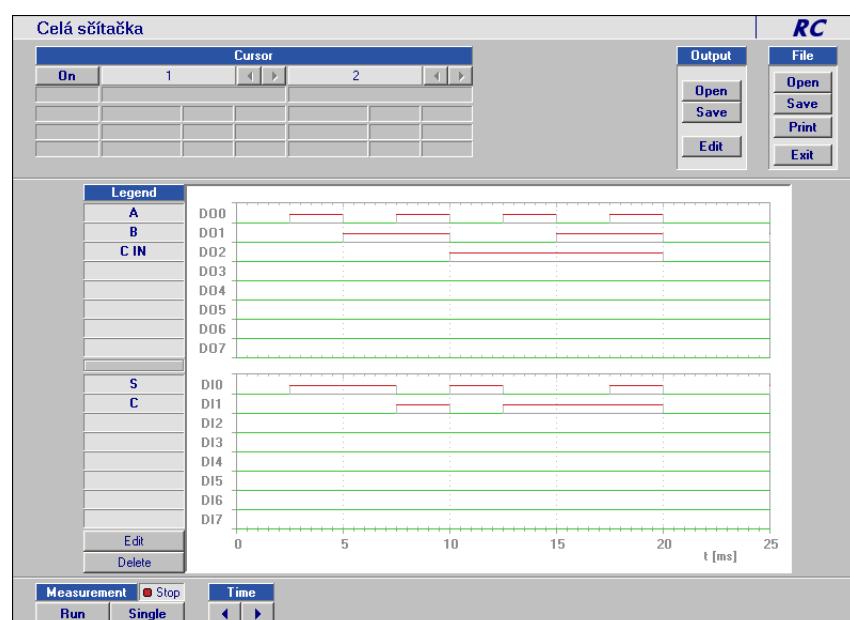


Fig. 2

Measurement



7.10

1-bit Comparator

Exercise

Design and check the circuit that compares two one-bit numbers.

Schema

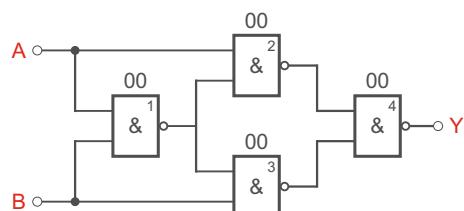


Fig. 1

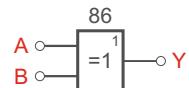


Fig. 2

Circuit

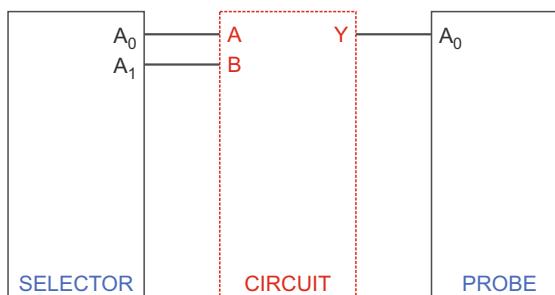


Fig. 1

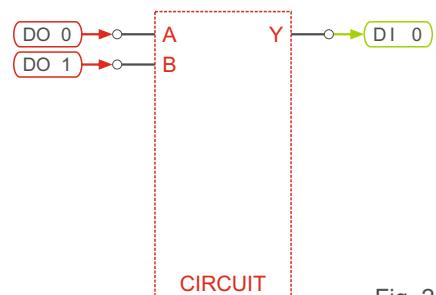
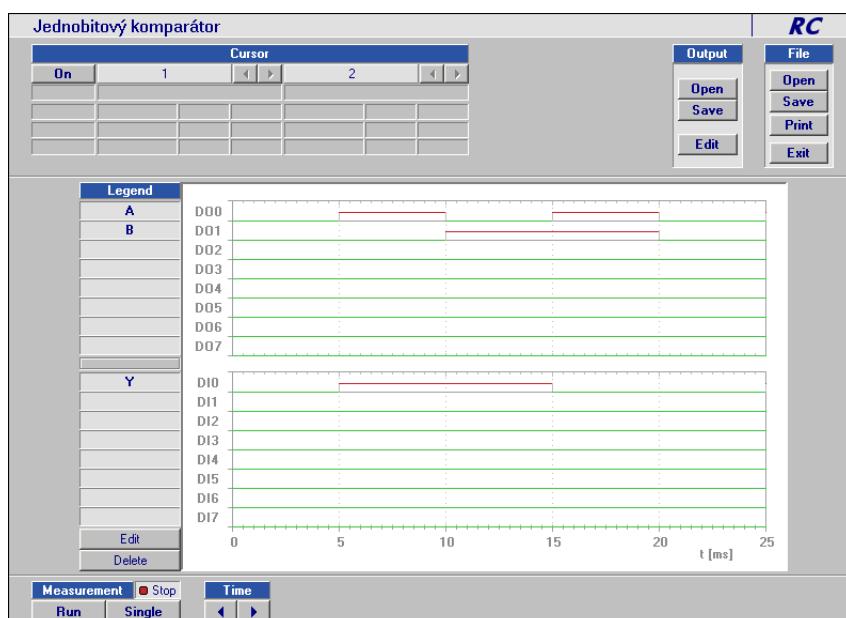


Fig. 2

Measurement



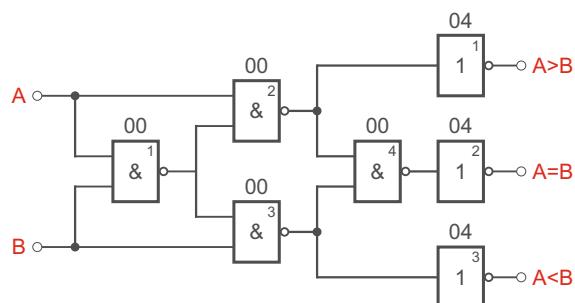
7.11

Comparison Circuit

Exercise

Make a circuit connection to compare two one-bit numbers. The circuit has outputs $A > B$, $A = B$, $A < B$.

Schema



Circuit

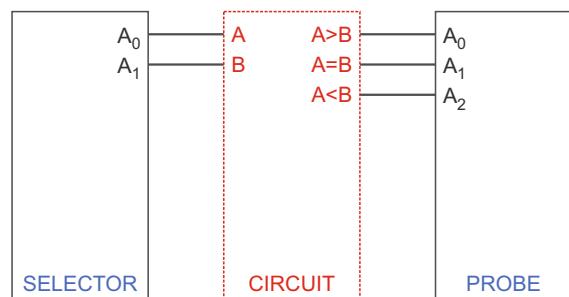


Fig. 1

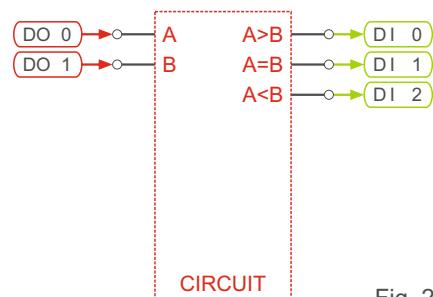
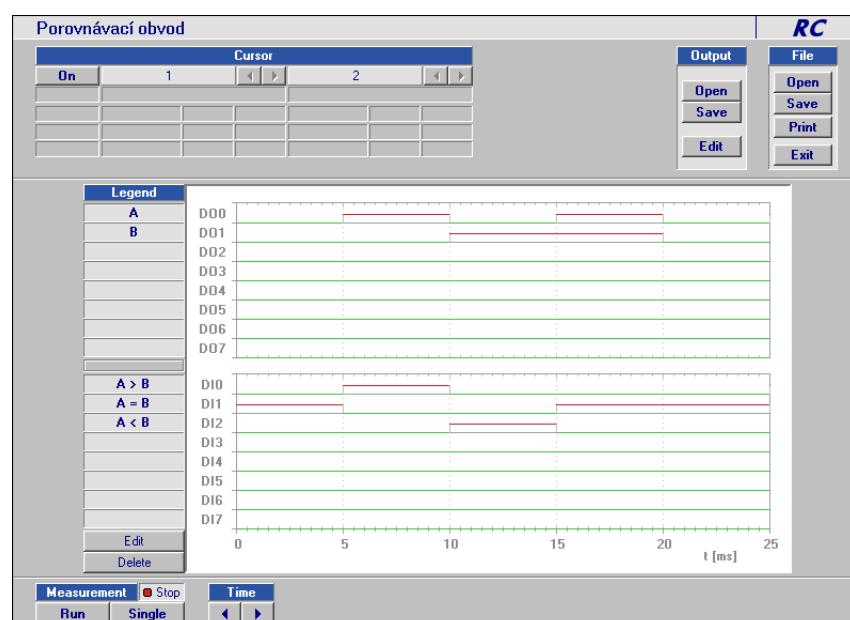


Fig. 2

Measurement



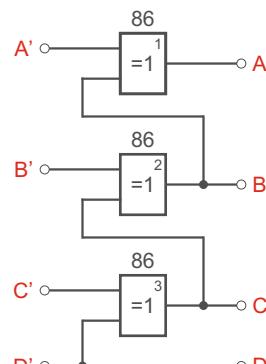
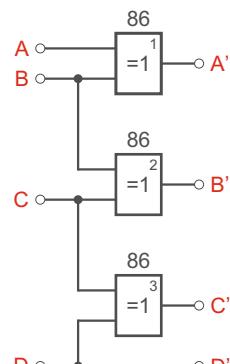
7.12

Binary <-> Gray Code Converter

Exercise

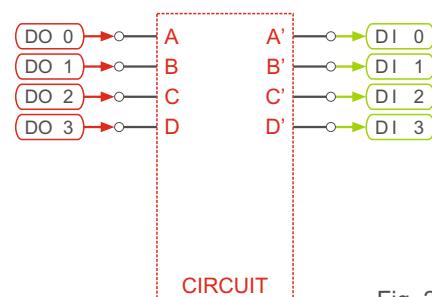
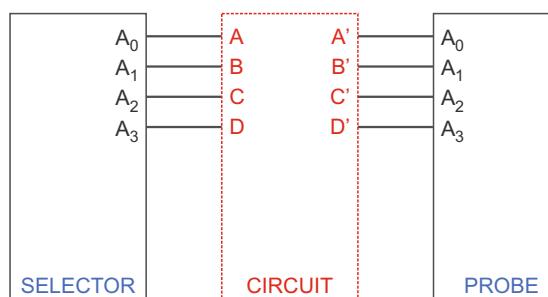
Create the circuit of the converter, which converts the numbers from the binary code to the Gray code.

Schema

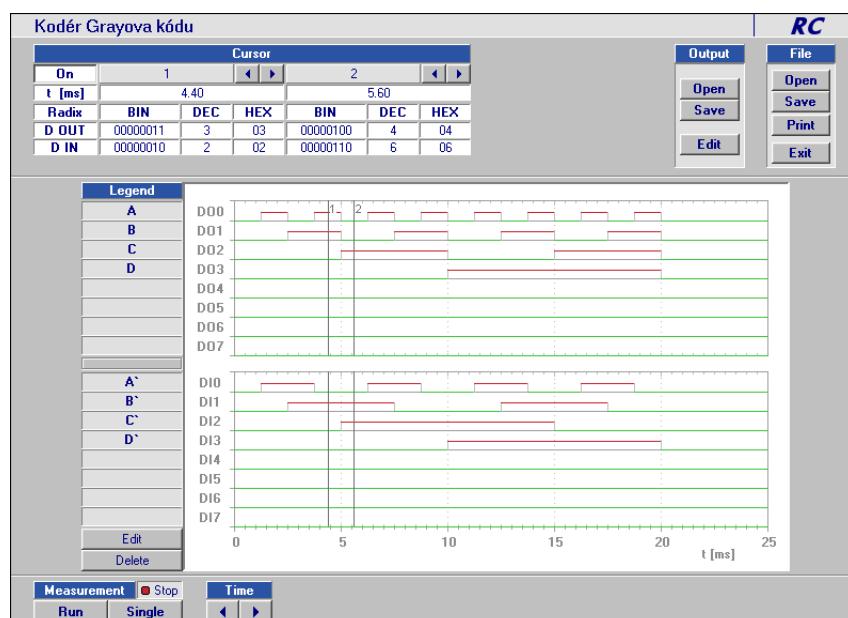


Decimal system	Binary code	Gray code
0	DCBA	D'C'B'A'
1	0000	0000
2	0001	0001
3	0011	0010
4	0100	0110
5	0101	0111
6	0110	0101
7	0111	0100
8	1000	1100
9	1001	1101
10	1010	1111
11	1011	1110
12	1100	1010
13	1101	1011
14	1110	1001
15	1111	1000

Circuit



Measurement



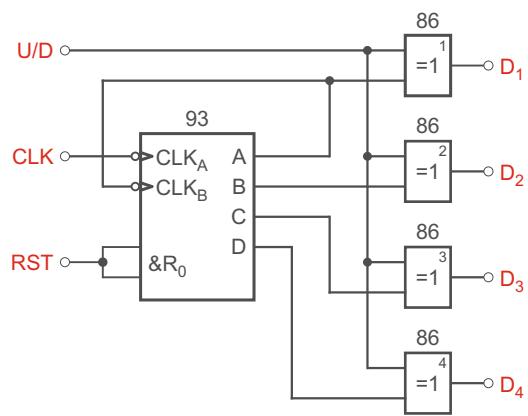
7.13

Counter (up / down)

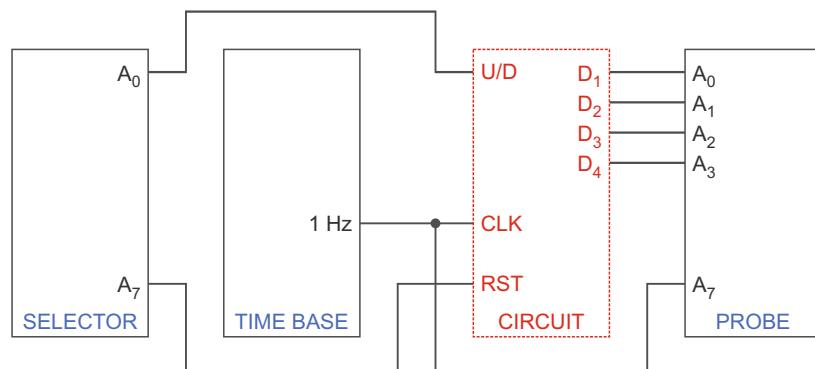
Exercise

Design and implement the counter with the 7493 circuit, which can read up and down. Check the function.

Schema



Circuit



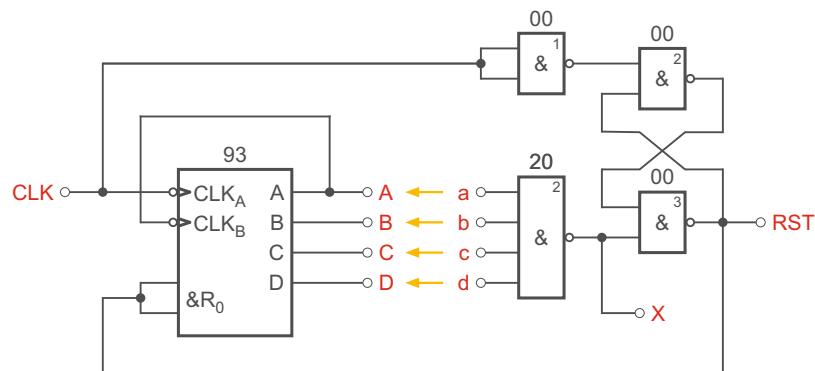
7.14

Modulo - N - Counter

Exercise

Design and implement the Modulo - N - Counter 2 - 15 with the 7493 circuit. Check the function.

Schema



Circuit

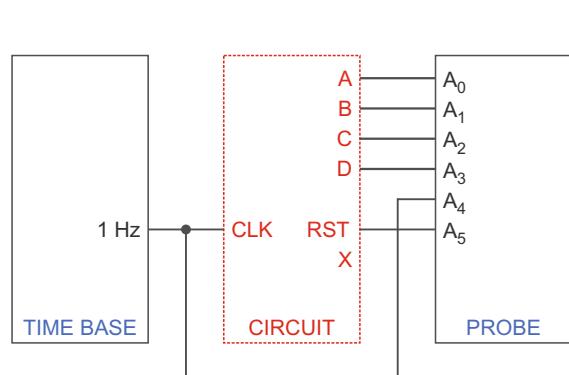


Fig. 1

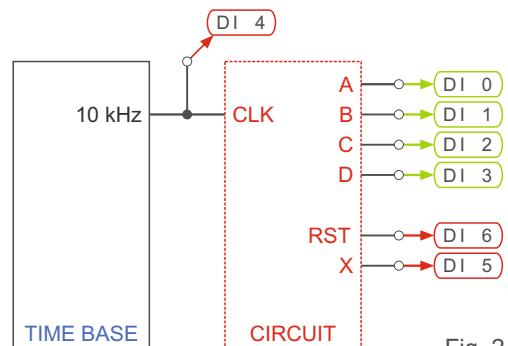
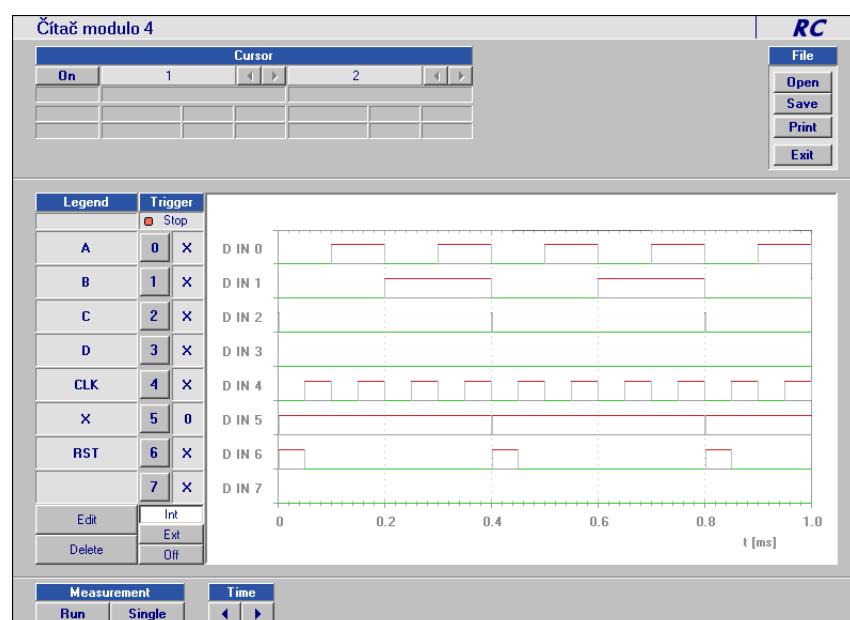


Fig. 2

Measurement



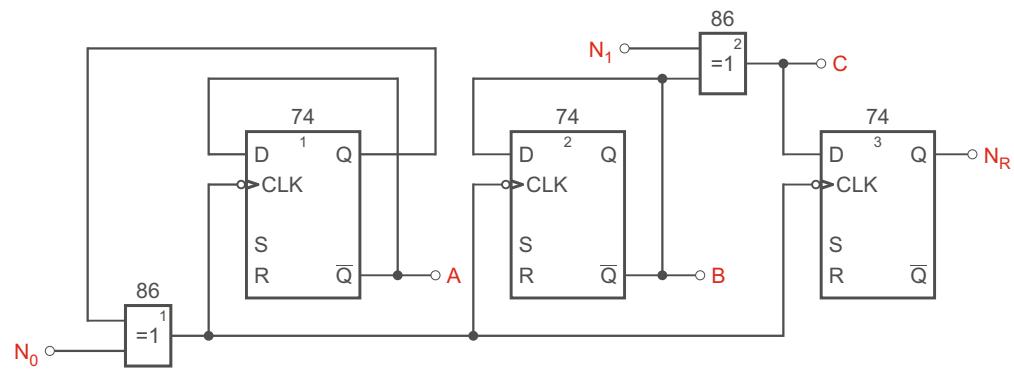
7.15

Sequence Circuit - Digital Differential Circuit

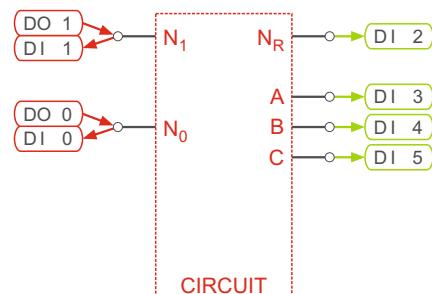
Exercise

Design and measure the circuit that generates the difference in the number of pulses of the two waveforms. Measure the circuit for synchronized waveforms when $N_0 > N_1$ resp. $N_1 > N_0$, and for unsynchronized waveforms.

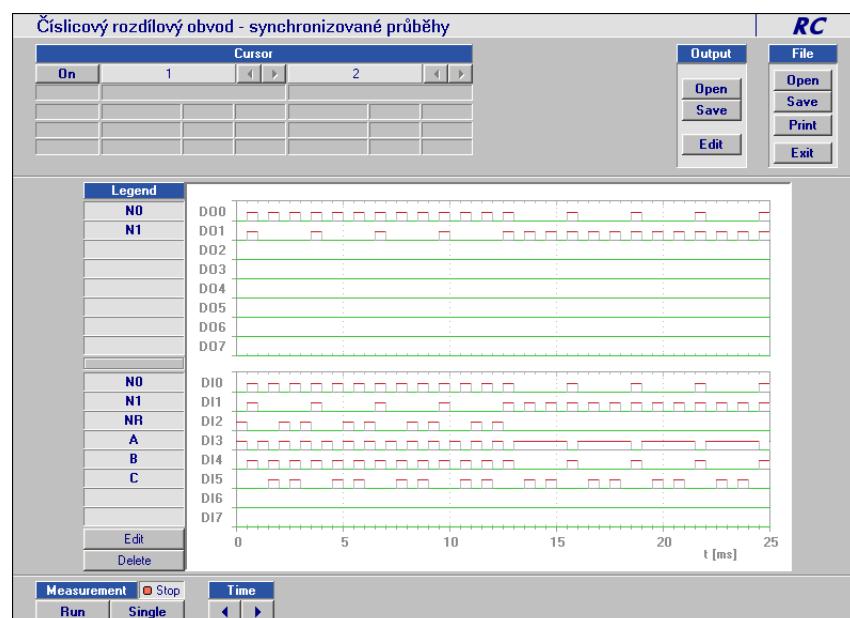
Schema



Circuit

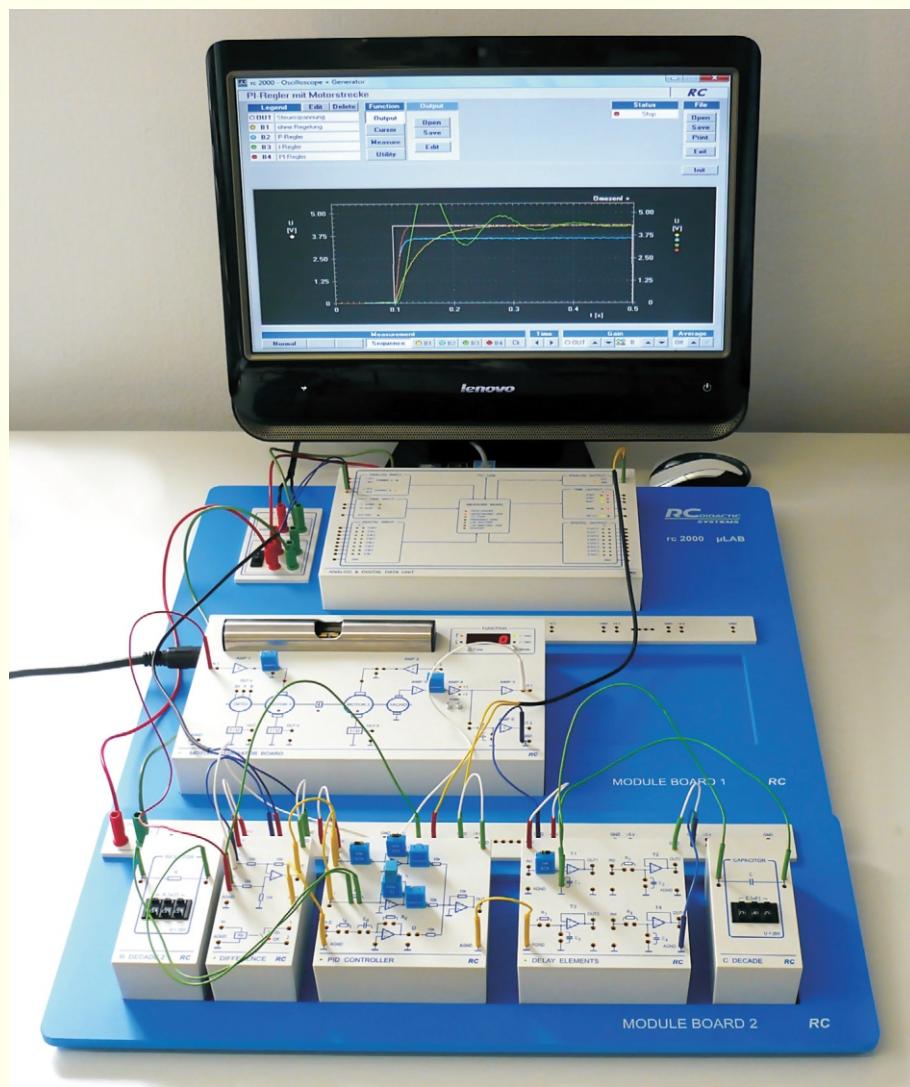


Measurement



Teaching System rc2000 - μ LAB

Regulation



Content

Regulation	8.0
PI Controller - Timing Analysis	8.1
PID Controller - Timing Analysis	8.2
Delay Element of the Second Order - Timing Analysis	8.3
Identification of the Delay Element with Motor System	8.4
P-Controller - Measurement with Motor	8.5
I-Controller - Measurement with Motor	8.6
PI-Controller - Measurement with Motor	8.7
PI-Controller - Measurement with Delay Element	8.8
Loaded Motor - Without and with PI Controller	8.9

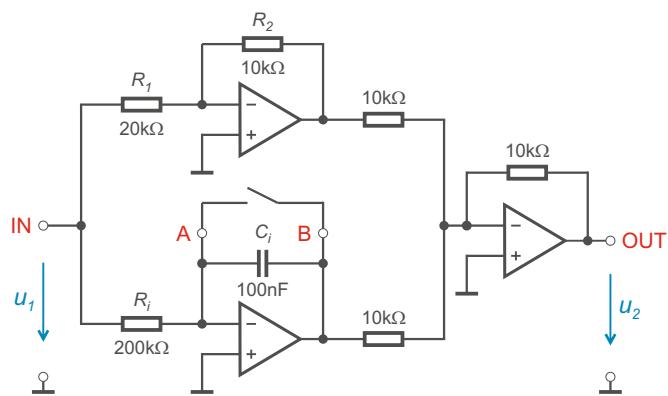
8.1

PI control element - time analysis

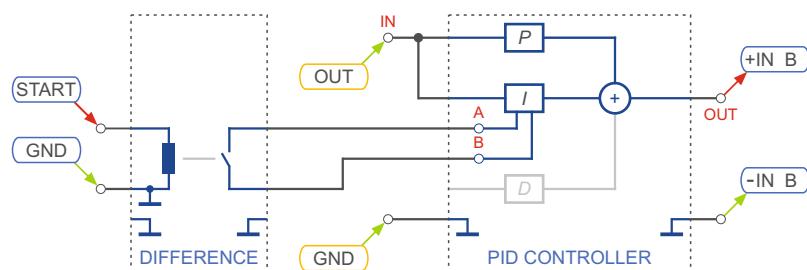
Exercise

Measure the transition characteristic of the PI controller.

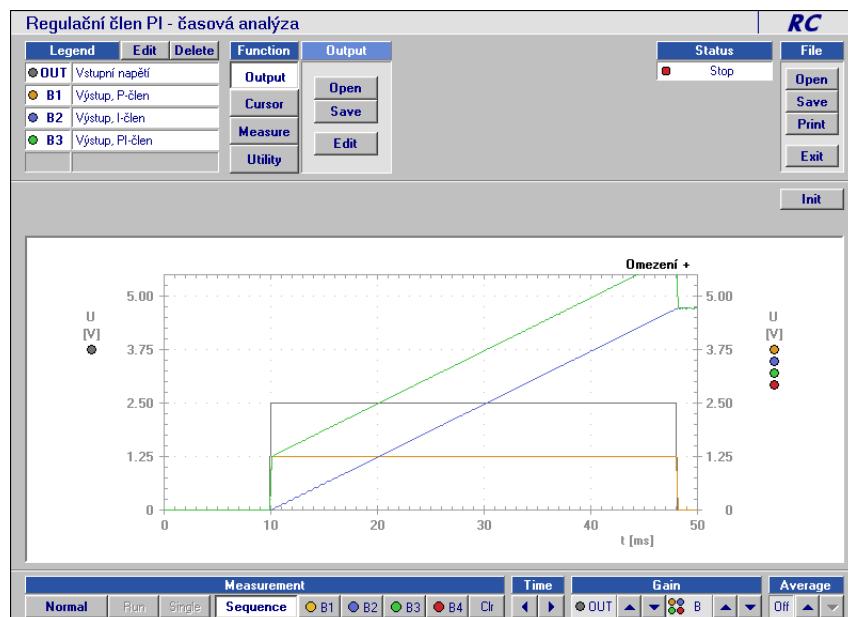
Schema



Circuit



Measurement



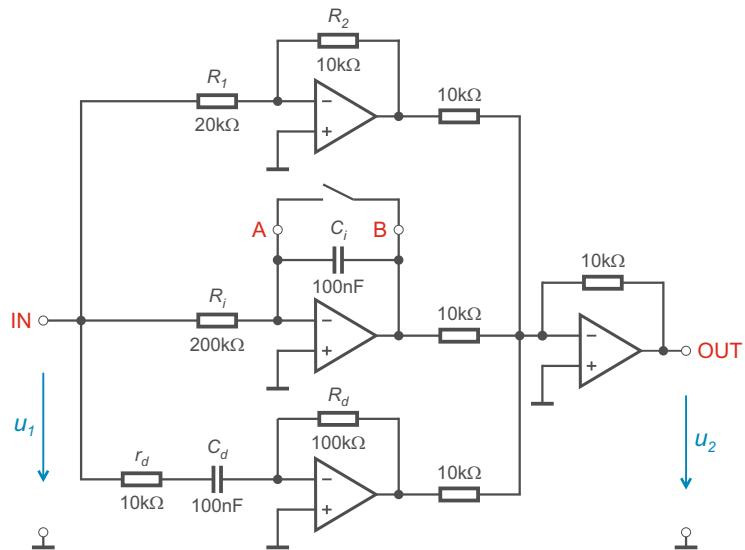
8.2

PID control element - time analysis

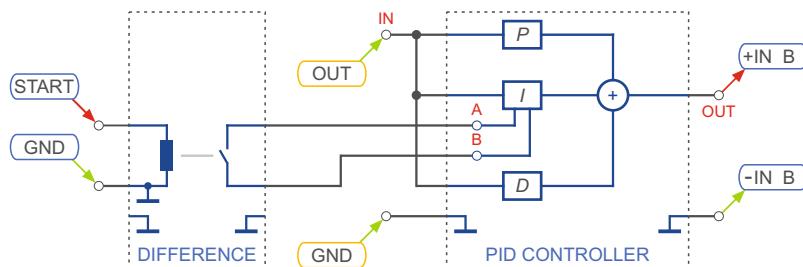
Exercise

Measure the transition characteristic of the PID controller.

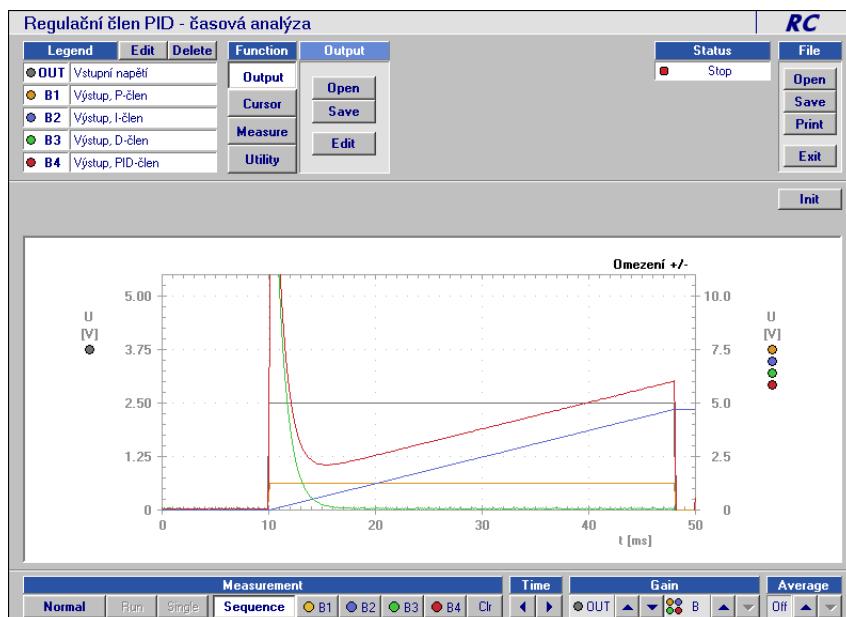
Schema



Circuit



Measurement



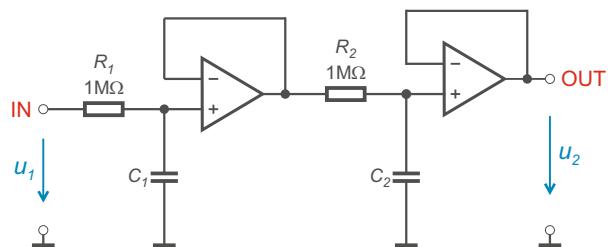
8.3

Delay element of the second order - time analysis

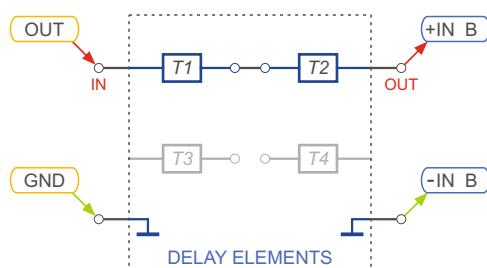
Exercise

Measure the transition characteristics of the second-order delay element.

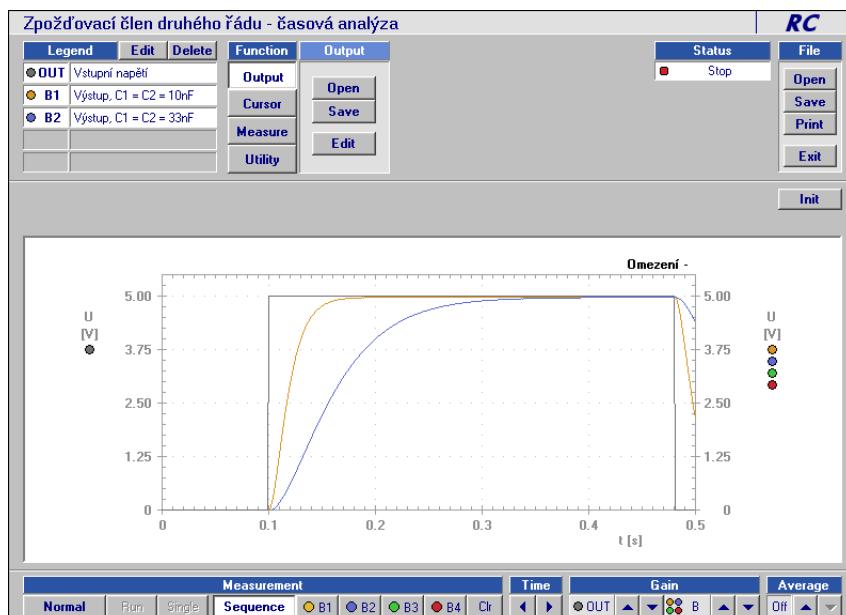
Schema



Circuit



Measurement



8.4 Identification of the delay element with a system of motor

Exercise

Find such a circuit of the delay element that has the best match in transition characteristics with the motor system and with tachodynamo from the motor - generator module. The value C_1 shall be about 40 nF.

Schema

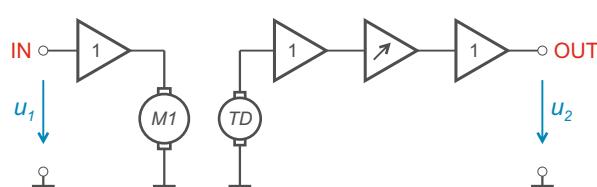


Fig. 1

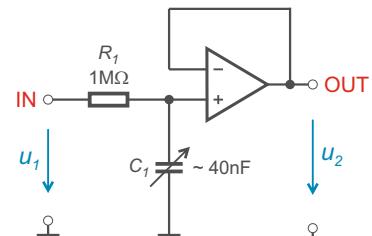


Fig. 2

Circuit

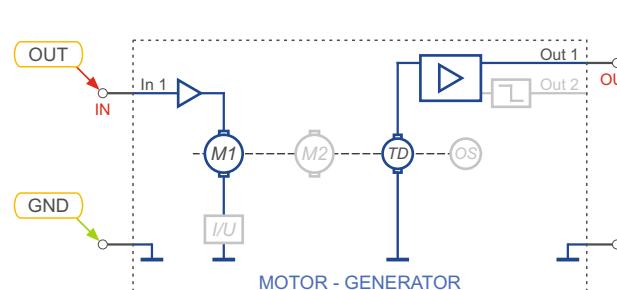


Fig. 1

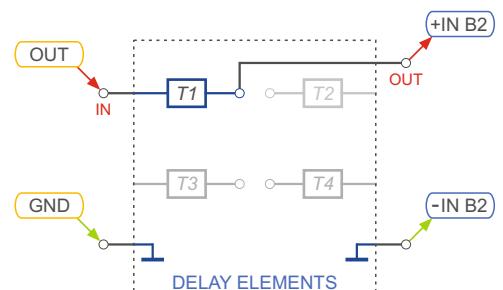
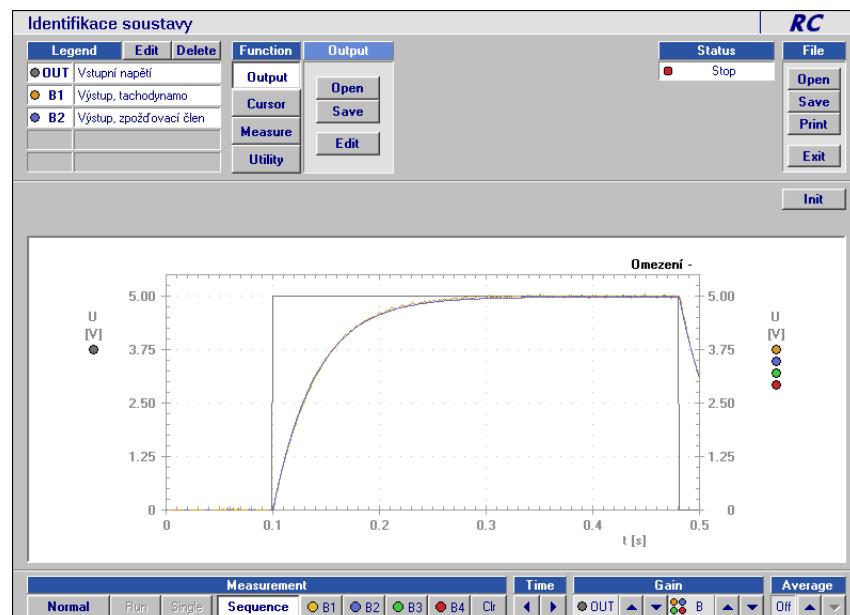


Fig. 2

Measurement



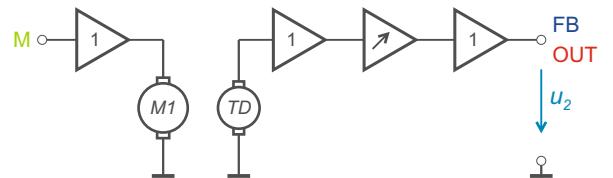
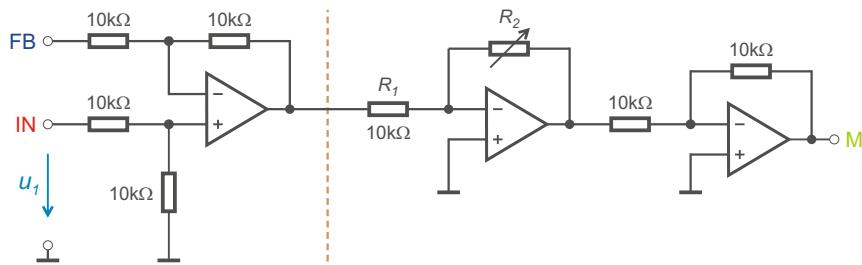
8.5

P-Controller - Measurement with motor

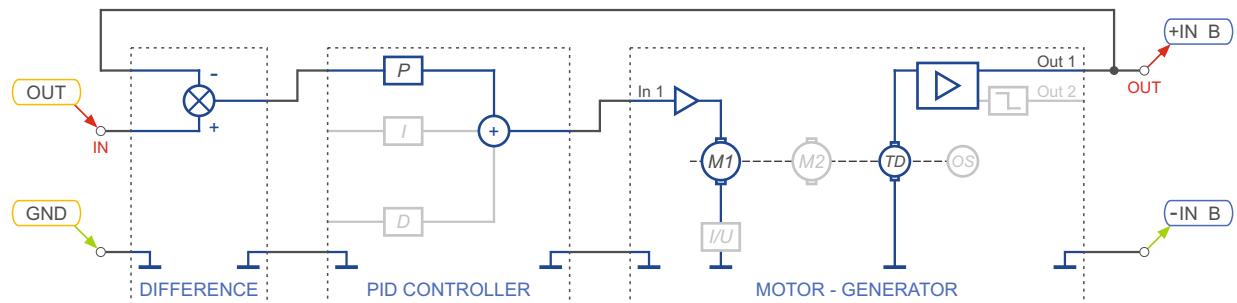
Exercise

Check the P-controller function. Measure the transition characteristic of the system with P-controller for the resistance values $R_2 = 20 \text{ k}\Omega$; $50 \text{ k}\Omega$; $140 \text{ k}\Omega$. Compare the waveforms with the characteristics of the system without regulation.

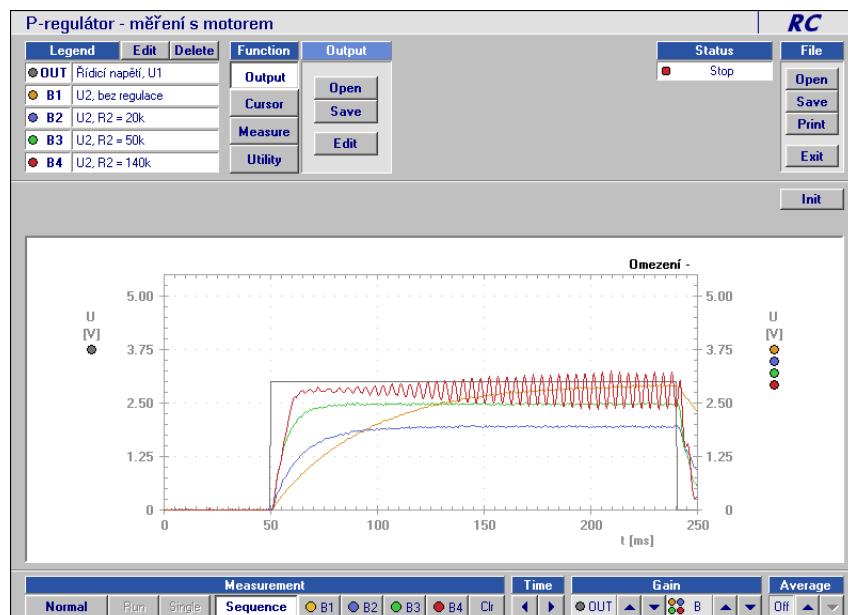
Schema



Circuit



Measurement



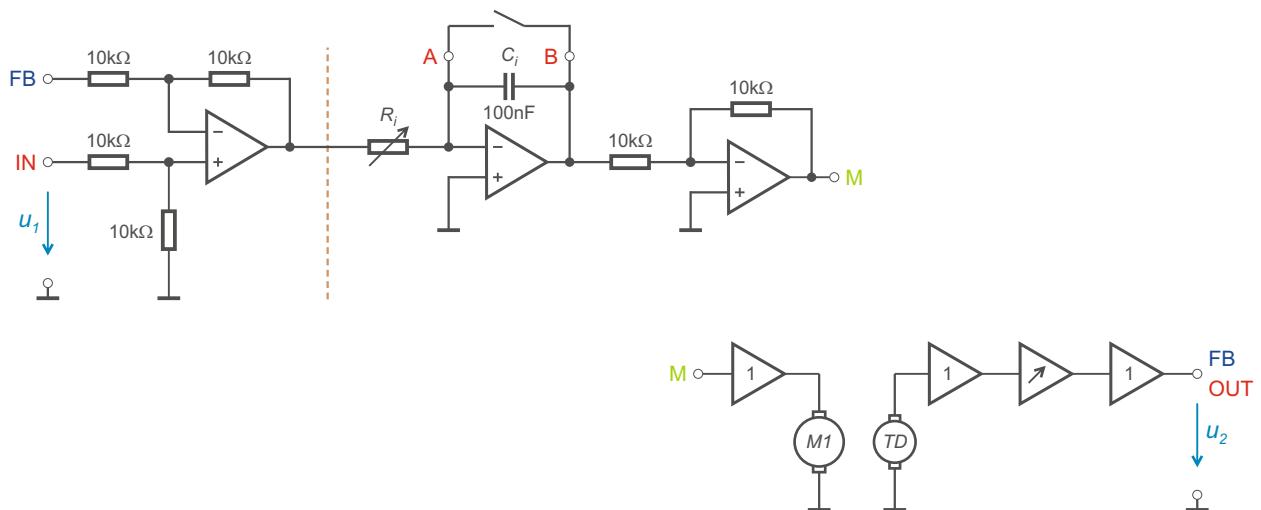
8.6

I-Controller - Measurement with motor

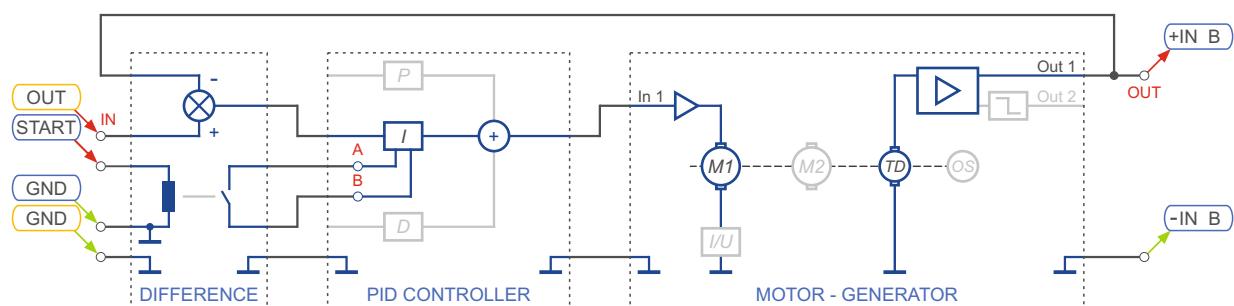
Exercise

Check the function of the I-controller. Measure the transition characteristic of the system with I controller for the resistance values $R_i = 20 \text{ k}\Omega$; $90 \text{ k}\Omega$; $190 \text{ k}\Omega$. Compare the waveforms with the characteristics of the system without control.

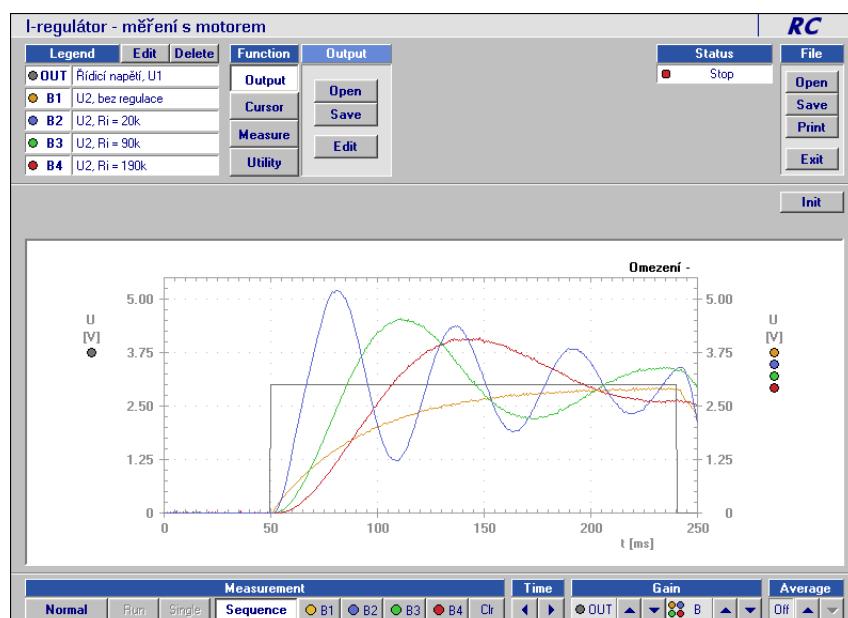
Schema



Circuit



Measurement



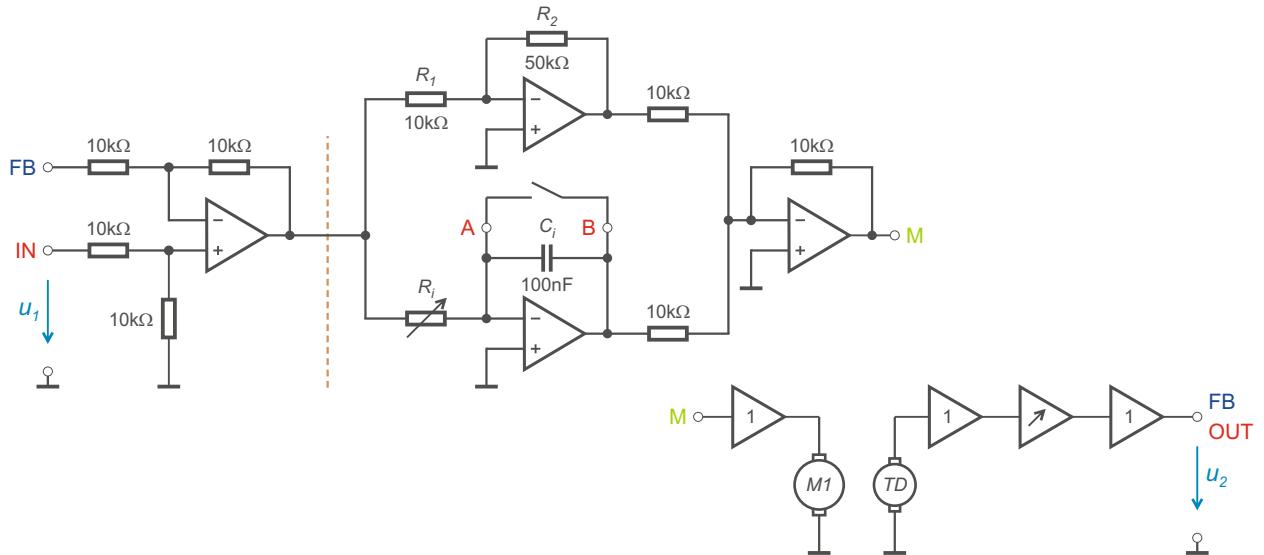
8.7

PI-Controller - Measurement with motor

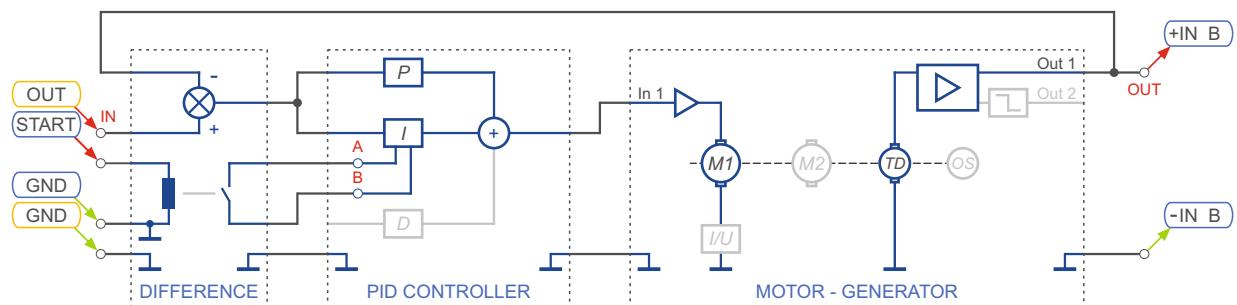
Exercise

Check the function of the PI controller. Measure the transition characteristic of the system in the case of the aperiodic control ($R_i = 20 \text{ k}\Omega$) and in the case of a control with overshoot ($R_i = 90 \text{ k}\Omega$). Compare the waveforms with the characteristics of the system without control.

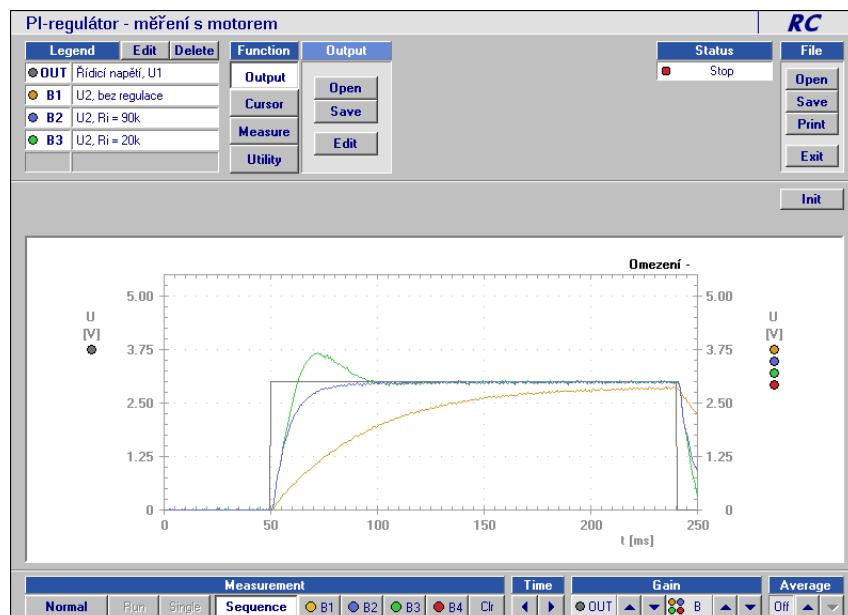
Schema



Circuit



Measurement



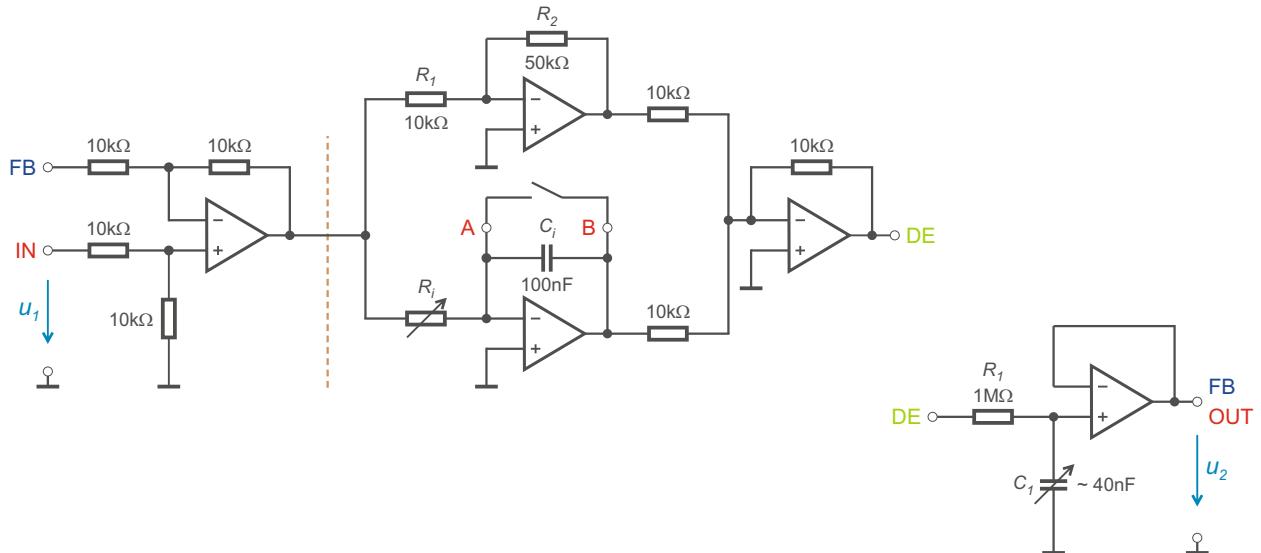
8.8

PI controller - Measurement with delay element

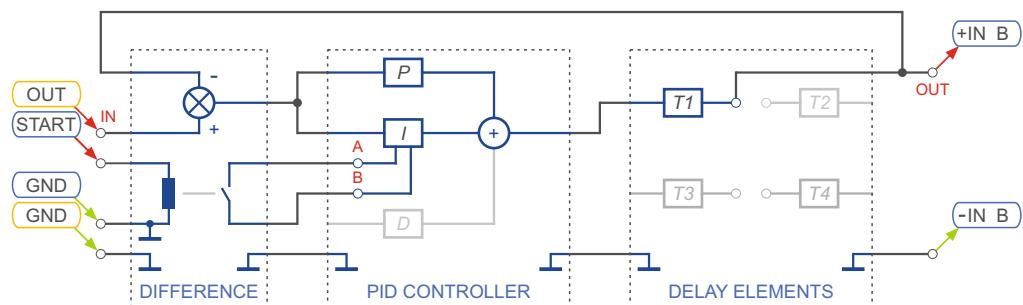
Exercise

Check the function of the PI controller. Measure the transition characteristics of the system during an aperiodic regulation ($R_i = 20 \text{ k}\Omega$) and during a regulation with overshoot ($R_i = 90 \text{ k}\Omega$). Compare the curves with characteristics of the system without regulation.

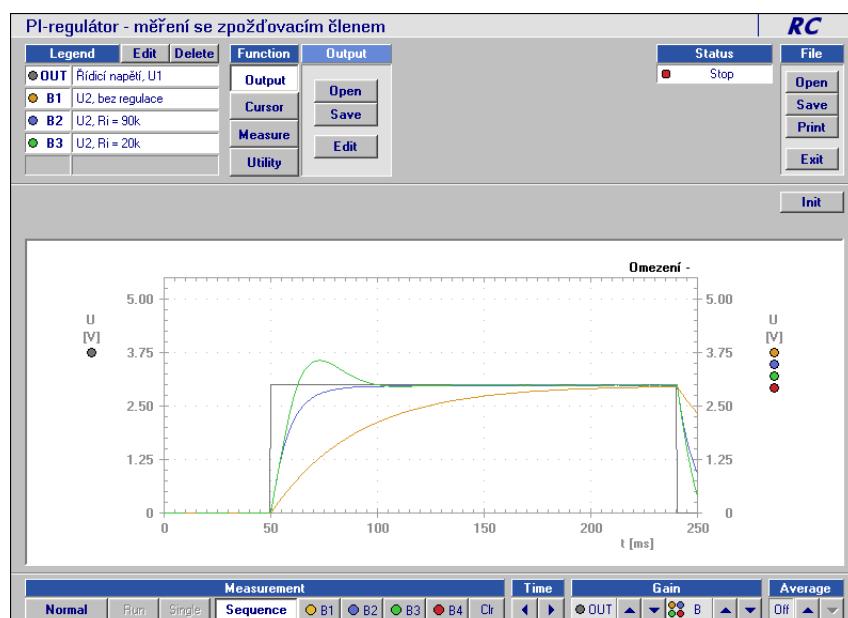
Schema



Circuit



Measurement



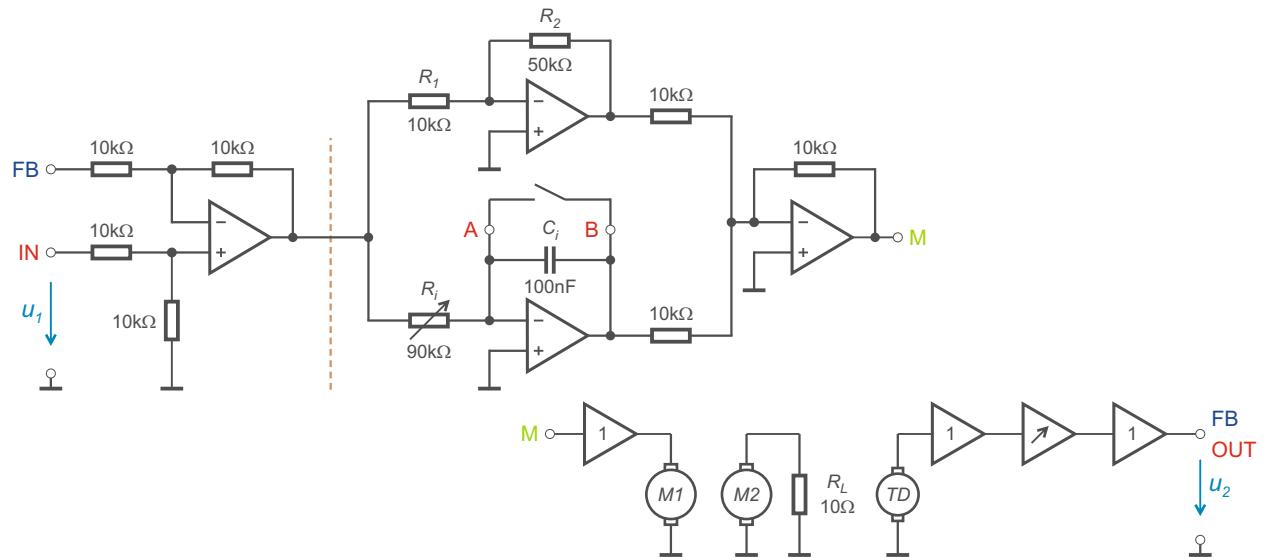
8.9

Loaded Motor - without and with PI-Controller

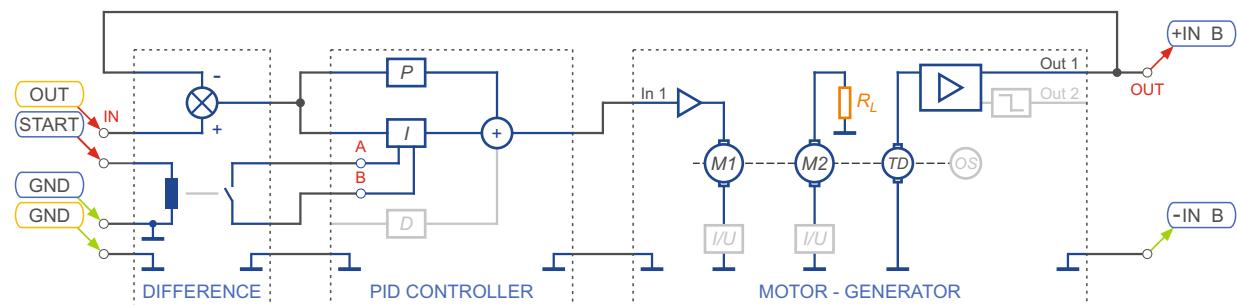
Exercise

Compare the transition characteristics of the unloaded and loaded system without regulation. Then compare the transition characteristic of the unloaded and loaded system with PI regulation.

Schema



Circuit



Measurement

